

# When extremists win Iterated learning with heterogenous agents

#### **Dani Navarro**

School of Psychology
University of New South Wales

#### **Arthur Kary**

School of Psychology
University of New South Wales

#### **Amy Perfors**

School of Psychological Science University of Melbourne

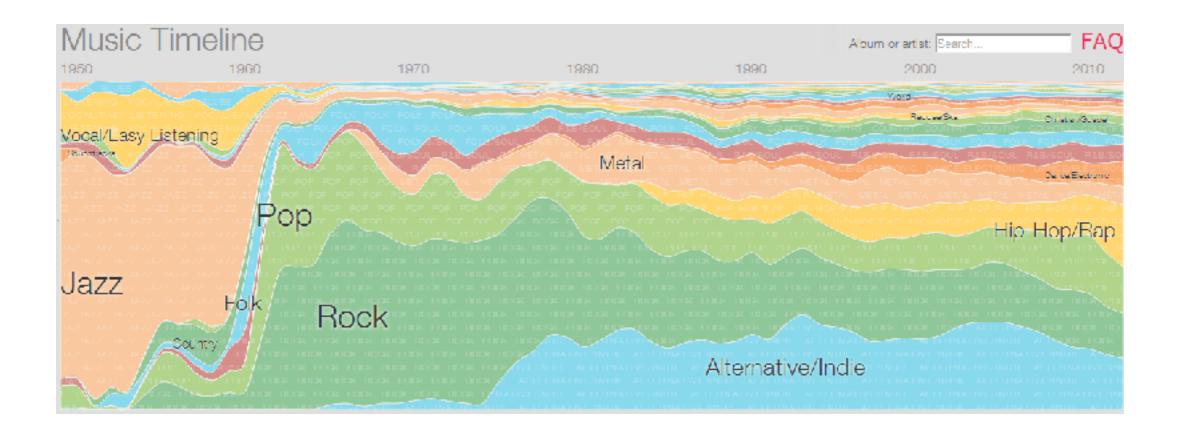
#### **Scott Brown**

School of Psychology University of Newcastle

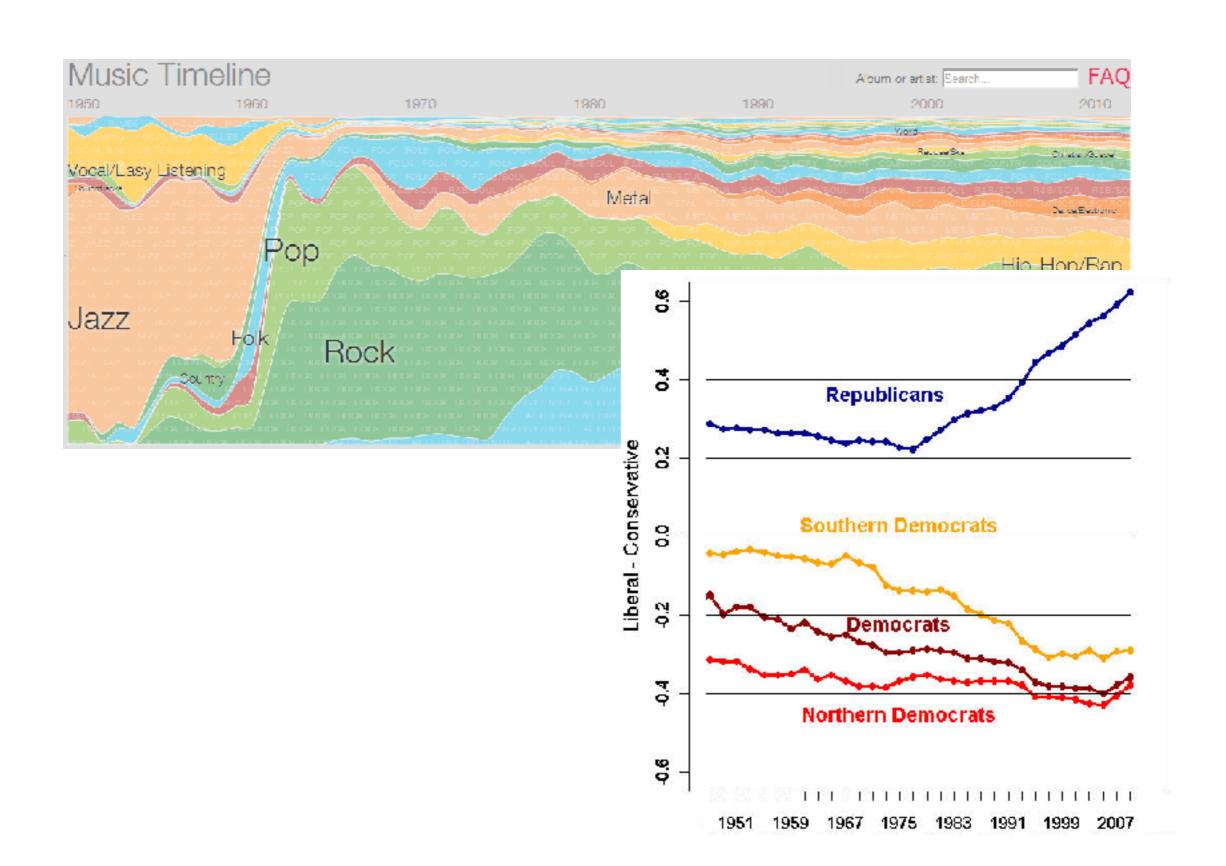
#### **Chris Donkin**

School of Psychology University of New South Wales

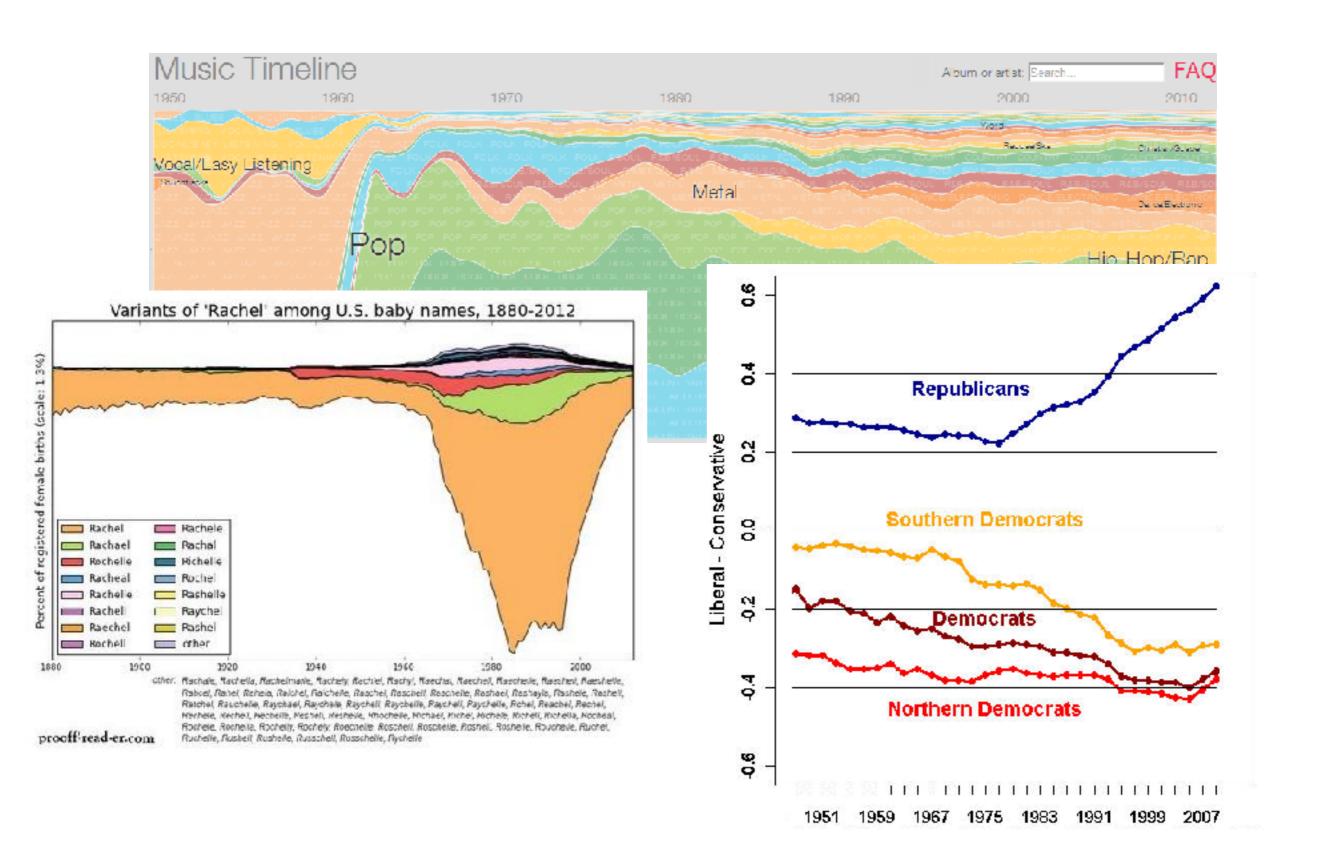
## Cultural evolution

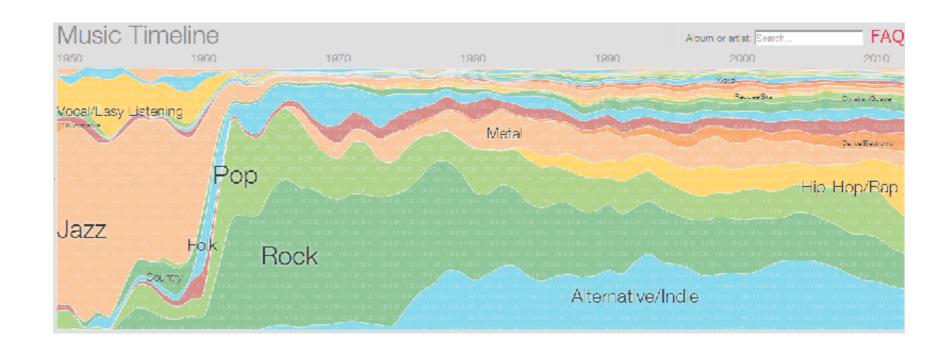


## Cultural evolution



### Cultural evolution



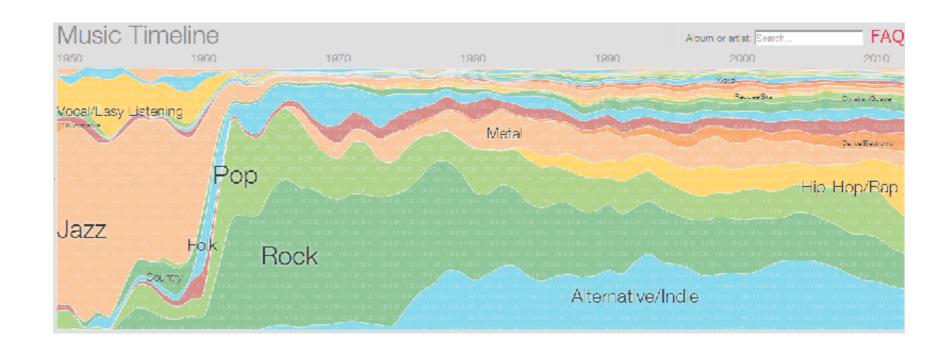


### Random drift?

Influence from from the environment?

Biases inherent to the cognitive system?

The dynamics of the communication system?

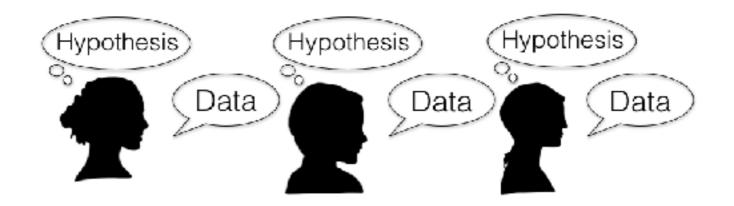


Random drift?

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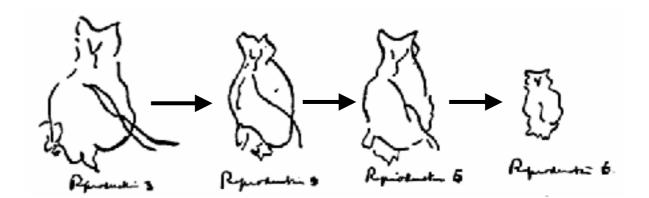
Biases inherent to the cognitive system?

The dynamics of the communication system?



The method of serial reproduction in memory

Bartlett (1920)

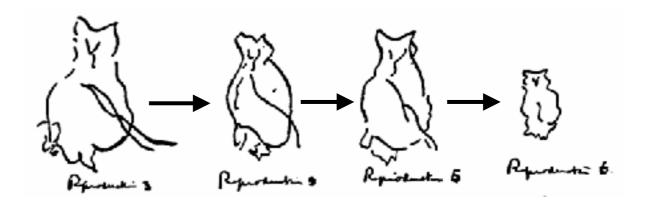


The method of serial reproduction in memory

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Language as sequential reproduction of culture

Smith et al (2002)



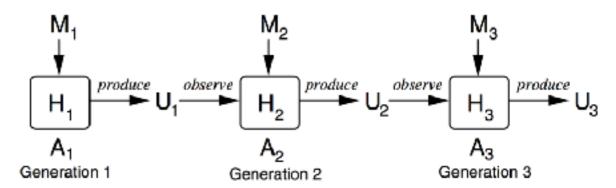


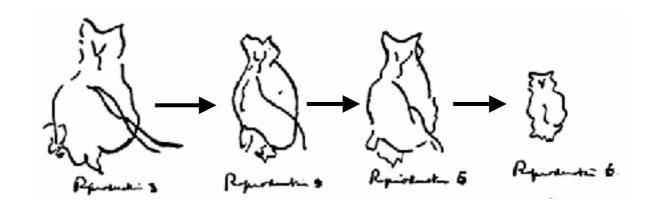
Figure 2. The iterated learning model. The ith generation of the population consists of a single agent  $A_i$  who has hypothesis  $H_i$ . Agent  $A_i$  is prompted with a set of meanings  $M_i$ . For each of these meanings the agent produces an utterance using  $H_i$ . This yields a set of utterances  $U_i$ . Agent  $A_{i+1}$  observes  $U_i$  and forms a hypothesis  $H_{i+1}$  to explain the set of observed utterances. This process of observation and hypothesis formation constitutes learning.

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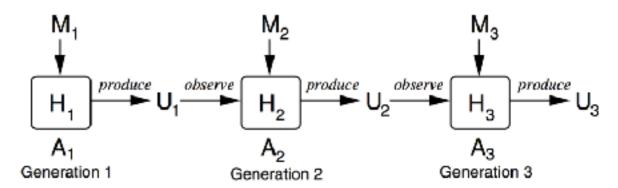
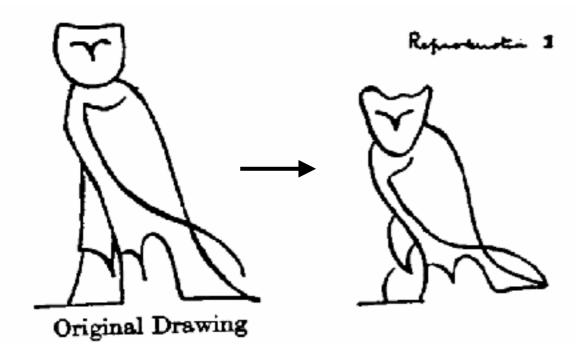


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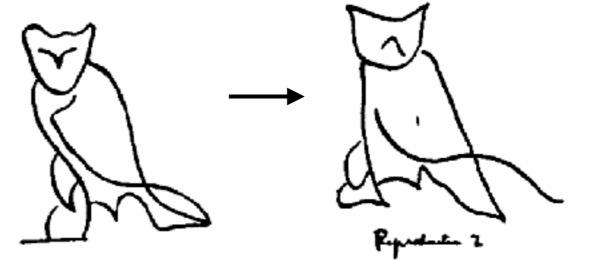
The method of iterated learning reveals inductive bias

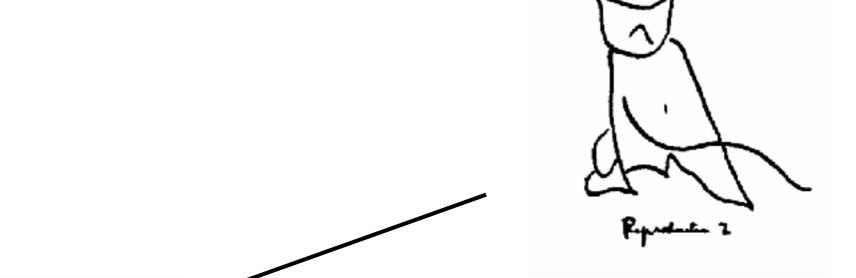
Kalish et al (2007)



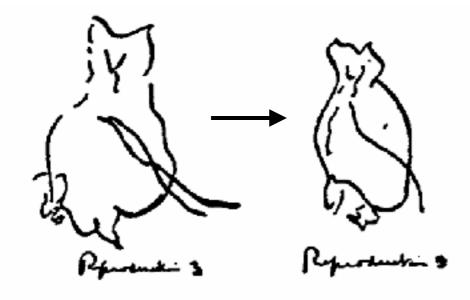


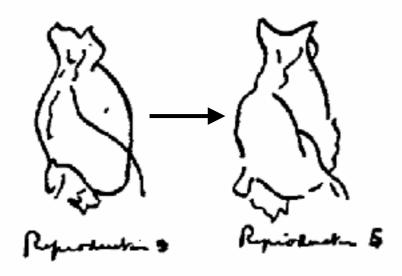
### Referencia 1

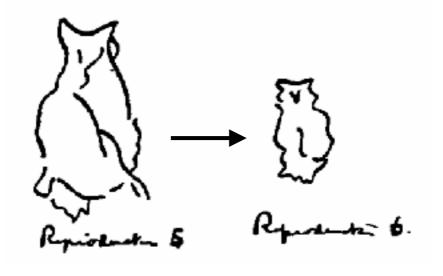


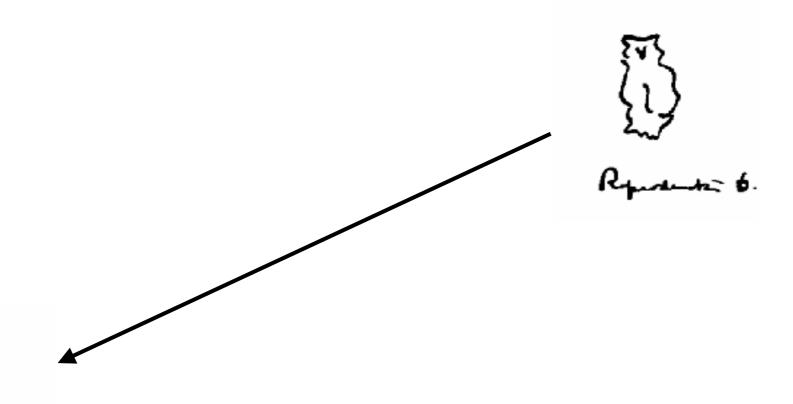


Phone 3

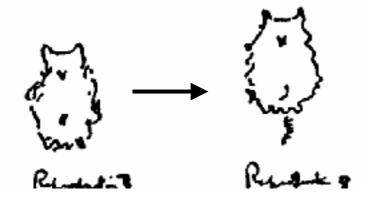


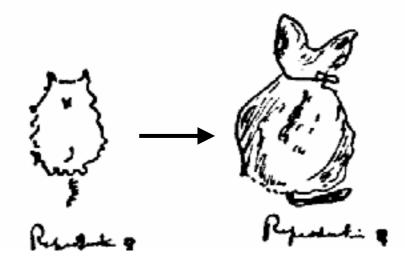


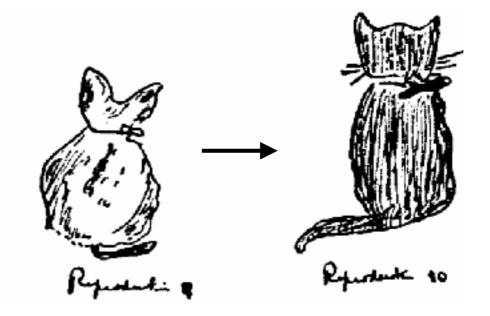


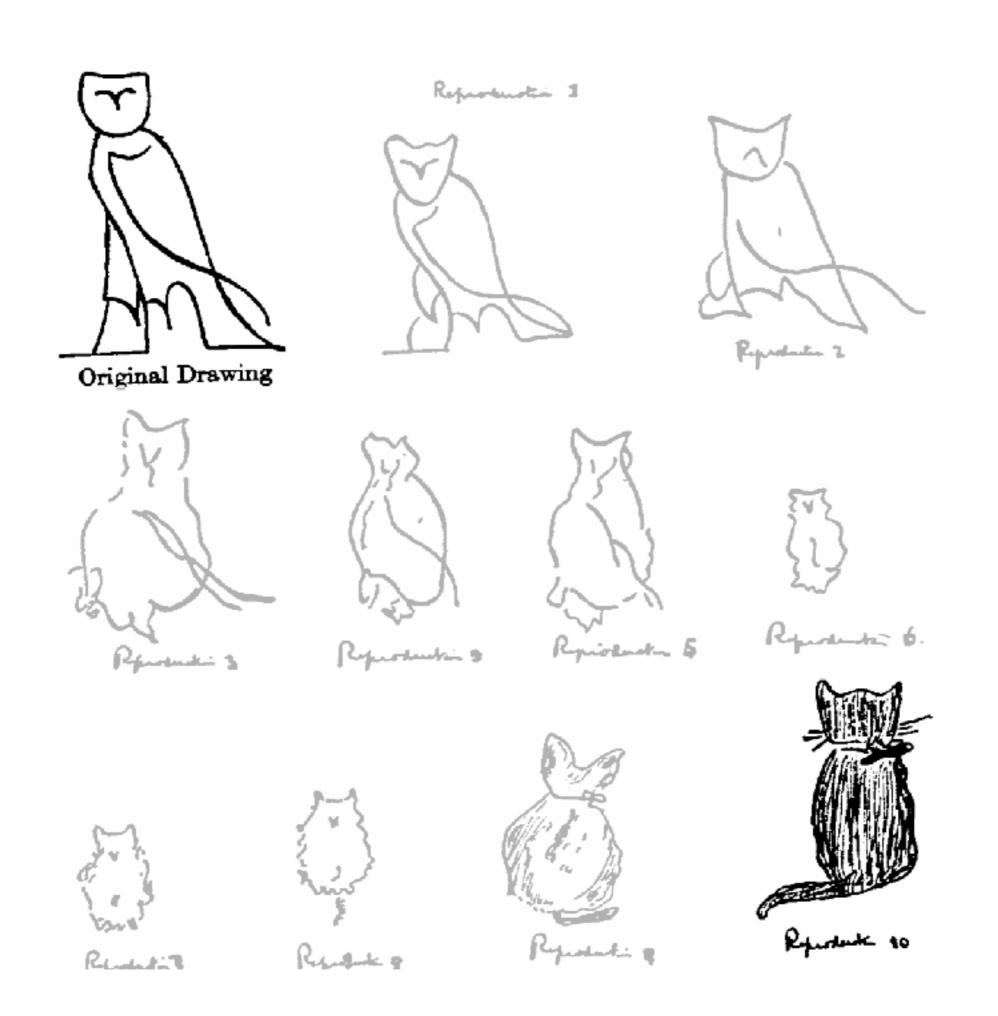


Permentit



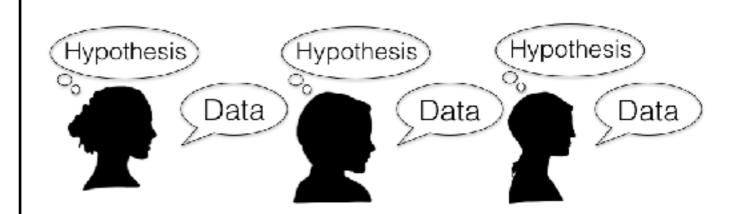






# Iterated learning with Bayesian agents reveals their shared prior

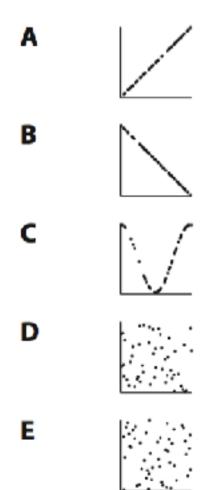
$$\begin{split} P(h_n = i) &= \sum_{j} P_{\text{samp},PA}(h_n = i \mid h_{n-1} = j) P(h_{n-1} = j) \\ &= \sum_{j} \sum_{d \in \mathcal{D}} P_{\text{samp}}(h_n = i \mid d) P_{PA}(d \mid h_{n-1} = j) P(h_{n-1} = j) \\ &= \sum_{d \in \mathcal{D}} P_{\text{samp}}(h_n = i \mid d) \sum_{j} P_{PA}(d \mid h_{n-1} = j) P(h_{n-1} = j) \\ &= \sum_{d \in \mathcal{D}} P_{\text{samp}}(h_n = i \mid d) P_{PA}(d) \\ &= \sum_{d \in \mathcal{D}} \frac{P_{PA}(d \mid h_n = i) P(h_n = i)}{P_{PA}(d)} P_{PA}(d) \\ &= P(h_n = i) \sum_{d \in \mathcal{D}} P_{PA}(d \mid h_n = i), \end{split}$$



(Griffiths & Kalish 2007)

## Example: function learning

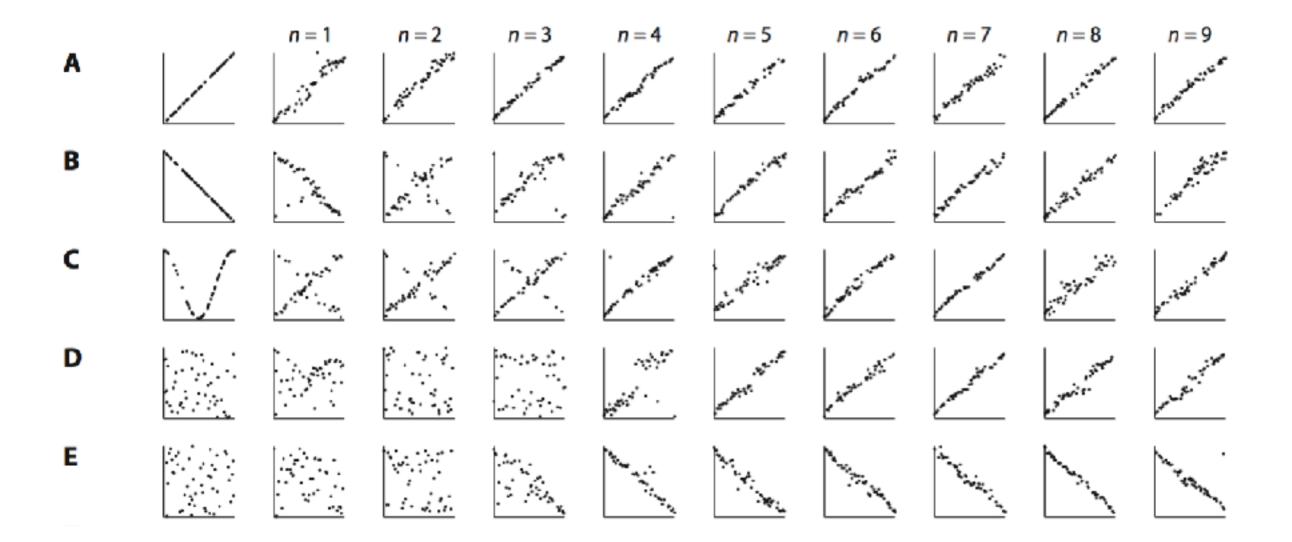
(Kalish et al 2007)



original

## Example: function learning

(Kalish et al 2007)



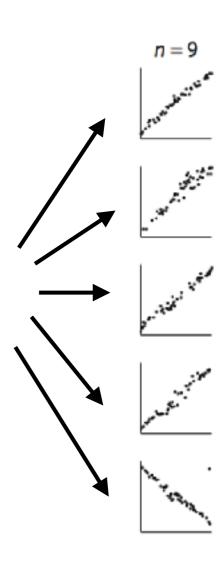
original

final

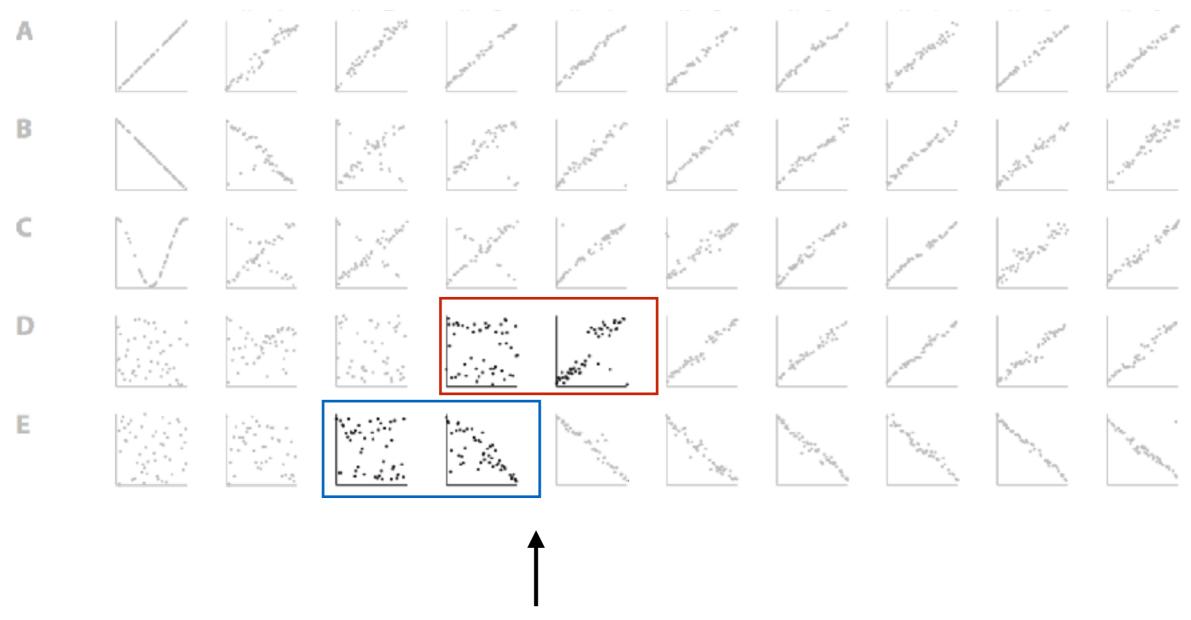
## Example: function learning

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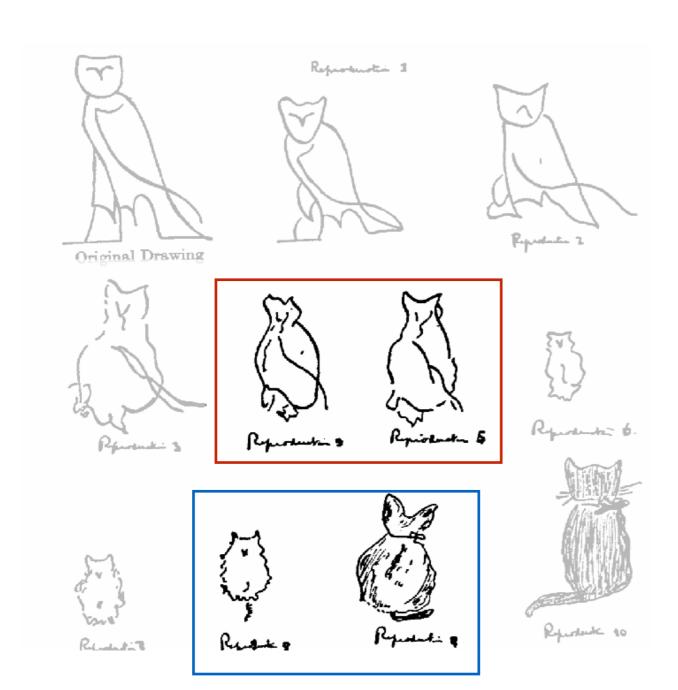
Conclusion: the cognitive system has a prior bias for linear functions



## The individual differences question

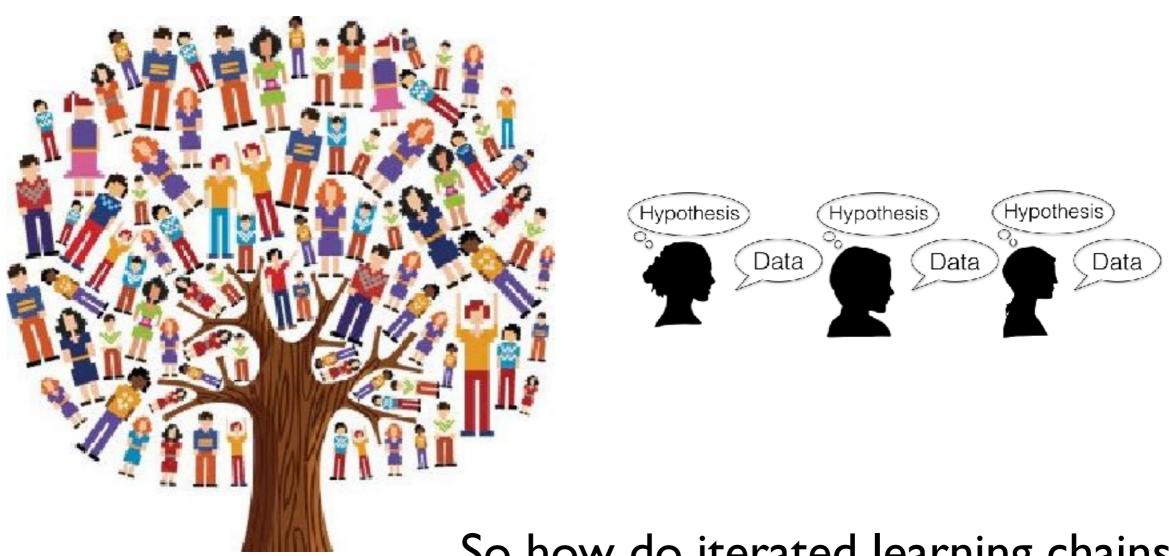


Do these two people have the same "inductive bias" that the procedure reveals?



# This seems unlikely to reflect a shared prior?

## Individual differences are ubiquitous

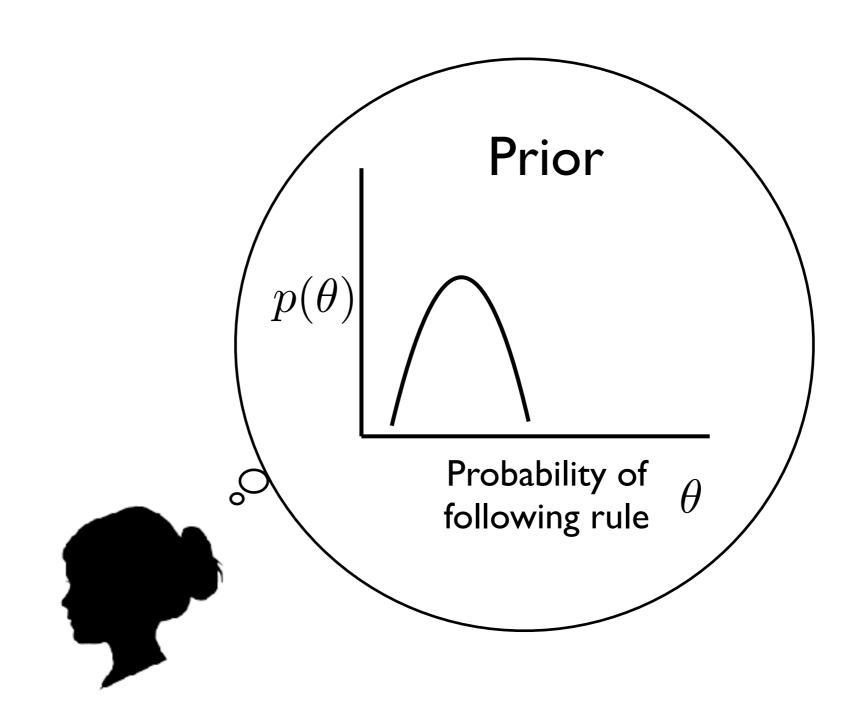


So how <u>do</u> iterated learning chains behave when individual differences exist?

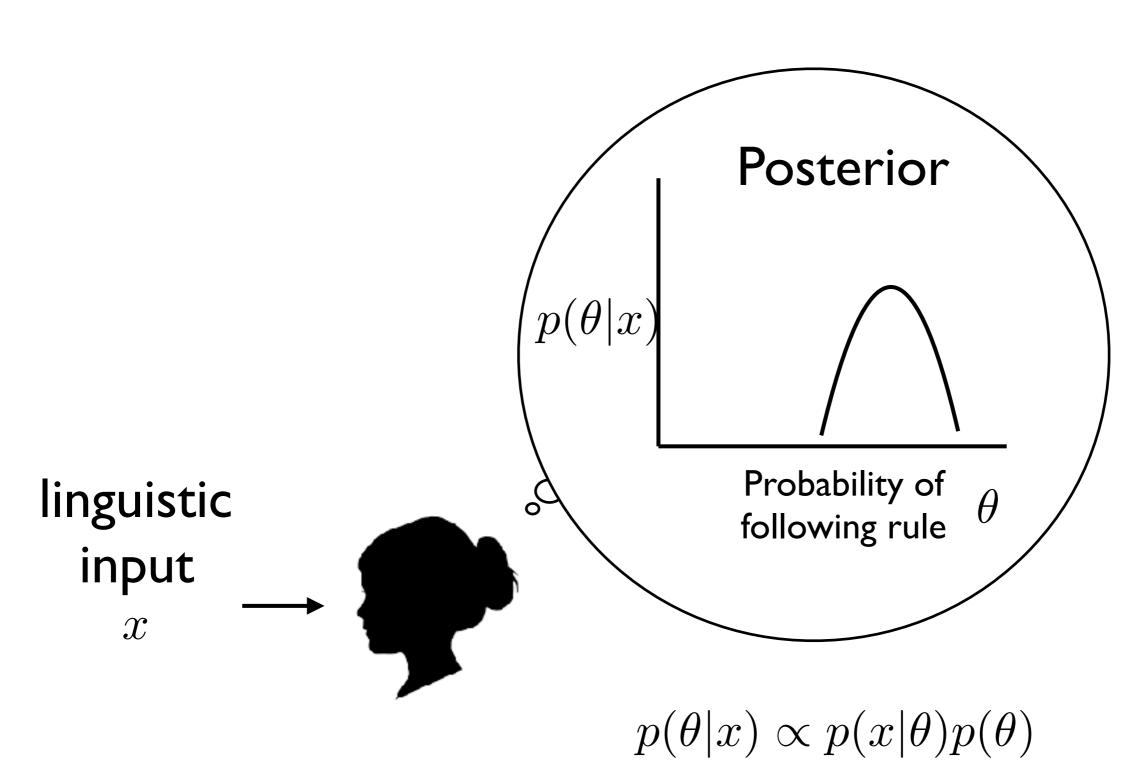
## Case study 1:

Does everybody contribute equally to the evolution of languages?

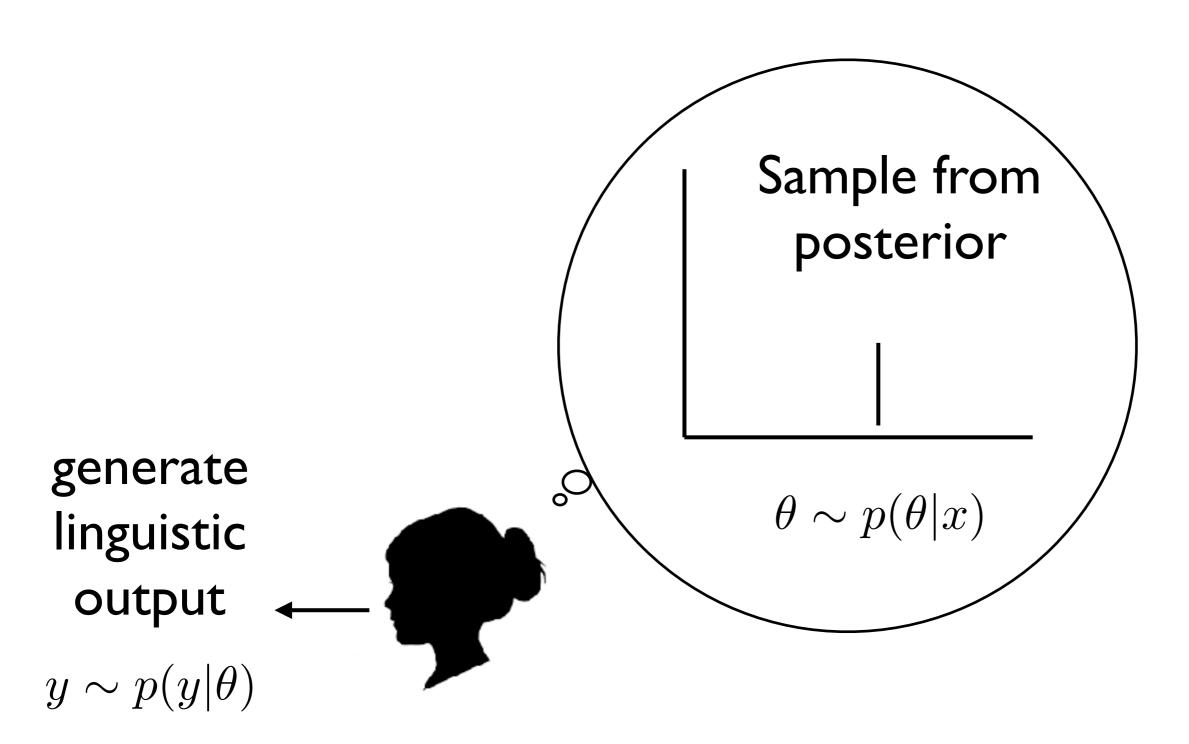
## A simple Bayesian learner



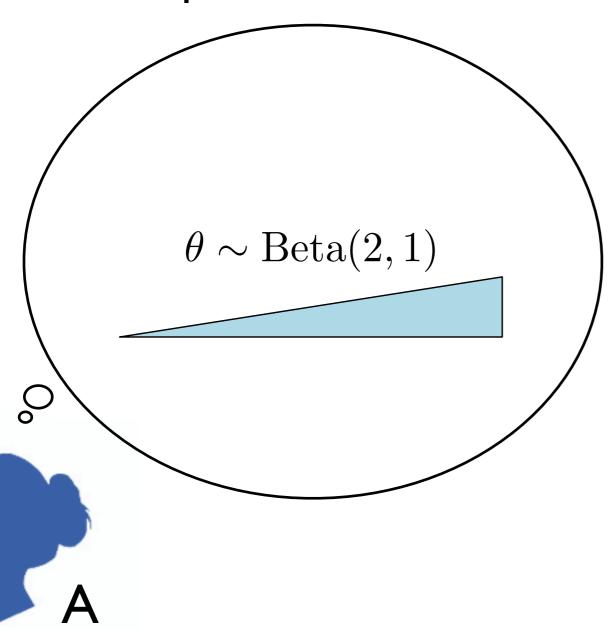
## A simple Bayesian learner



## A simple Bayesian learner

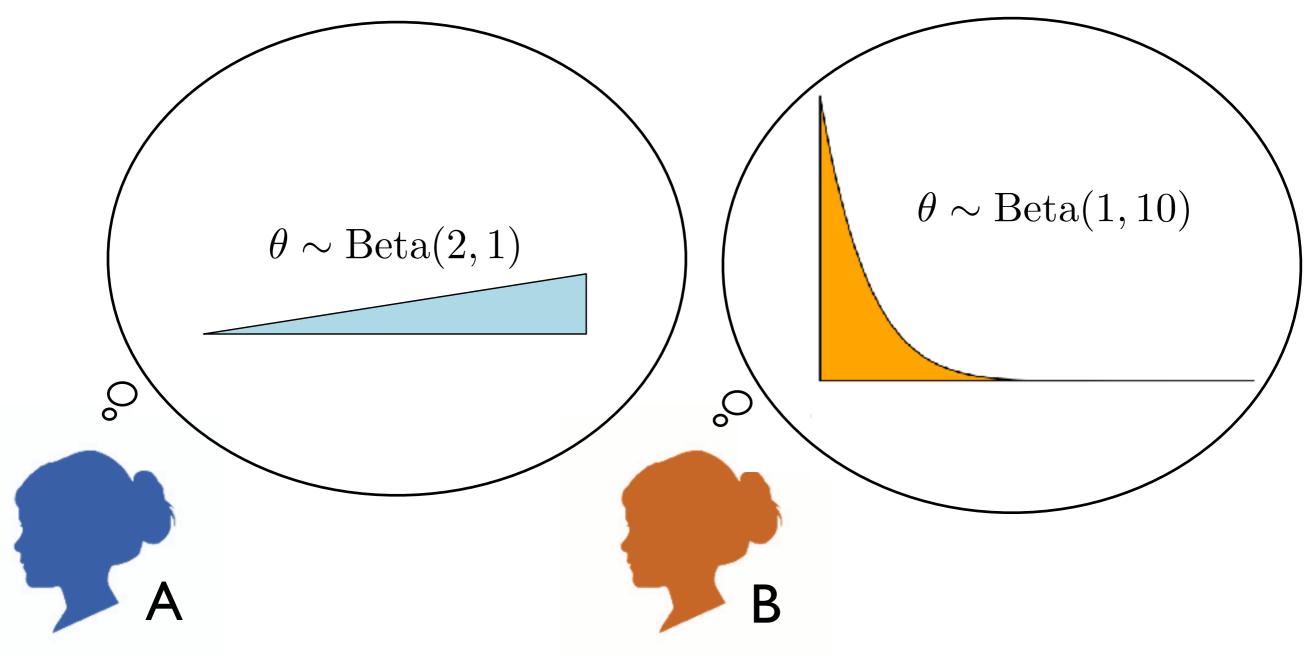


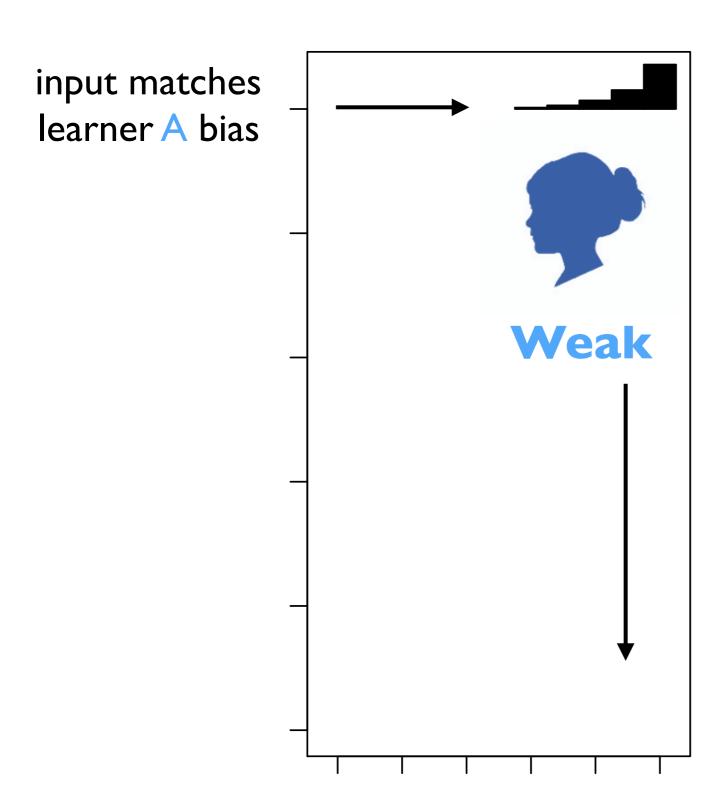
Some learners use a prior that imposes a weak bias



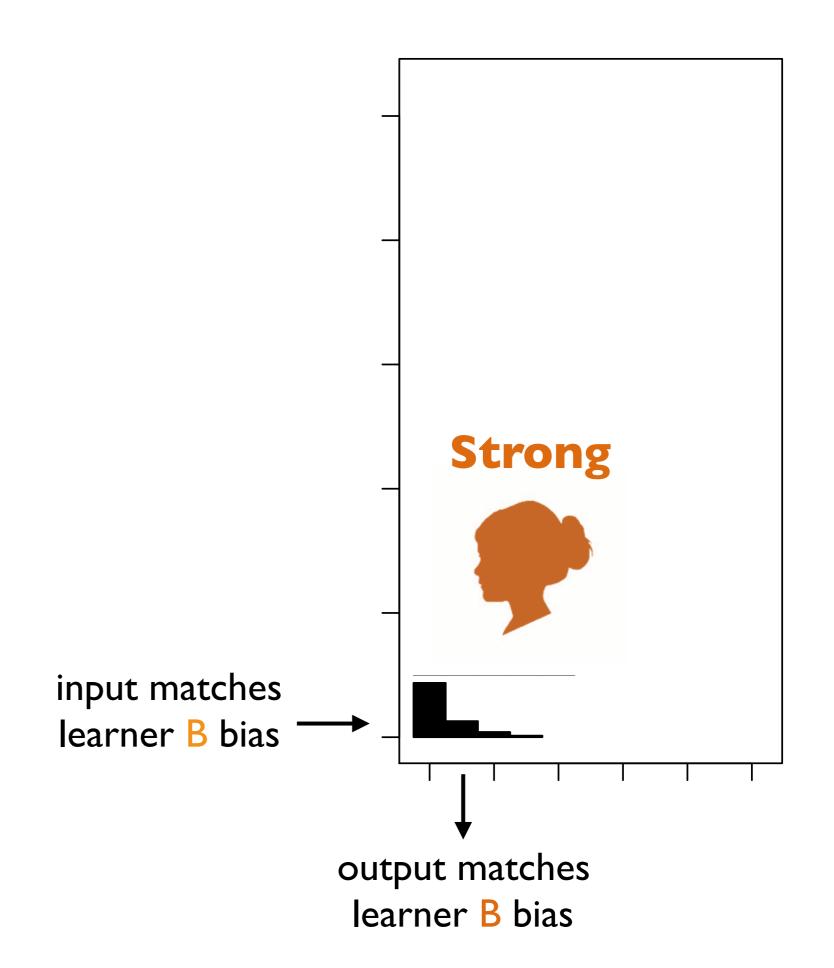
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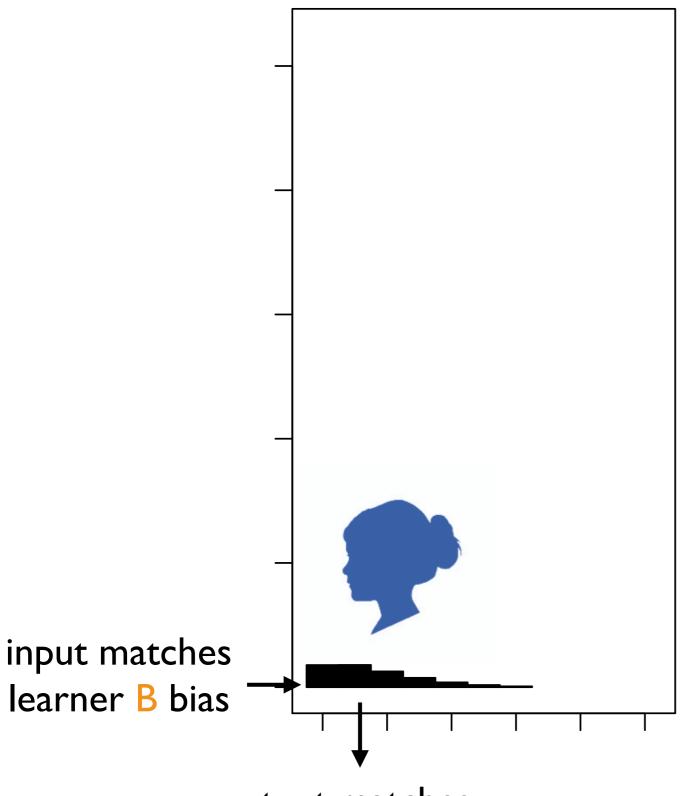
Some learners use a prior that imposes a strong bias





output matches learner A bias





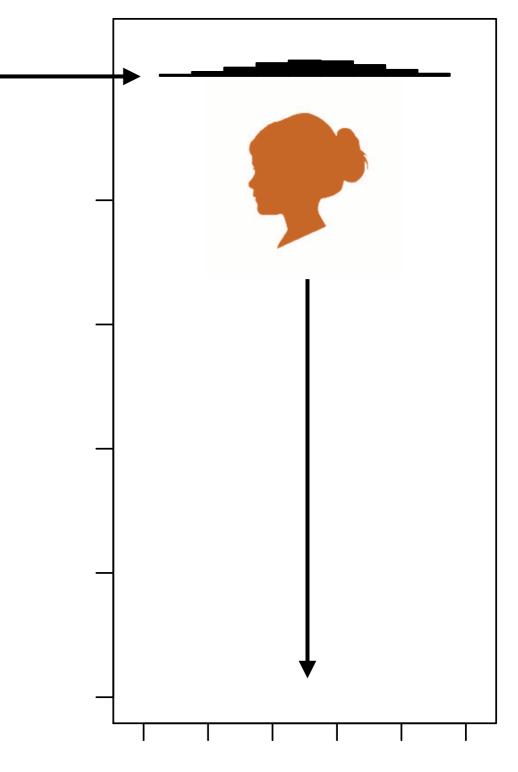
Learners with weak biases tend to mirror input even when it disagrees with the learner bias

output matches learner B bias

input matches learner A bias

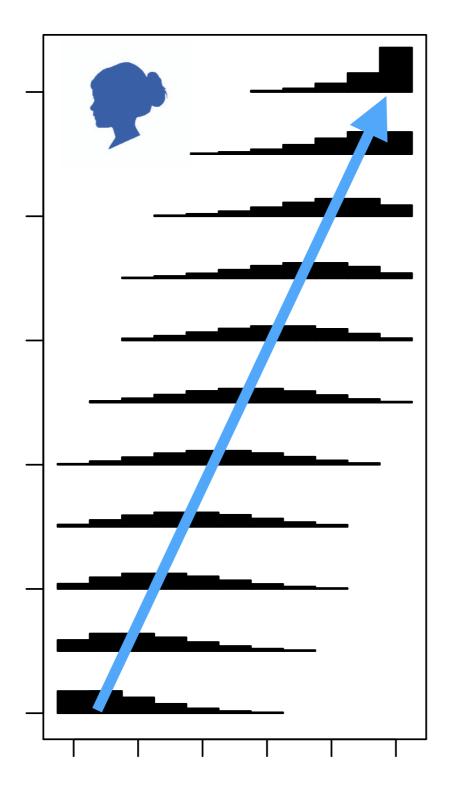
Learners with strong biases do not:

They (partially) impose their own biases

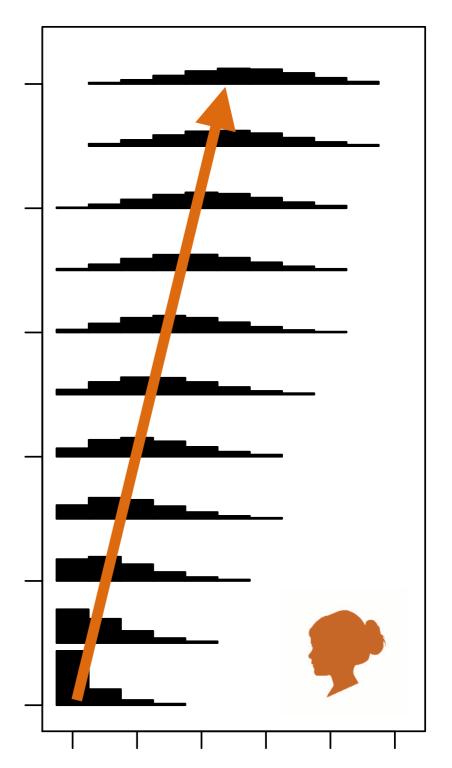


output is a compromise between learner B bias and the input

#### Weak bias

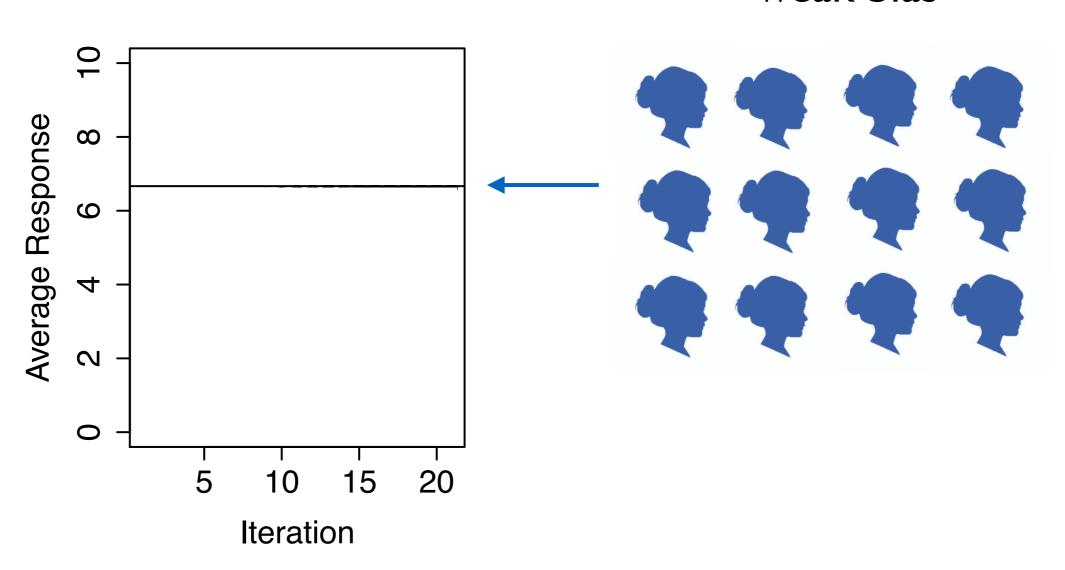


#### **Strong bias**

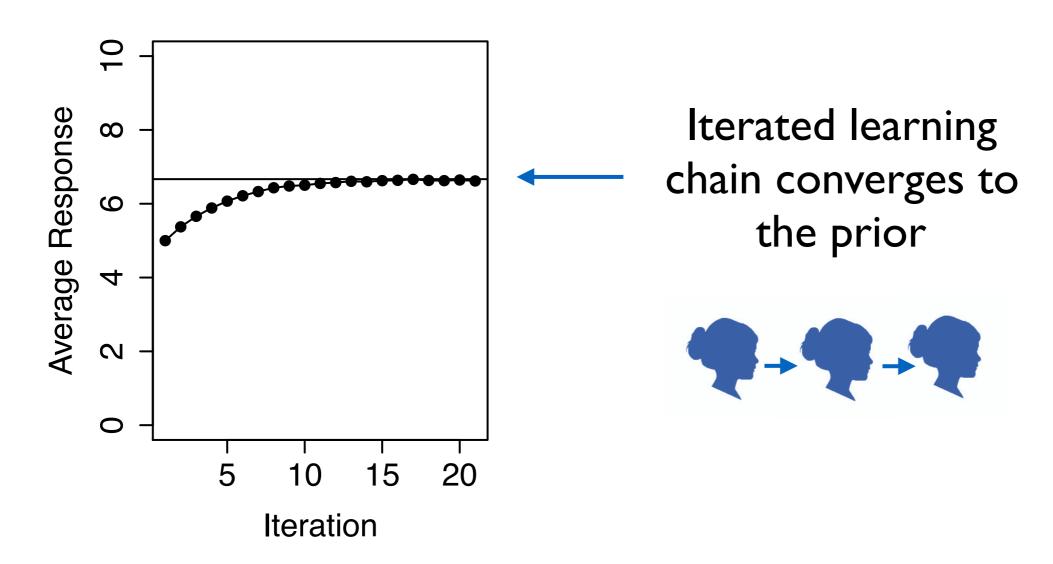


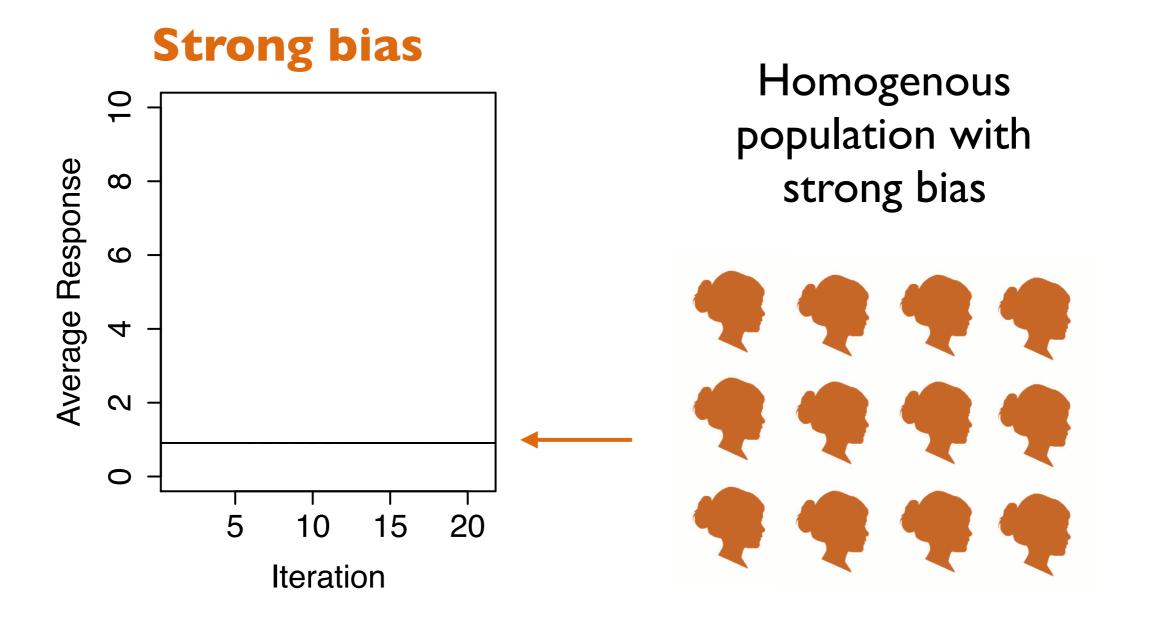
## Homogenous population with weak bias

#### **Weak bias**



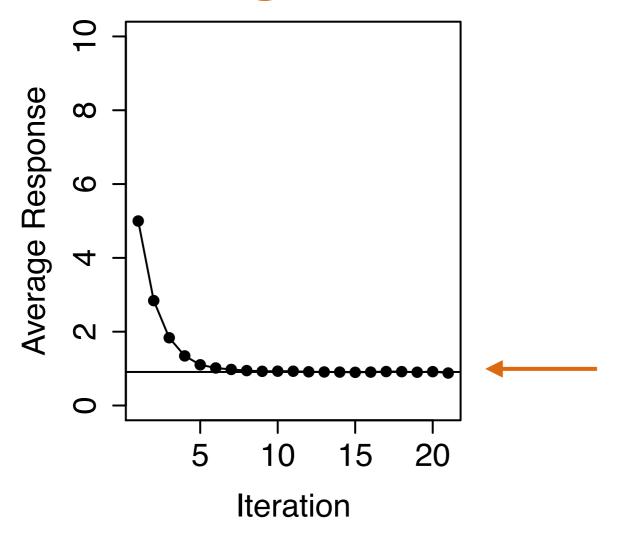
#### **Weak bias**





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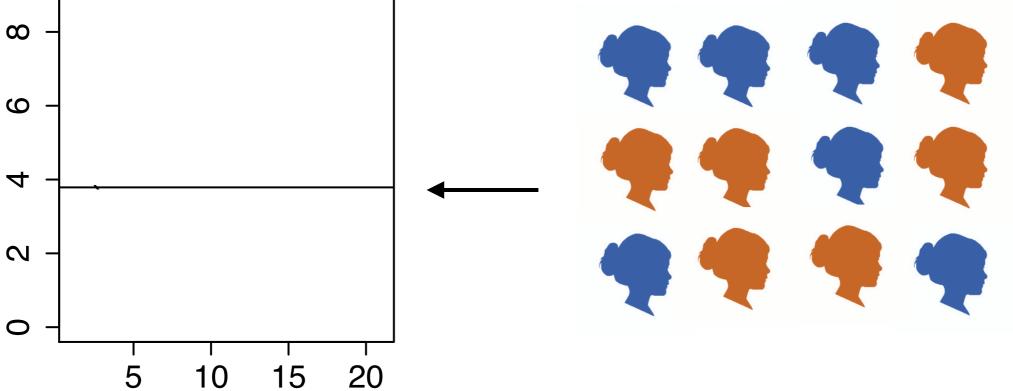
#### **Strong bias**



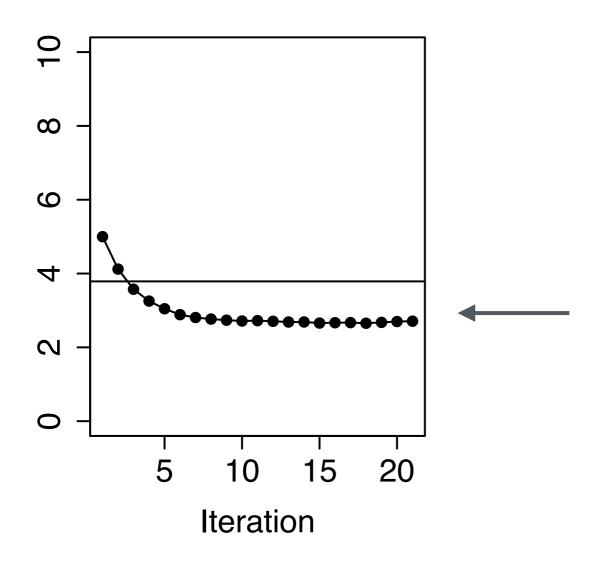
Iterated learning chain converges to the prior



## Heterogenous population with equal proportions of both learner types



Iteration

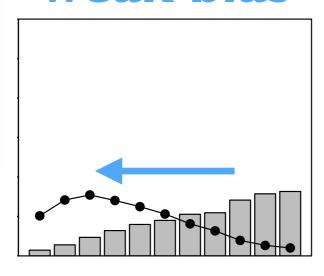


Mixed chain does not converge to the prior

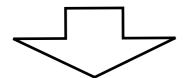




#### weak bias



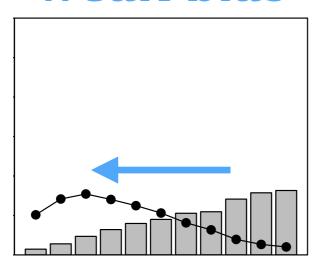
weak bias



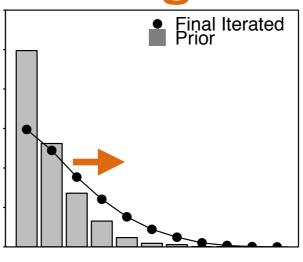
very responsive to input



#### weak bias

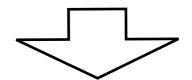


#### strong bias



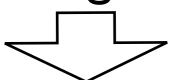


weak bias



very responsive to input

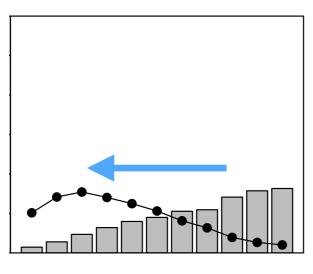
strong bias



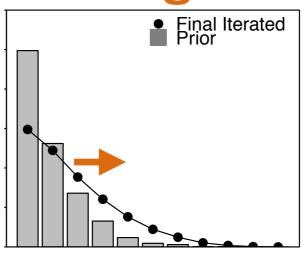
insensitivity to input



#### weak bias

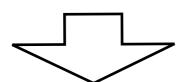




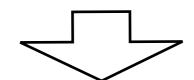




weak bias

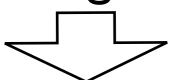


very responsive to input

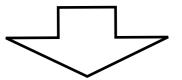


small influence on the chain

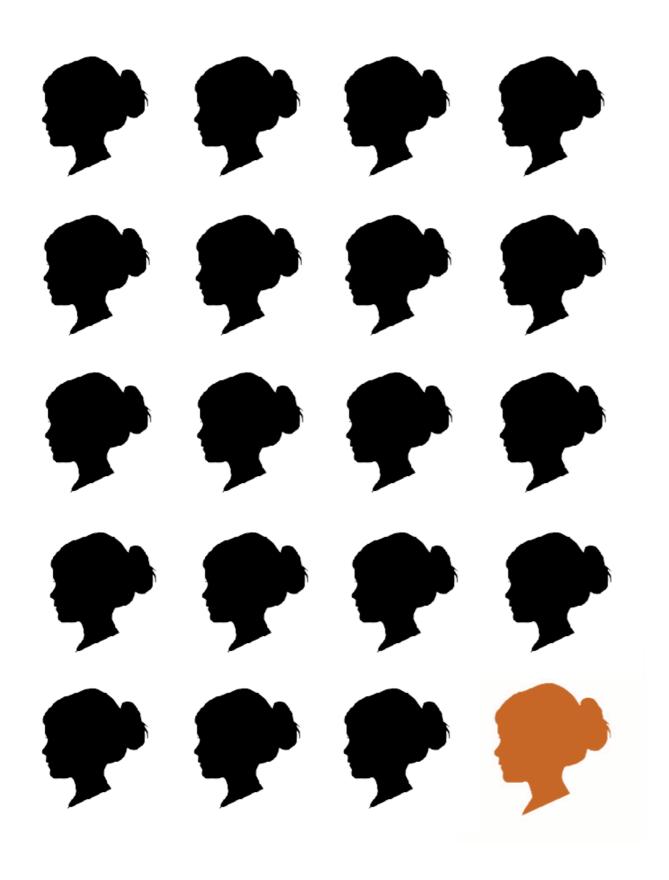
strong bias



insensitivity to input

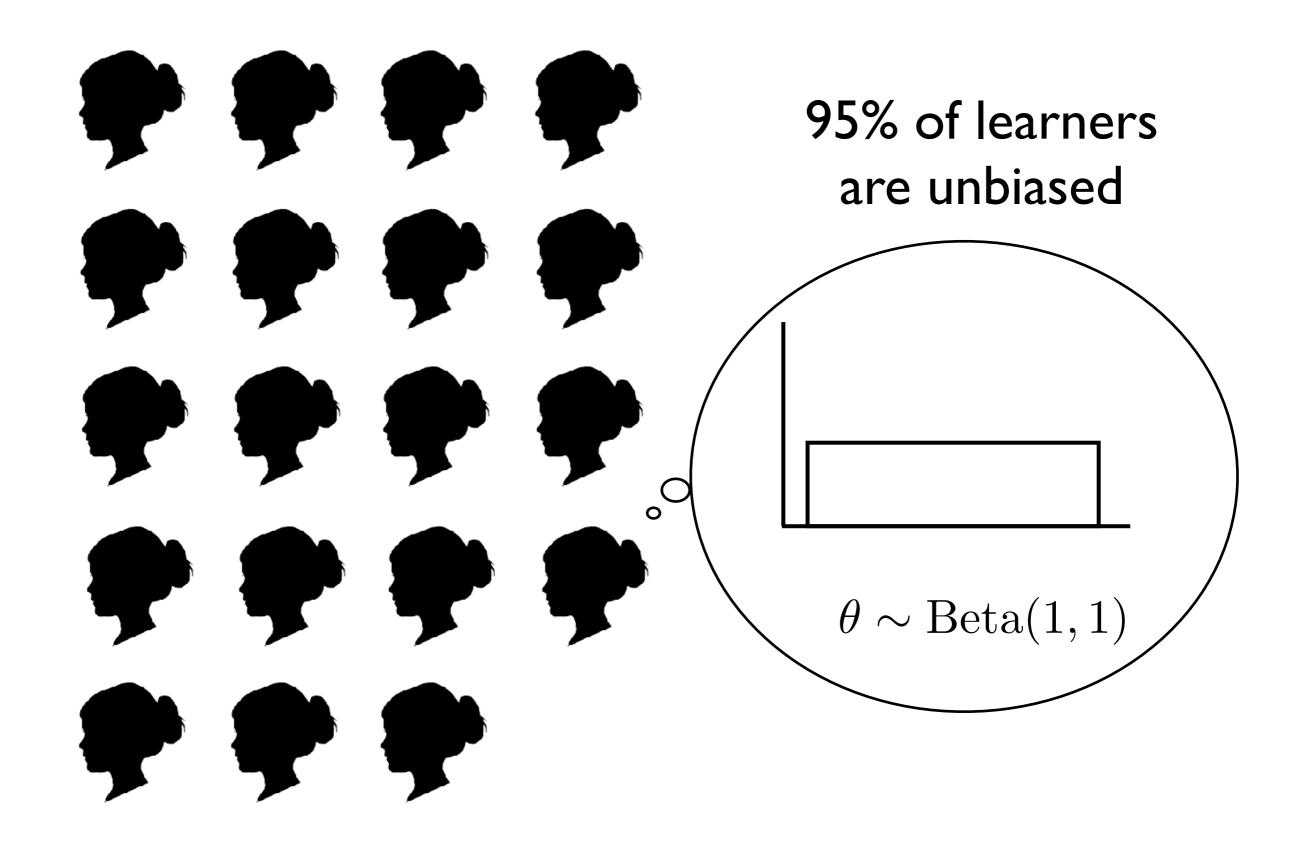


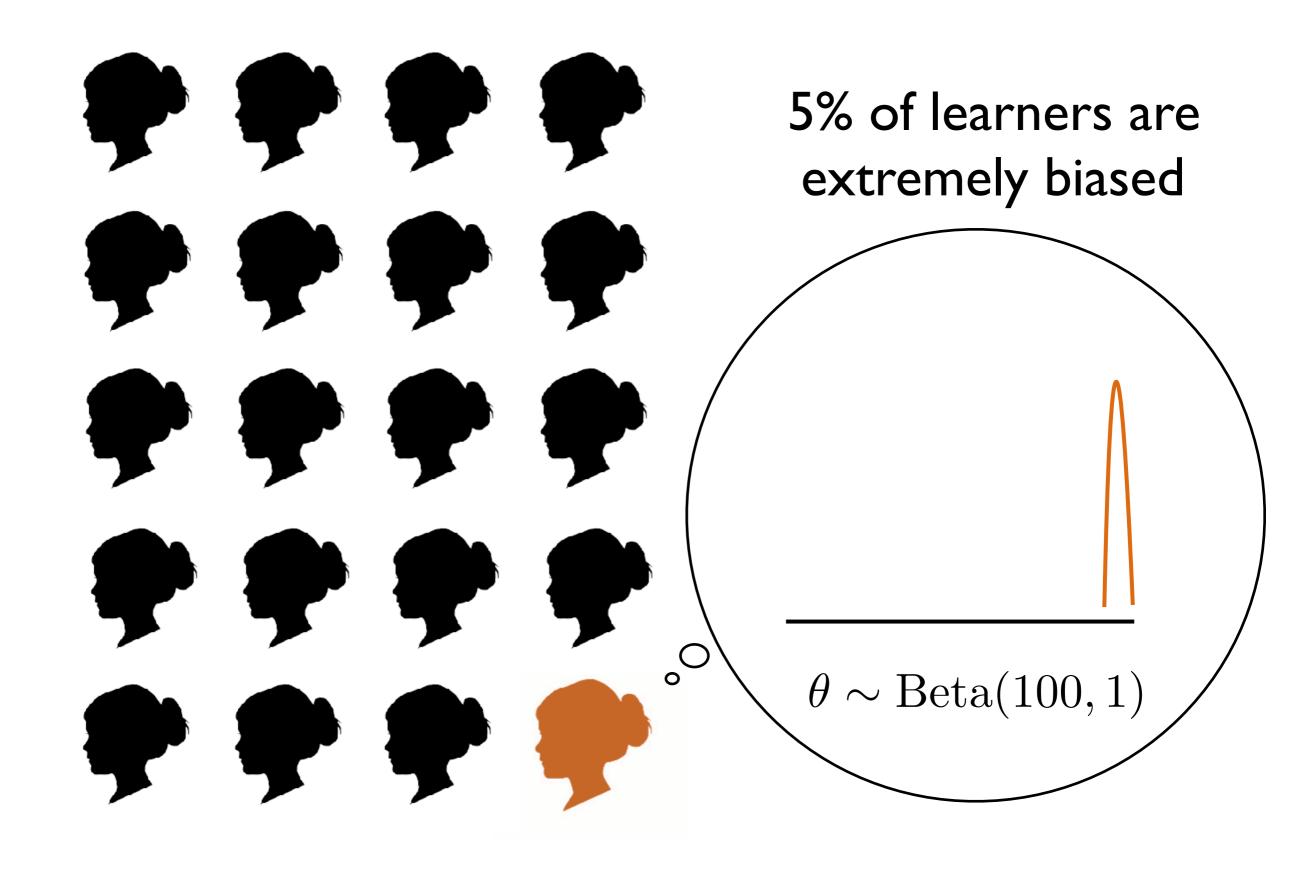
greater influence on the chain



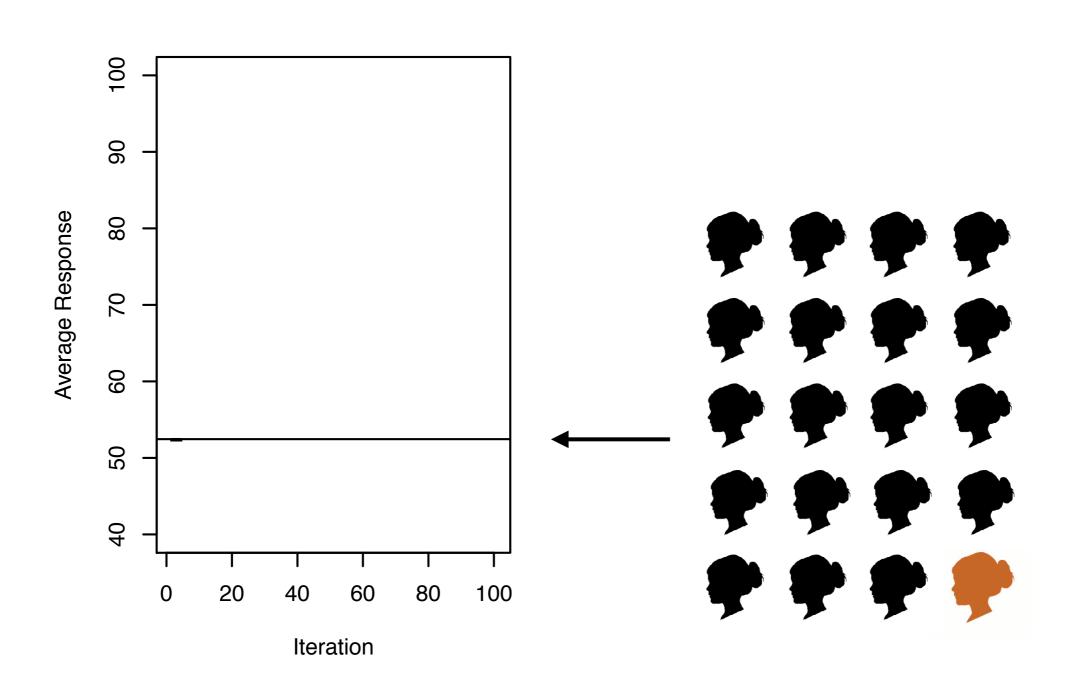
How much influence can a strong bias confer?

An extreme example

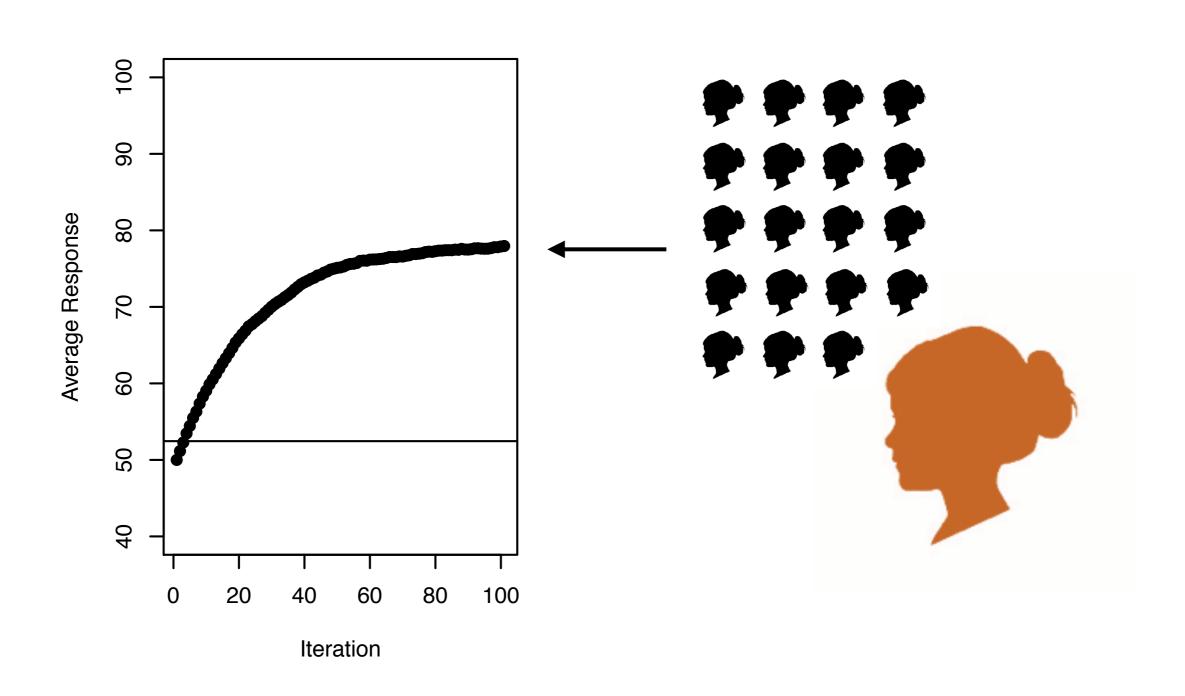




## The average response if everyone samples from their prior

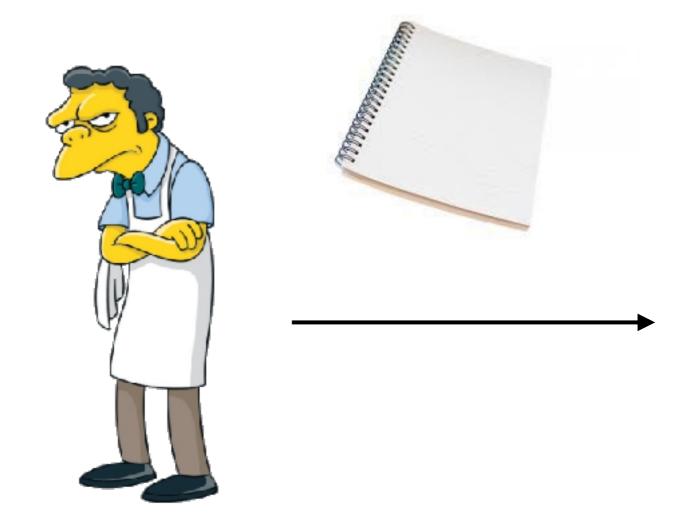


## Iterated learning chain is dominated by the extreme bias learners

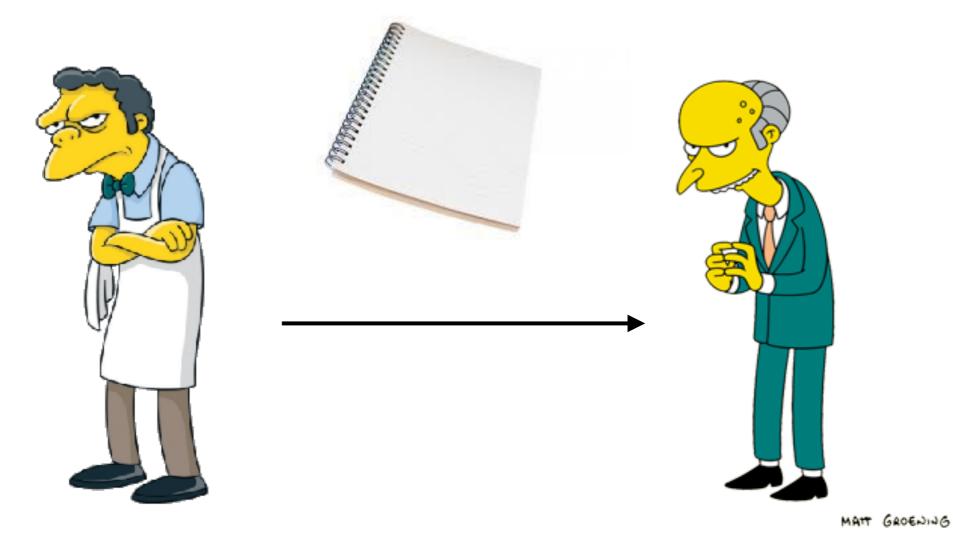


## Case study 2: How to induce Bayesian groupthink





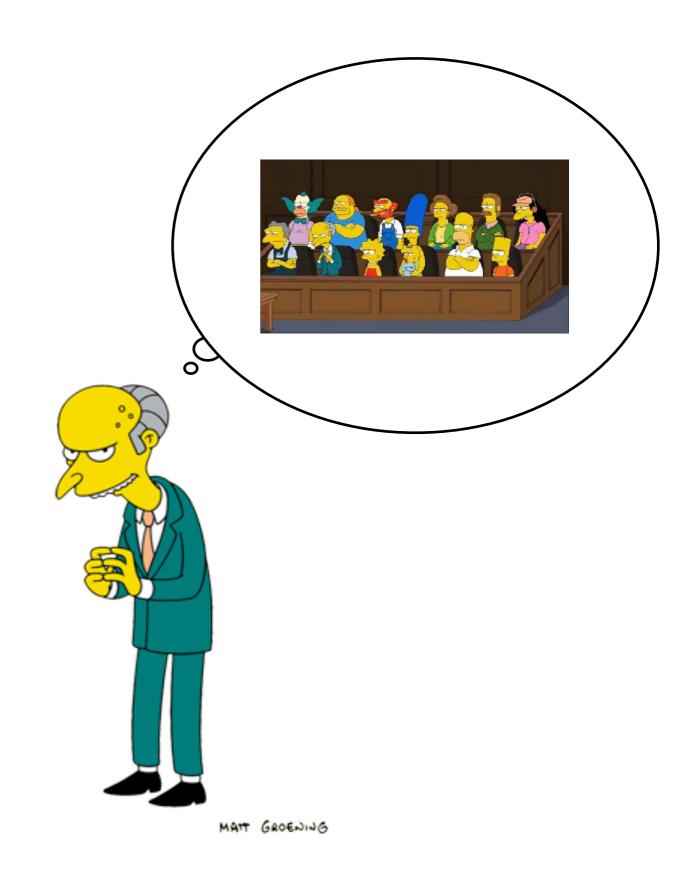
Juror *i* records vote, removes sheet, passes notebook



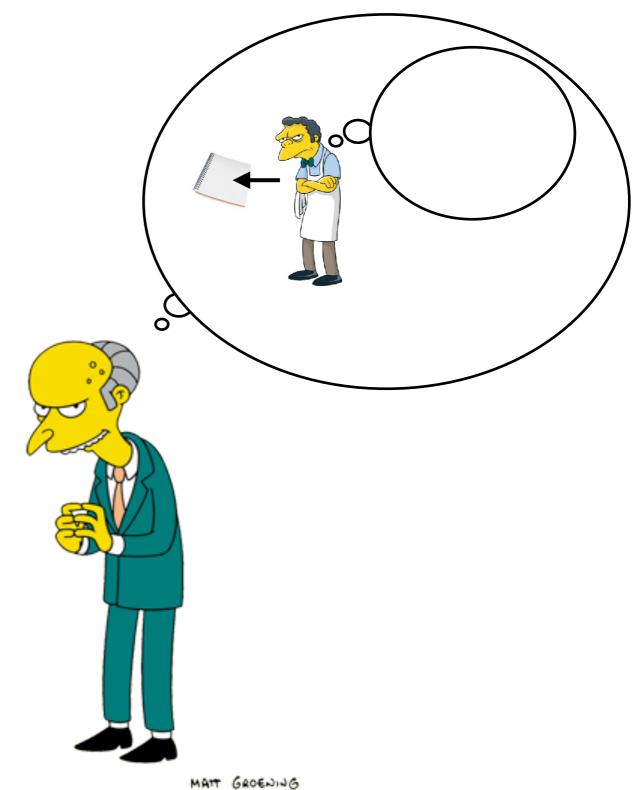
Juror *i* records vote, removes sheet, passes notebook

Juror i+1 can see the previous vote via indentations...

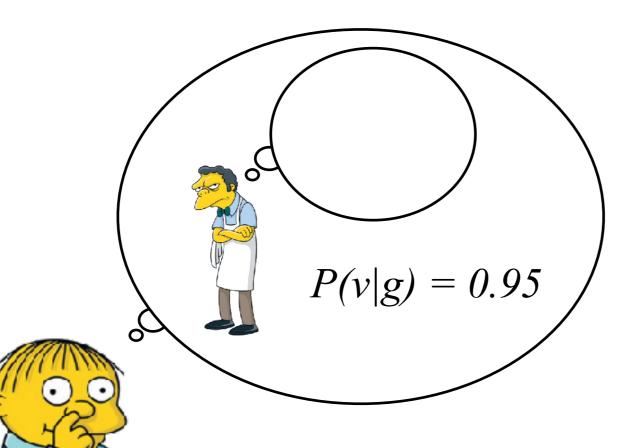
Prior belief about guilt P(g) is set by the trial



Likelihood of previous juror's vote P(v|g) requires a theory of the other juror... what do they know that I don't know?

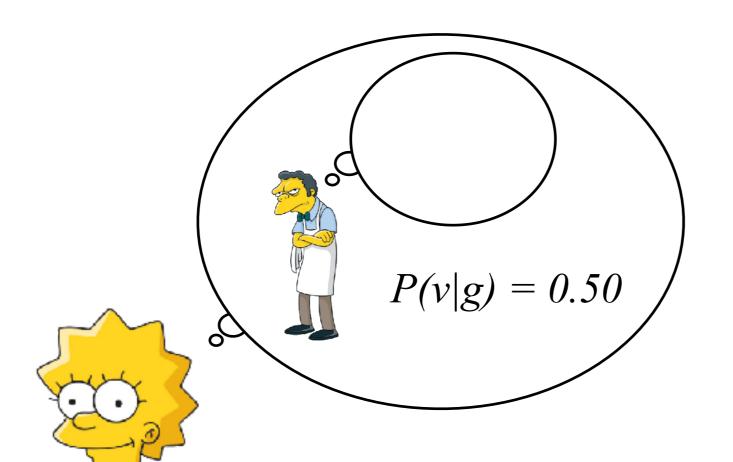


#### Bayesian "sheep"

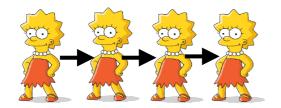


Assumes previous juror has considerable additional knowledge, assigns evidentiary weight to their opinion

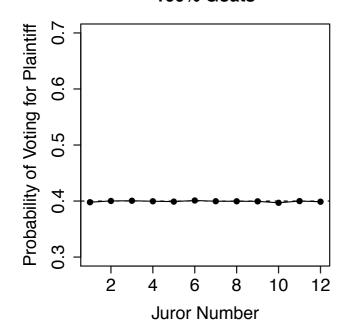
#### Bayesian "goat"



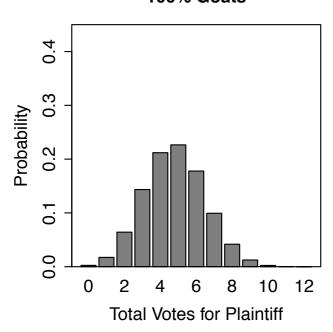
Assumes previous juror has no extra knowledge, assigns zero weight to their opinion



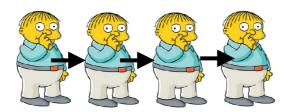
#### 100% Goats



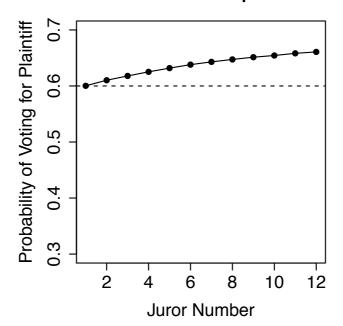
#### 100% Goats



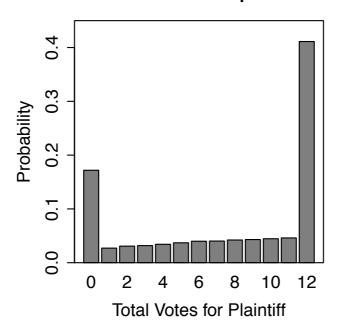
## A jury of goats ignores one another and the "chain" converges just fine



100% Sheep



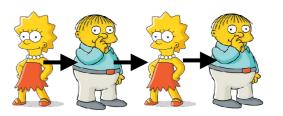
100% Sheep



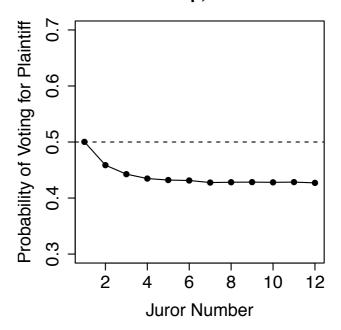
## A jury of sheep displays groupthink

$$\pi T \propto [d,p] \begin{bmatrix} 1-p & p \\ d & 1-d \end{bmatrix} \\
= [d(1-p)+pd,dp+p(1-d)] \\
= [d,p] \propto \pi$$

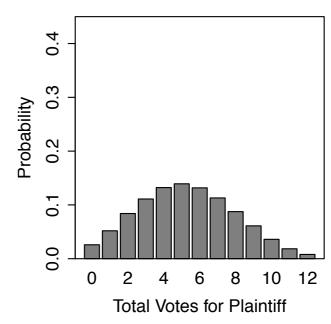
A mixed jury is dominated by goats



50% Sheep, 50% Goat



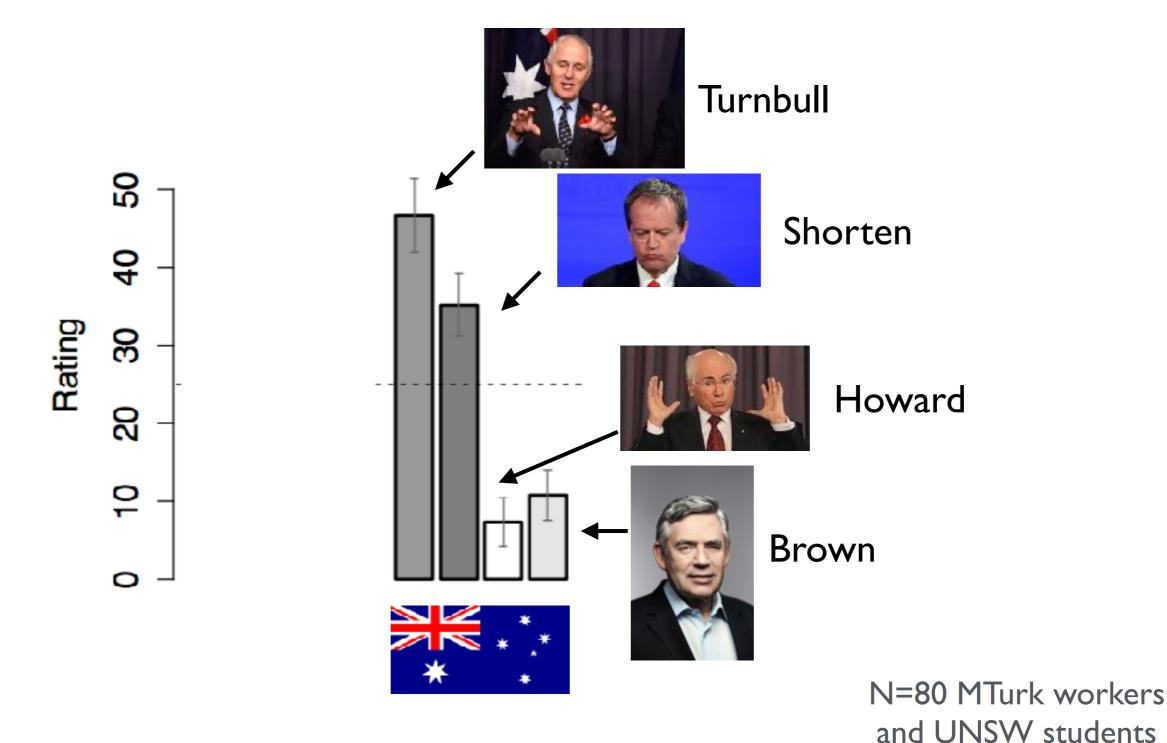
50% Sheep, 50% Goat

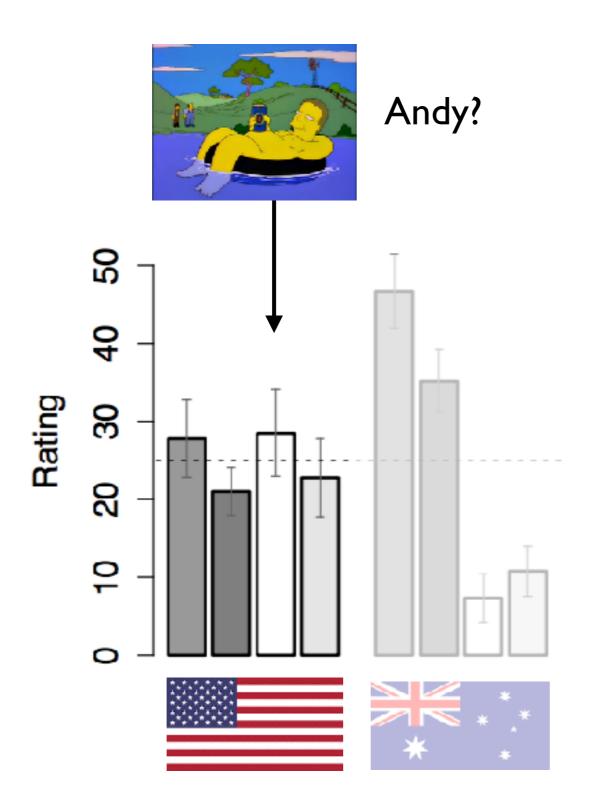


#### Case study 3:

Using differential expertise to create a sheep/goat split in an empirical context

#### "Who will win the 2016 Australian election?"





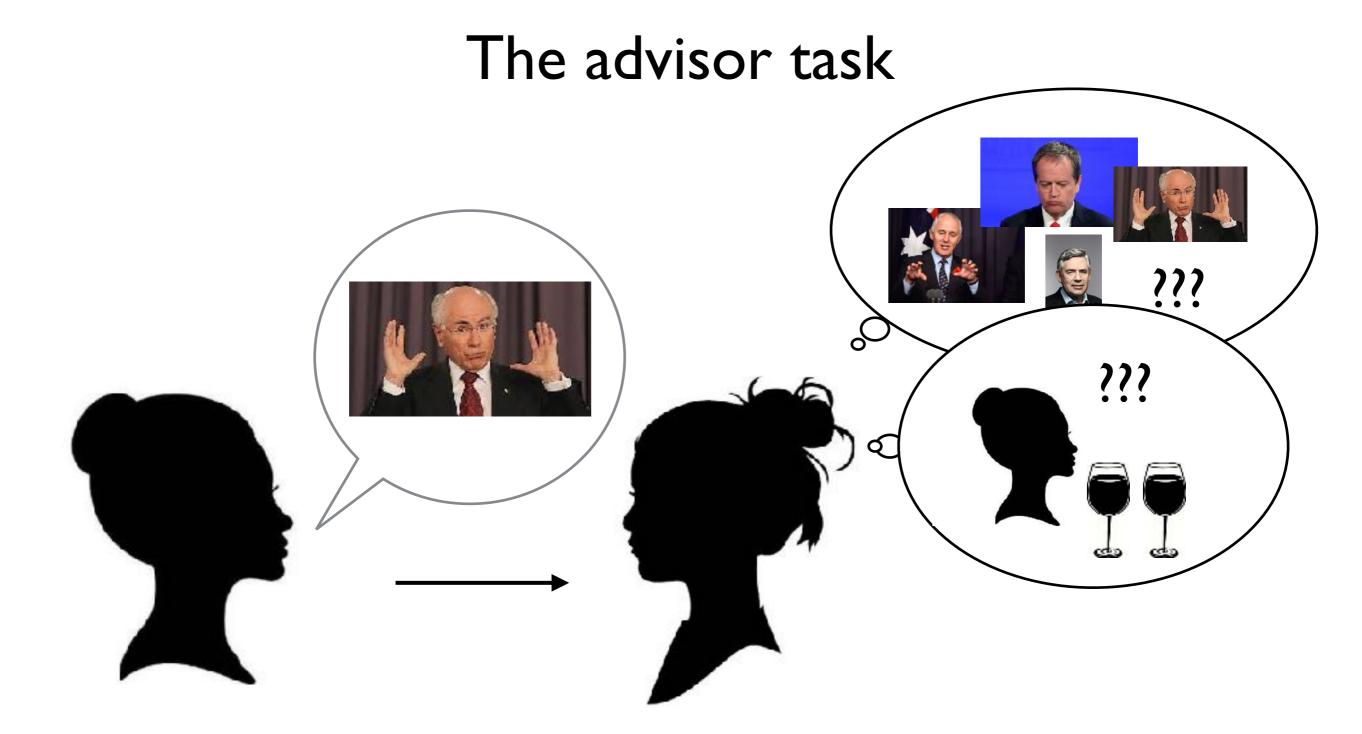
#### The advisor task

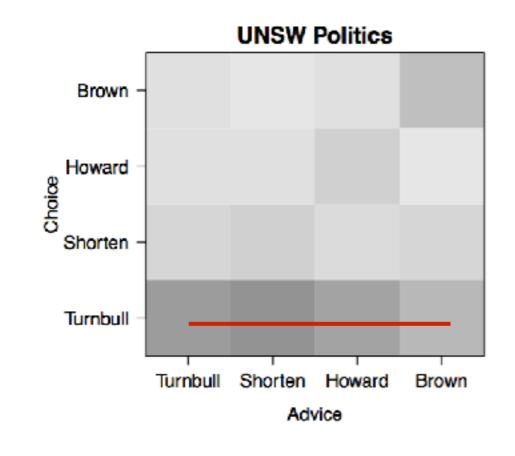
"Imagine that you are at your local bar with some friends.

After several drinks, the topic of conversation turns to politics.

You are asked for your opinion on which of the following politicians will win the next Australian Federal Election.

One of your close friends recommends that you say [insert option]. You know that they follow Australian politics quite closely and know a lot about it; on the other hand, they have just had several alcoholic drinks. In light of their recommendation, who do you think will win the election?"





## Australians ignored the advisor and predicted a Turnbull victory

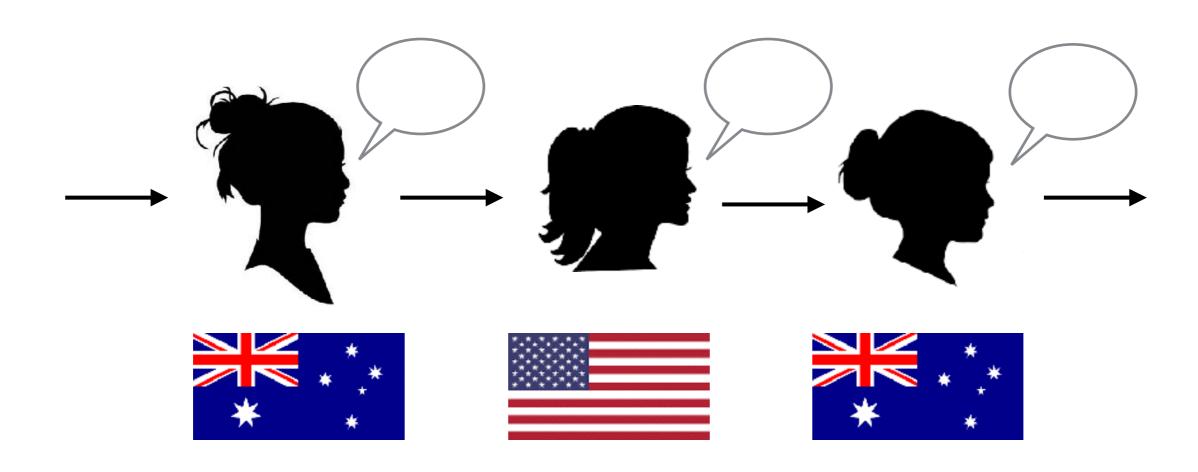


# Brown Howard Shorten Howard Brown Advice

## Americans followed the advisor regardless

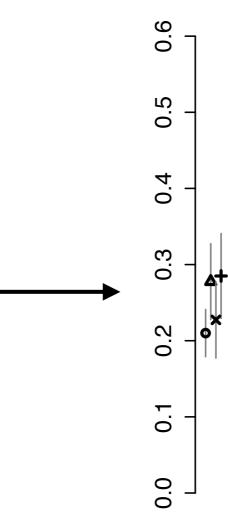


Using these empirical transition matrices we can construct iterated learning chains with any mixture of nationalities

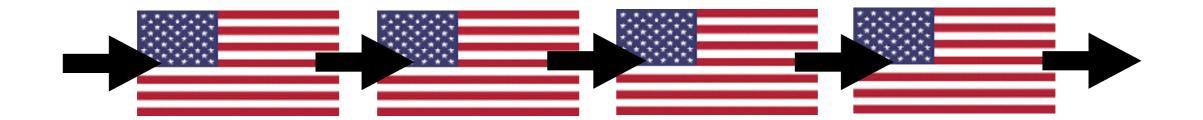




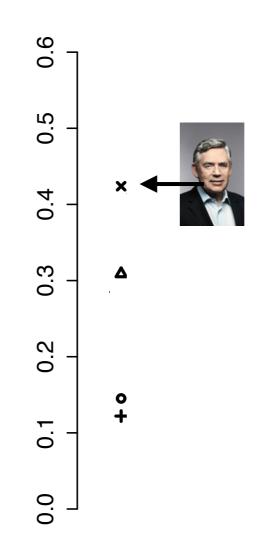
Americans *claim* to be totally ignorant about Australian politics...

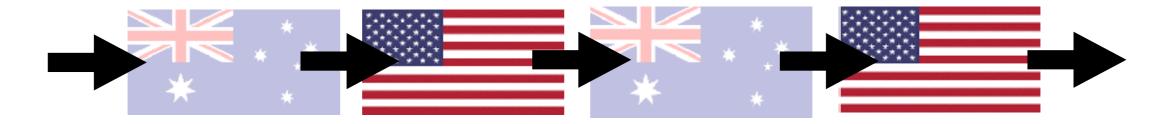


- Shorten△ Turnbull+ Howard× Brown

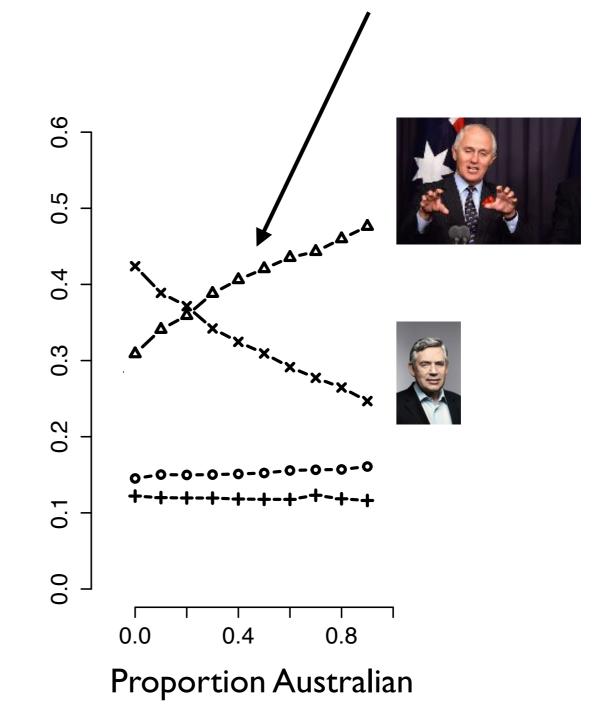


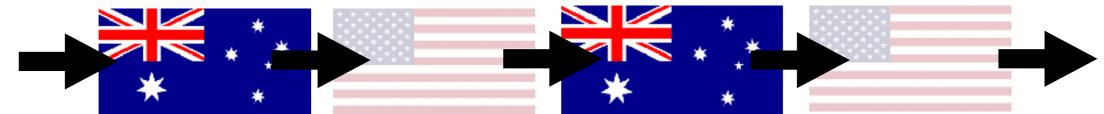
... and an all American iterated learning chain "reveals" a "preference" for *Gordon Brown* ...





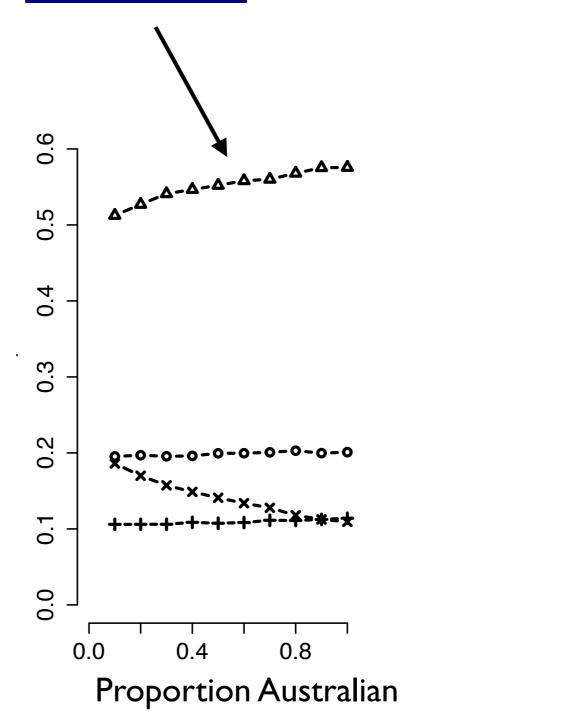
... but if we mix some Australians into the chain the Americans endorse Malcolm Turnbull





Australians choose
Turnbull no matter
how many Americans
are included





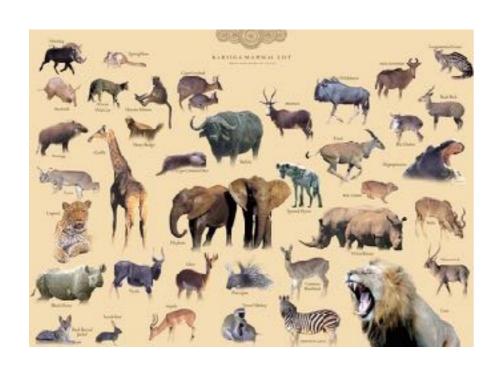
## Case study 4:

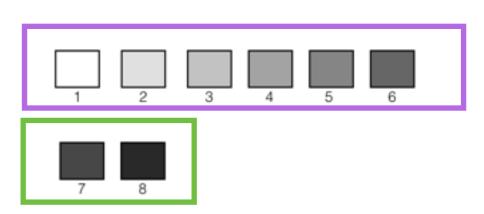
It's not always obvious which inductive biases are distorted by heterogeneity



Iterated learning can be used to study the biases people bring to categorisation problems

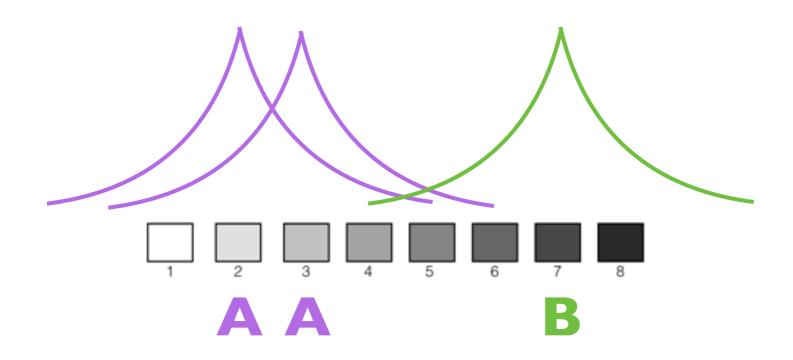
(e.g., Austerweil 2014)





## Exemplar model of categorisation

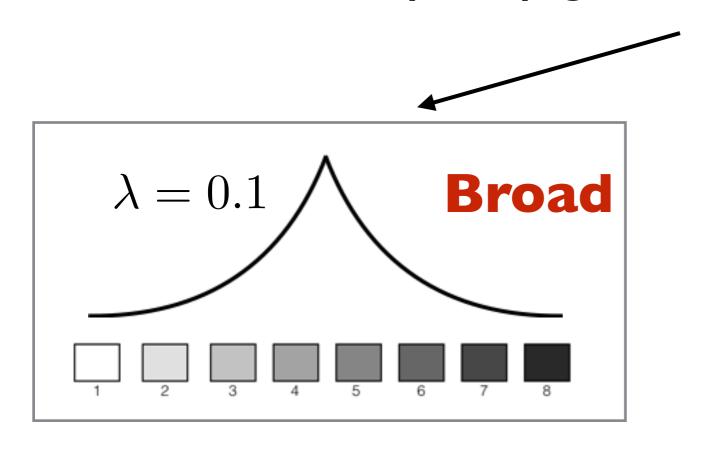
(Nosofsky 1986; Pothos & Bailey 2009)



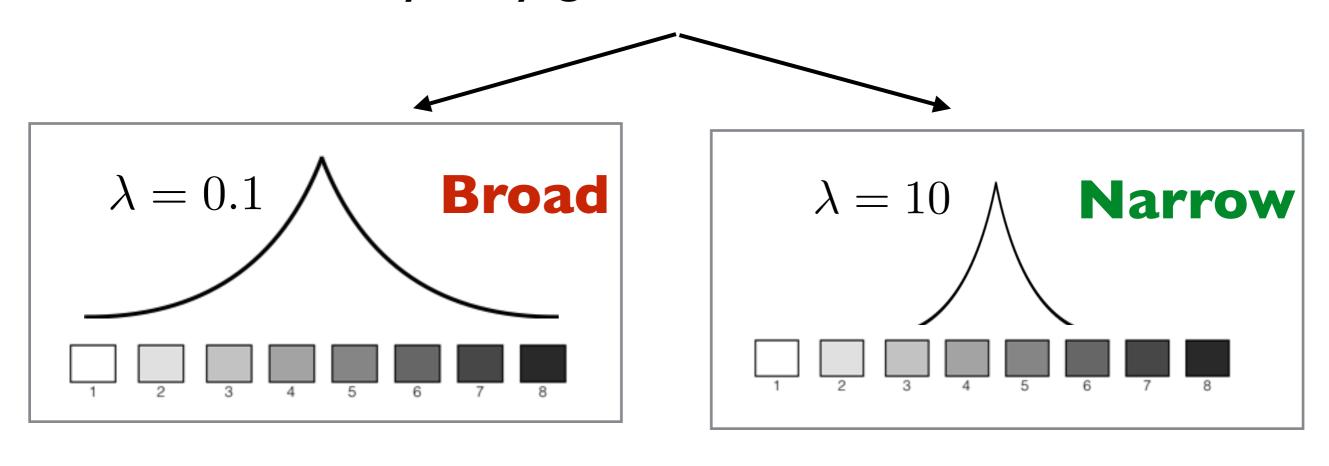
## GCM: categorisation probability is proportional to sum similarity

$$P(y \in A) = \frac{\sum_{a \in A} s(a, y)}{\sum_{x \in X} \sum_{x \in X} s(x, y)}$$

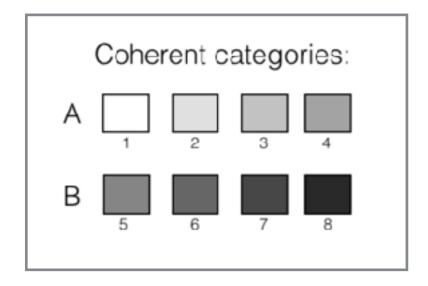
# GCM allows learners to vary in how broadly they generalise from a stimulus



# GCM allows learners to vary in how broadly they generalise from a stimulus



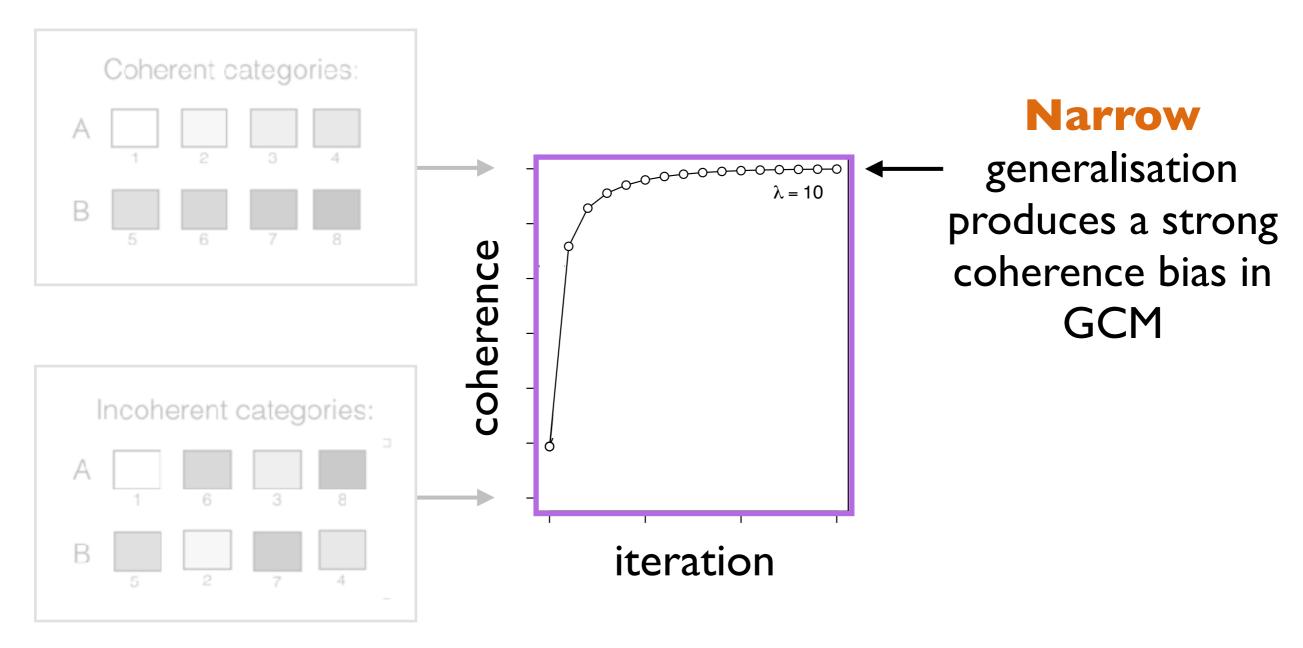
### Categorisation bias #1



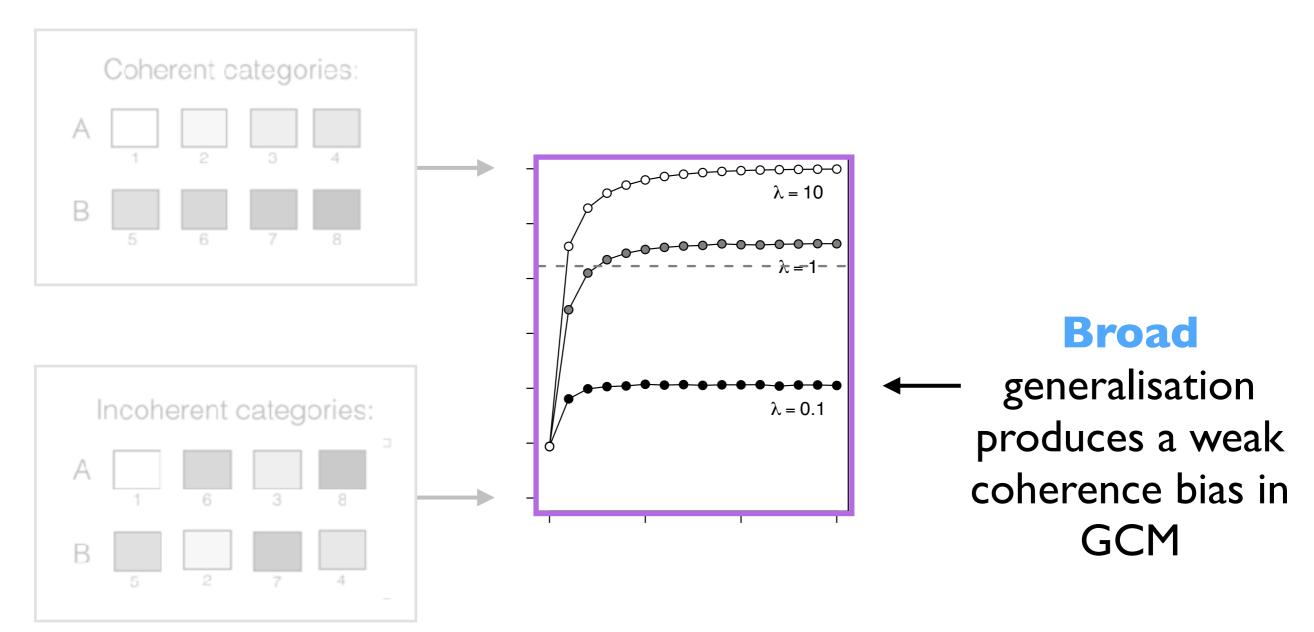
<u>Coherent</u> systems
assign similar items
to the same category



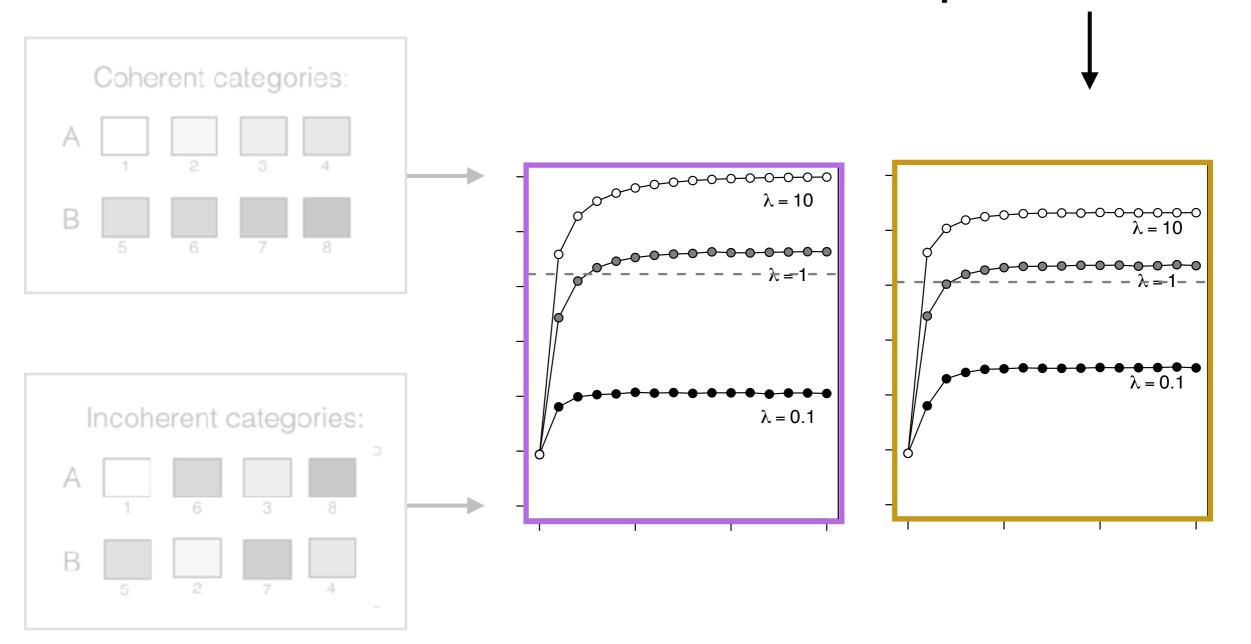
## Homogenous population

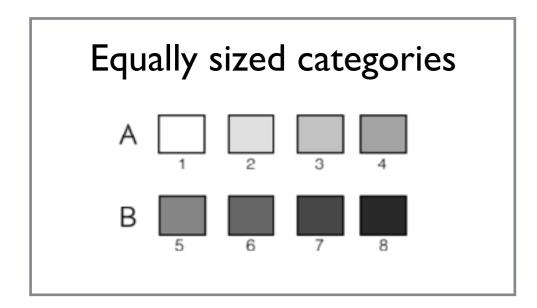


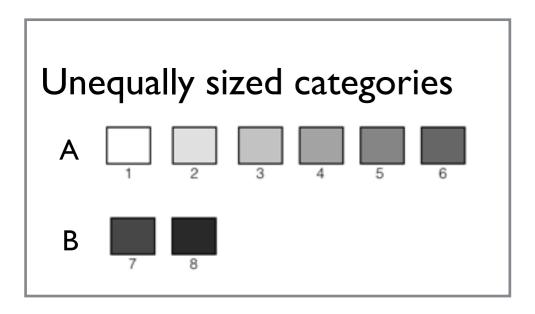
## Homogenous population



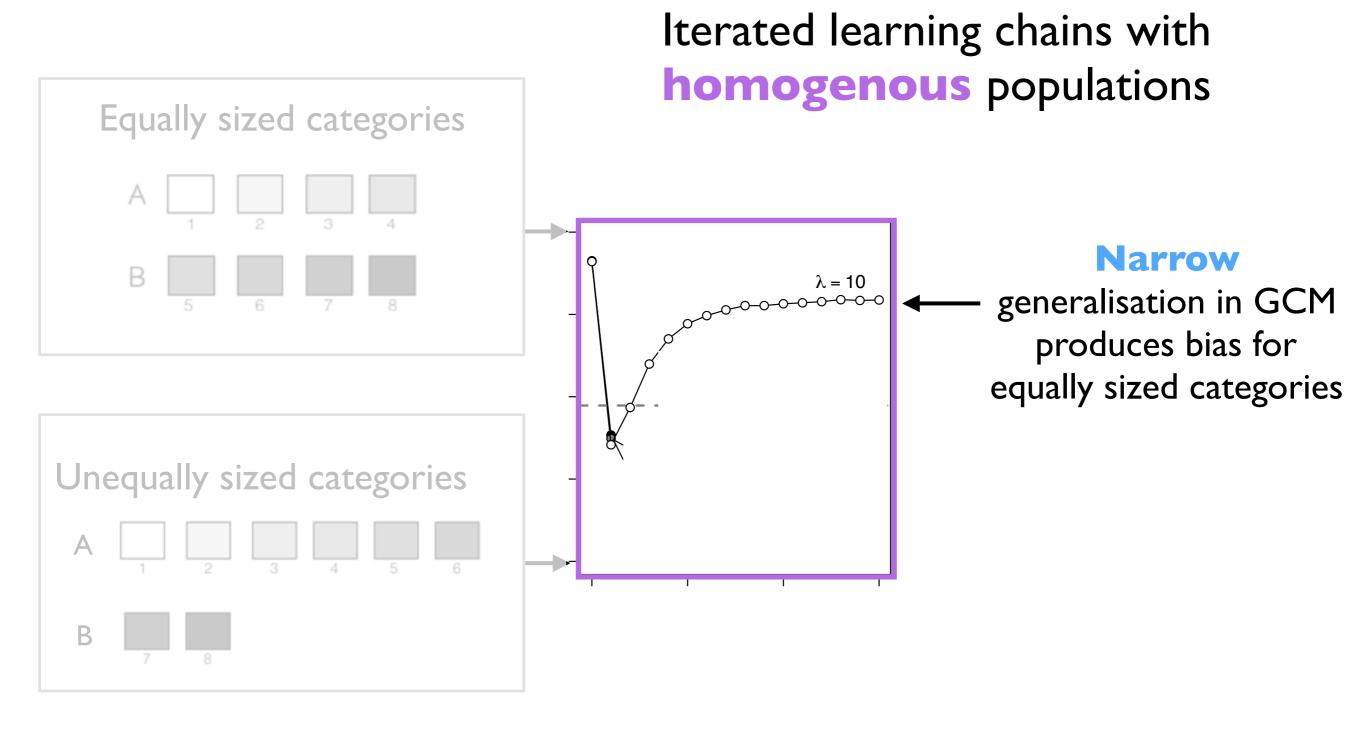
# Heterogeneity isn't much of a problem here

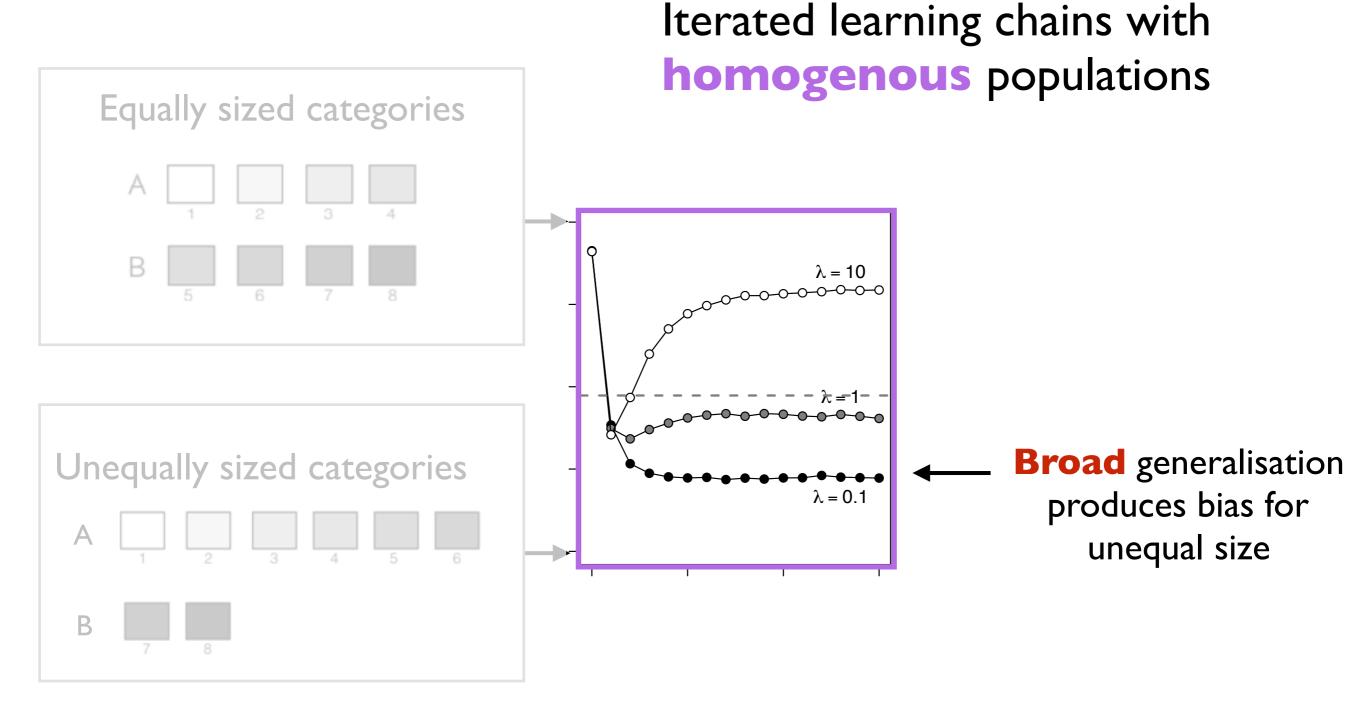




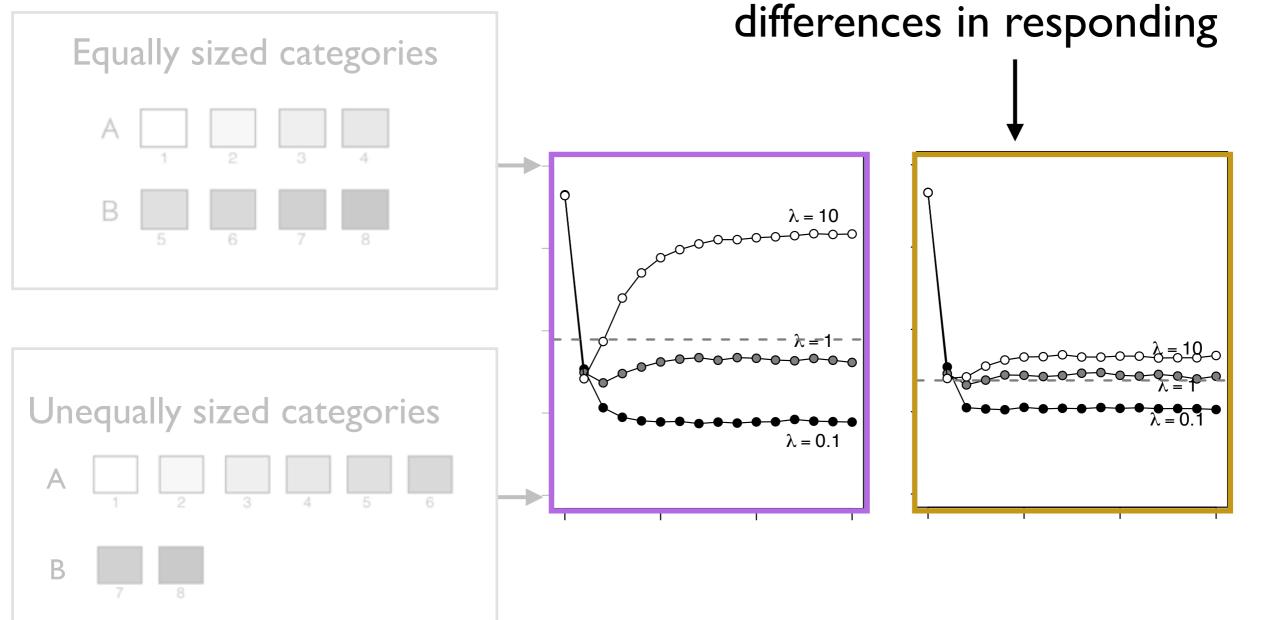


### Categorisation bias #2

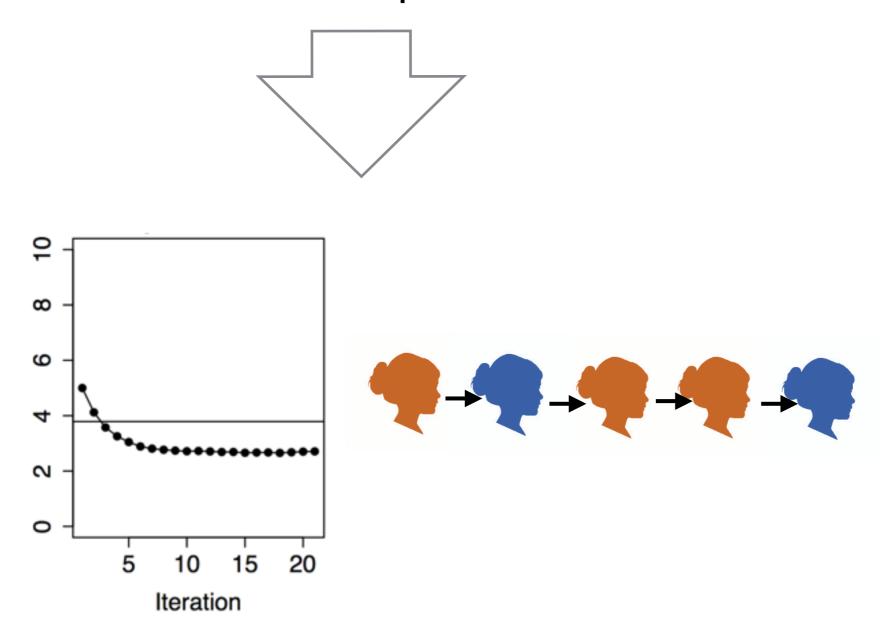




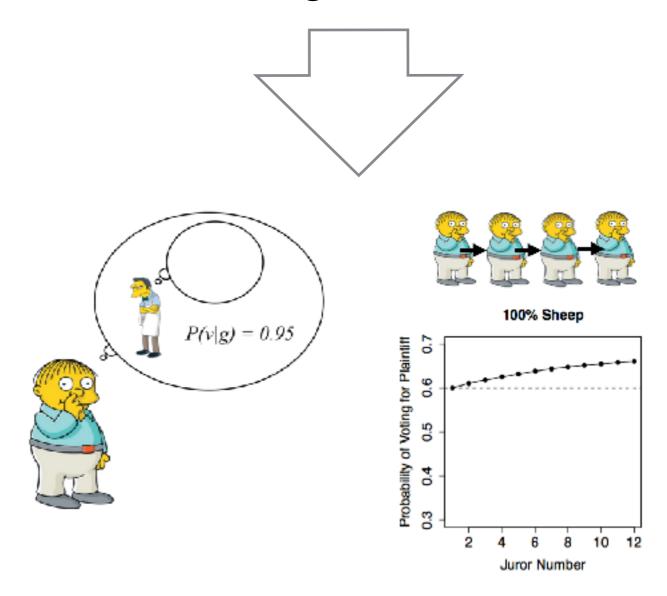
Heterogeneity in the population erases the individual differences in responding



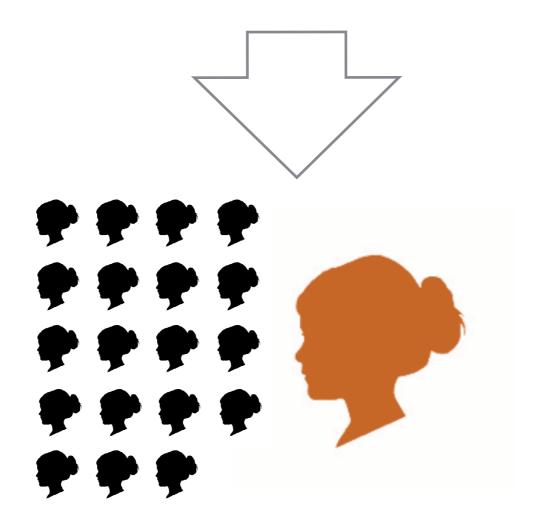
 Iterated learning distorts inductive bias when individual differences are present



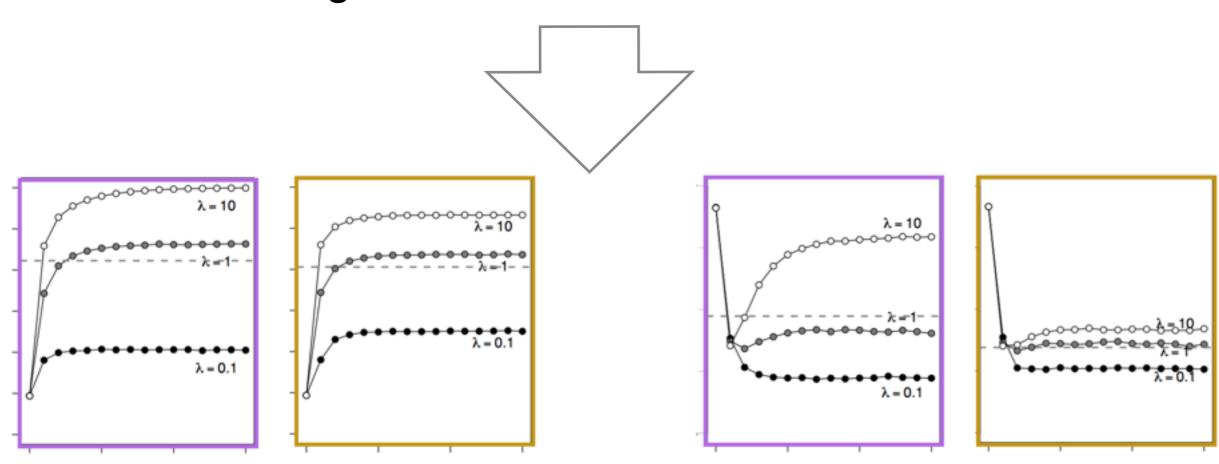
- Summary:
  - Iterated learning distorts inductive bias when individual differences are present
  - Miscalibrated agents can distort their own inductive biases even in homogenous chains



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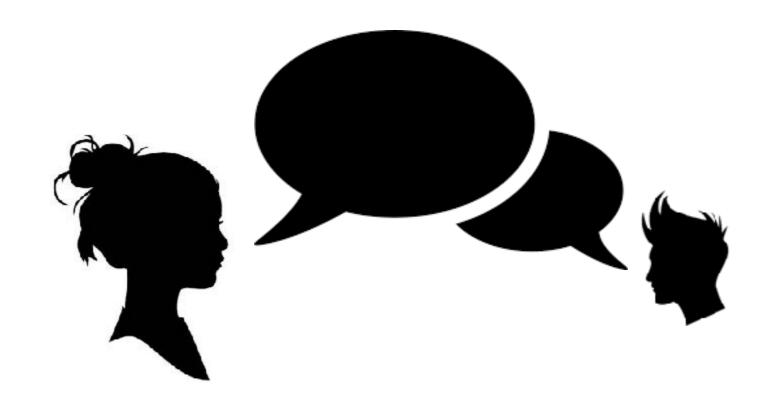


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#### • <u>Implications</u>:

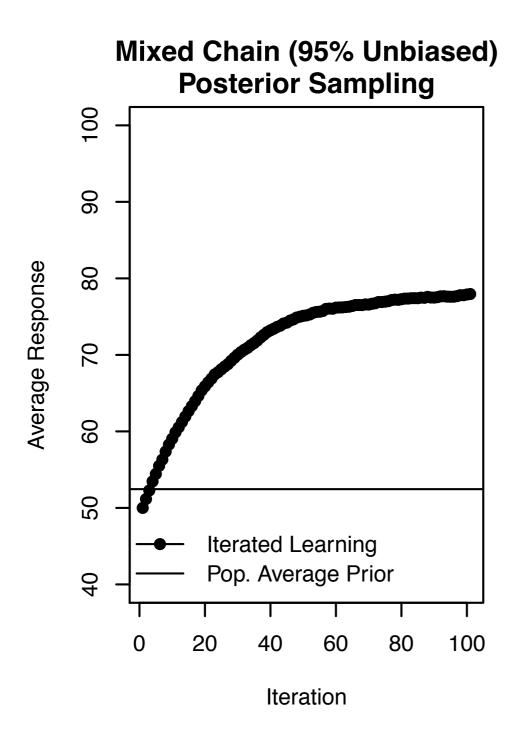
- IL has limits as a tool for "revealing priors"
- IL is useful for studying "distortions" in cultural and linguistic evolution

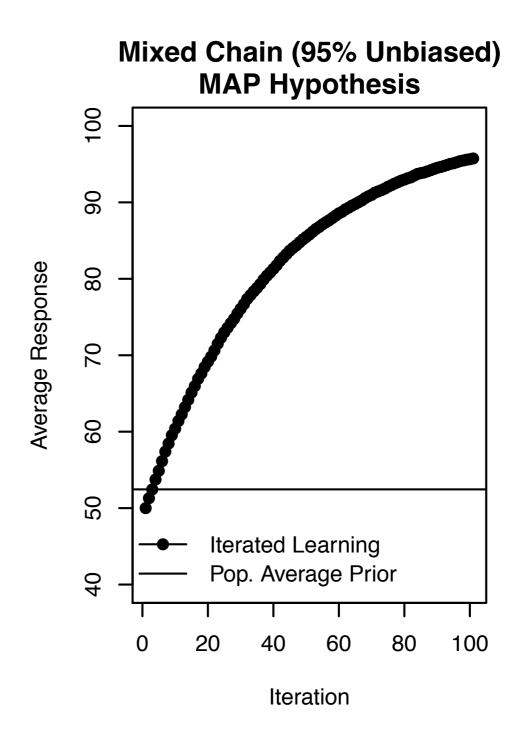
## Thanks!

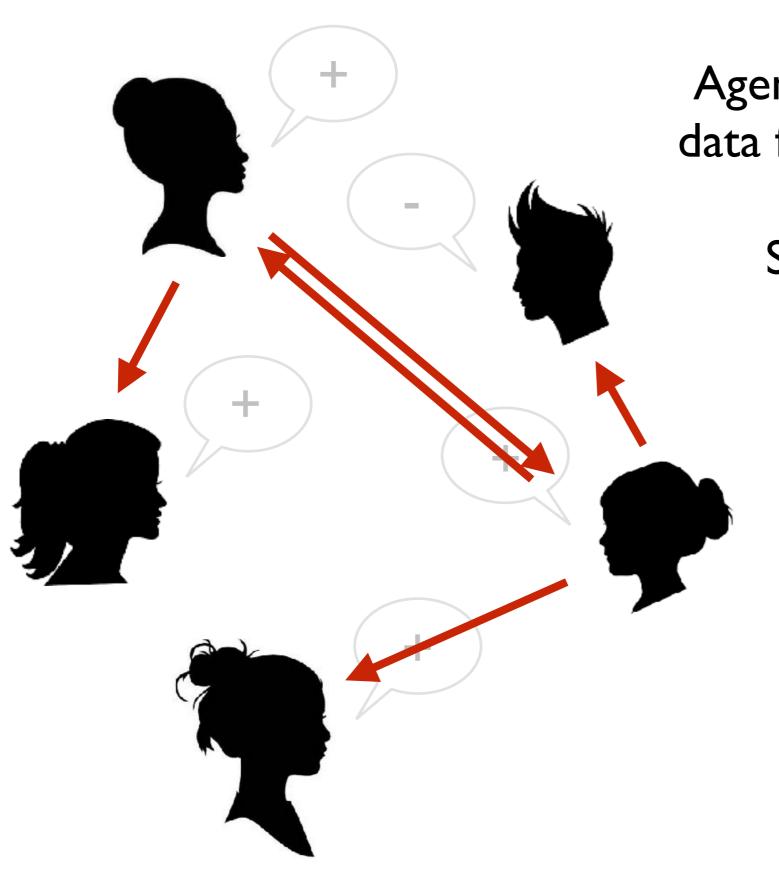




## The effect is exaggerated if learners maximise rather than sample

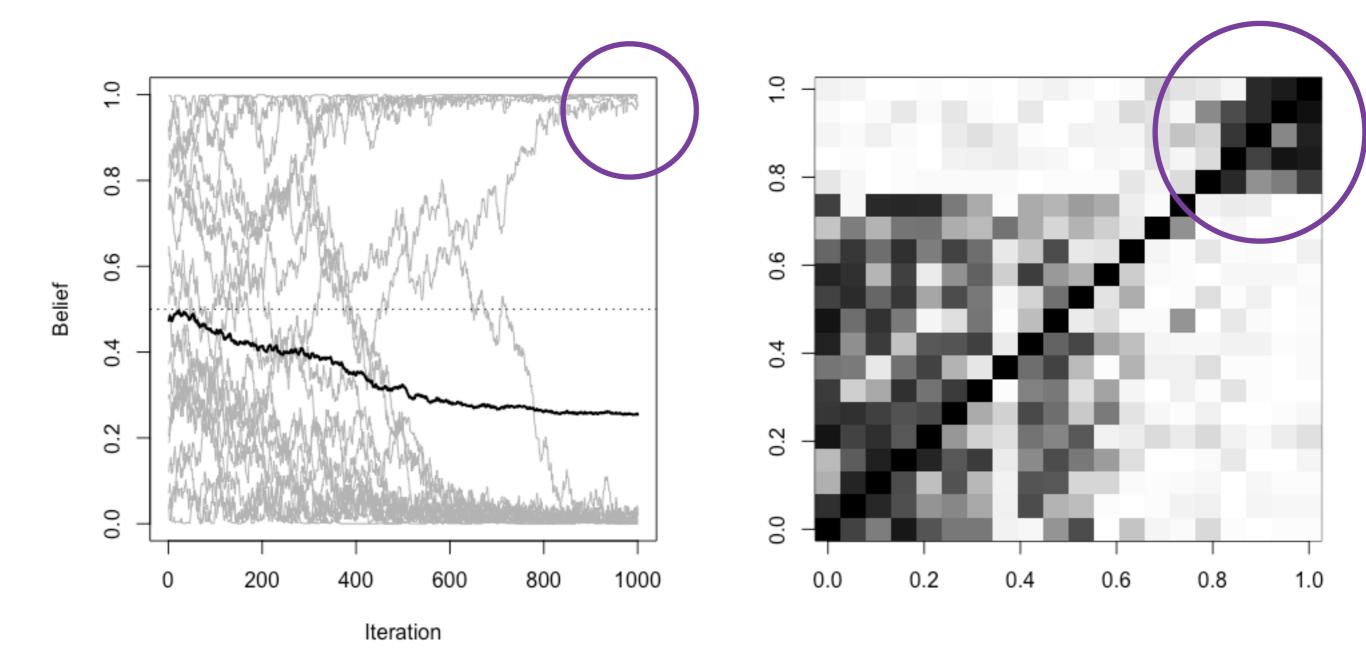


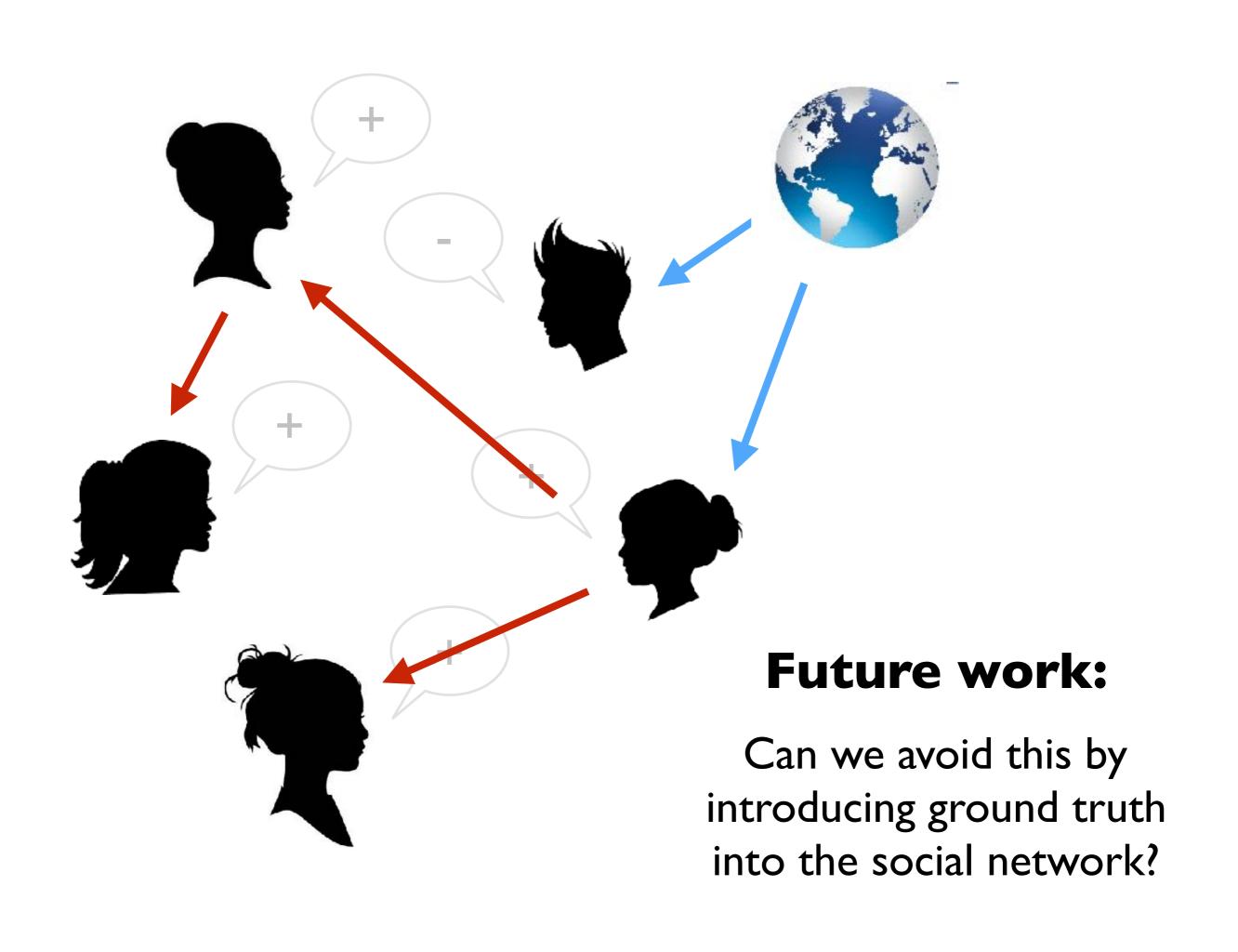


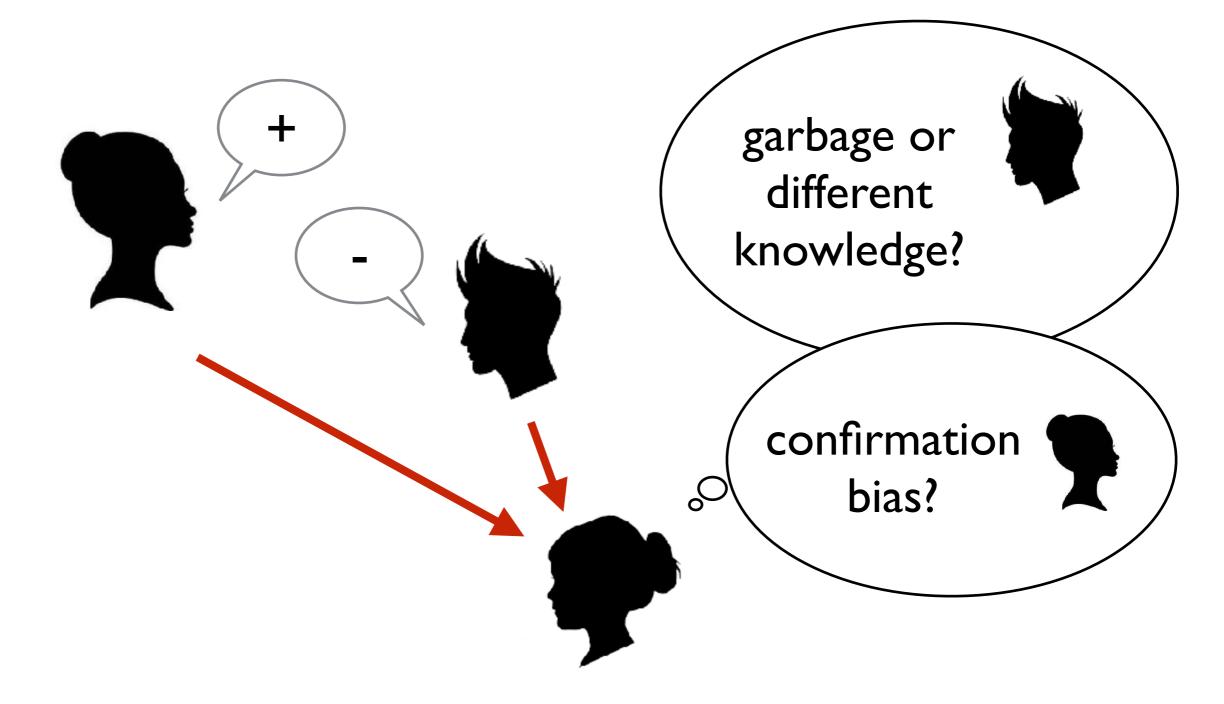


Agents prefer to receive data from trusted sources

Simple ToM to update trustworthiness







#### **Future work:**

Can we avoid this by giving our agents a more sophisticated ToM?