

# **When extremists win**

## **Iterated learning with heterogenous agents**

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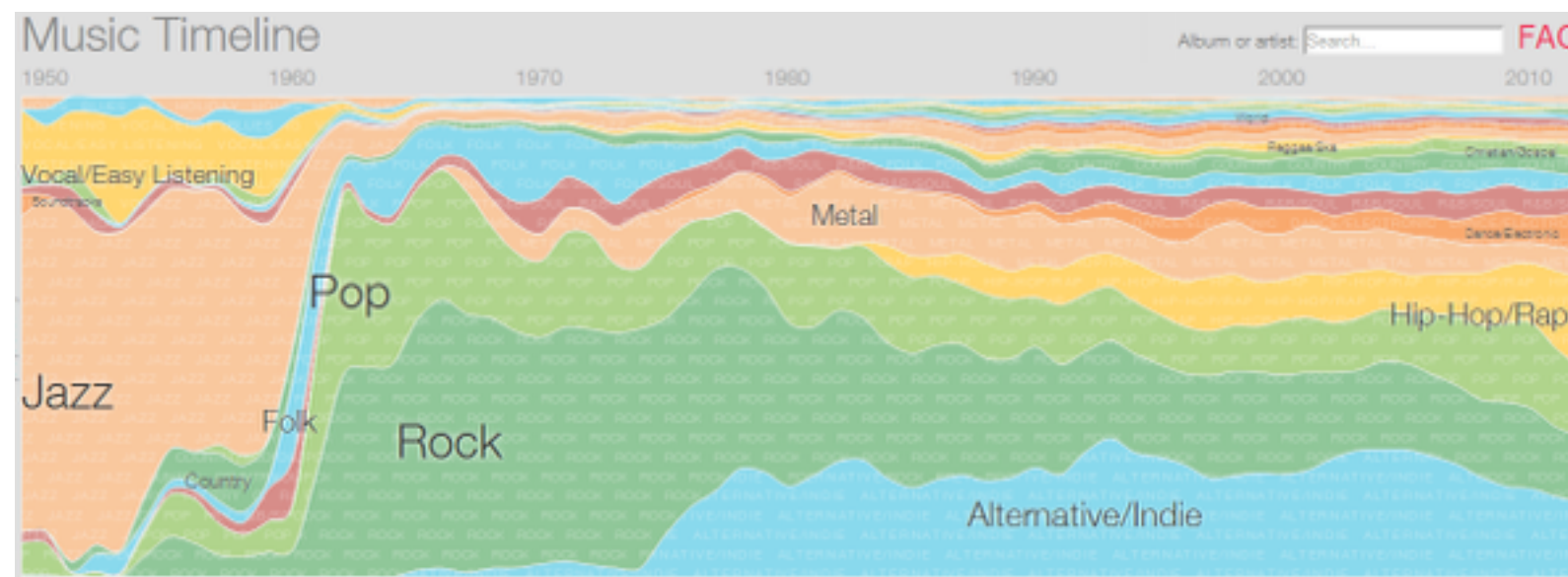
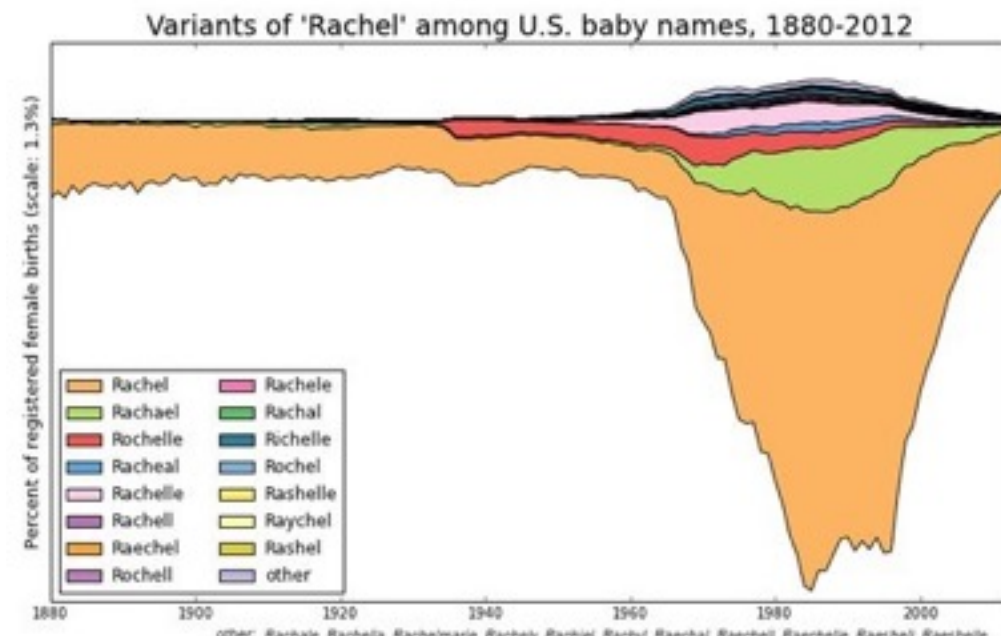
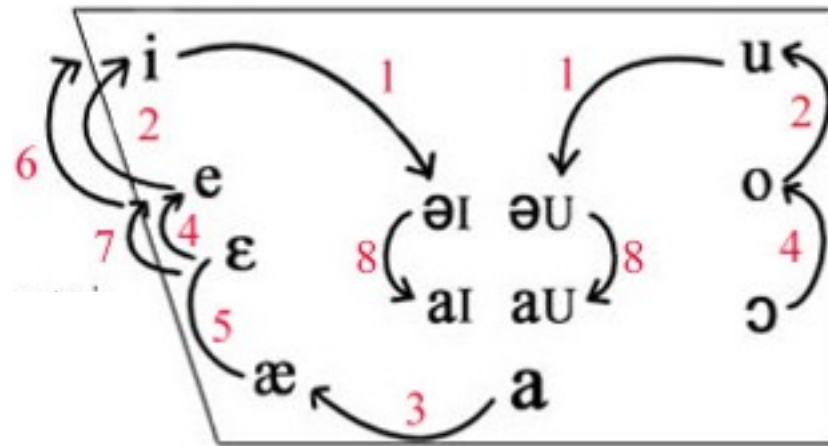
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University of New South Wales

**Scott Brown**  
School of Psychology  
University of Newcastle

**Chris Donkin**  
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University of New South Wales

# What dynamics underpin cultural and linguistic change? What do they say about the mind?







Original Drawing



Reproduction 1

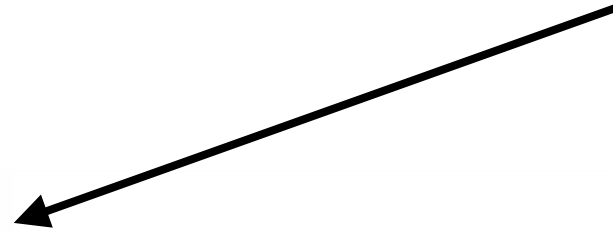
Reproduction 1



Reproduction 2



Reproduction 2



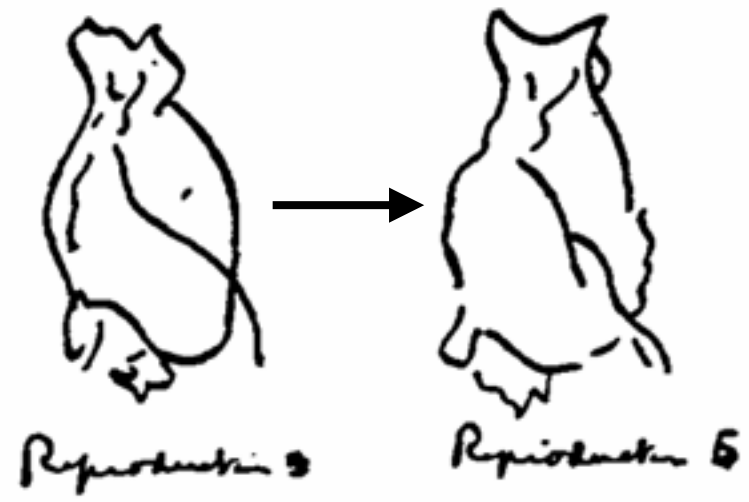
Reproduction 3



Reproduction 3



Reproduction 9







Reproduktor 5



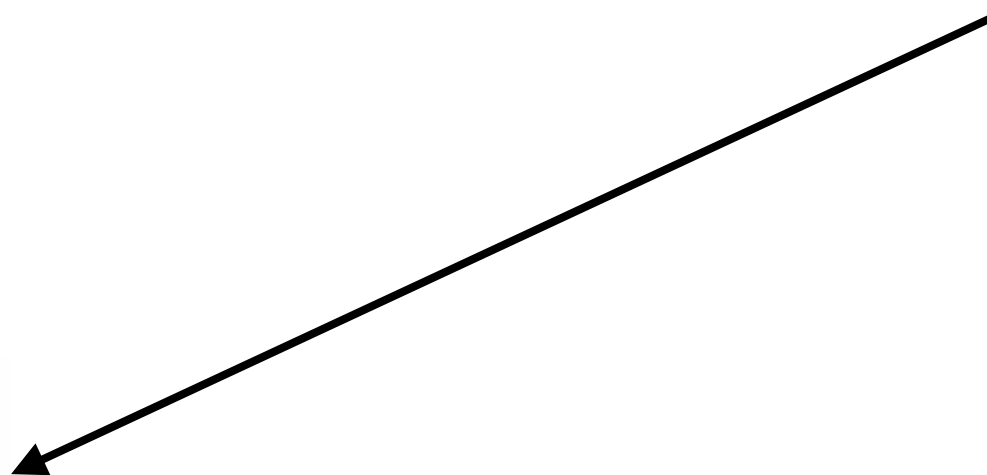
Reproduktor 6.

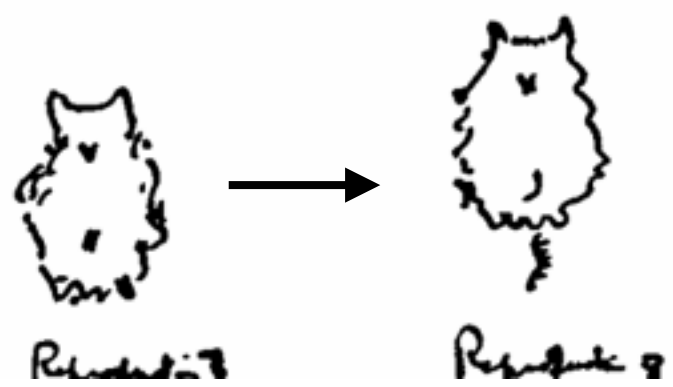


Representation 6.



Representation 7







Reproduction 2



Reproduction 2



Reproduction 9



Reproduction 10



Original Drawing

Reproduction 1



Reproduction 2



Reproduction 3



Reproduction 4



Reproduction 5



Reproduction 6



Reproduction 7



Reproduction 8



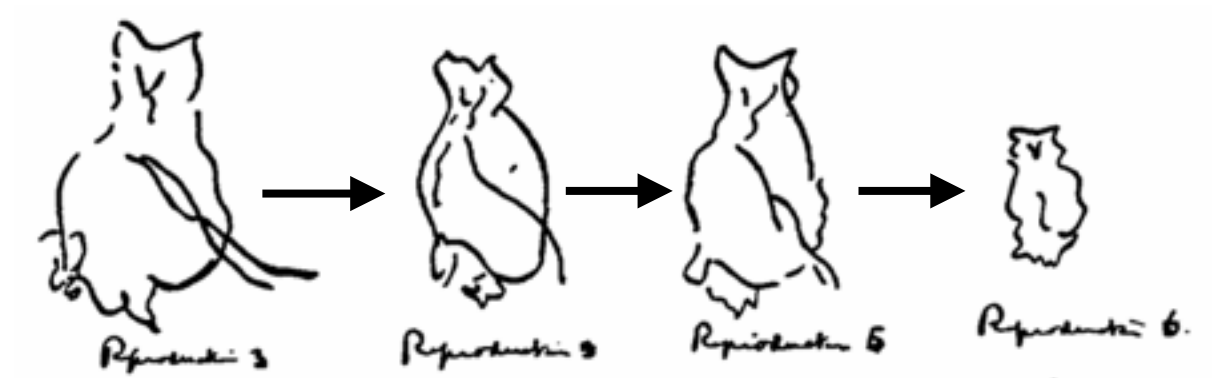
Reproduction 9



Reproduction 10

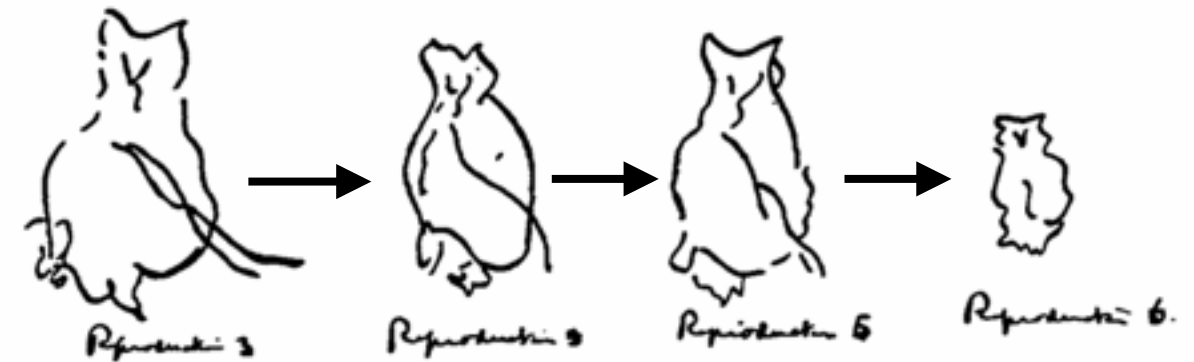
# The method of serial reproduction in memory

Bartlett (1920)



## The method of serial reproduction in memory

Bartlett (1920)



## Language as sequential reproduction of culture

Smith et al (2002)

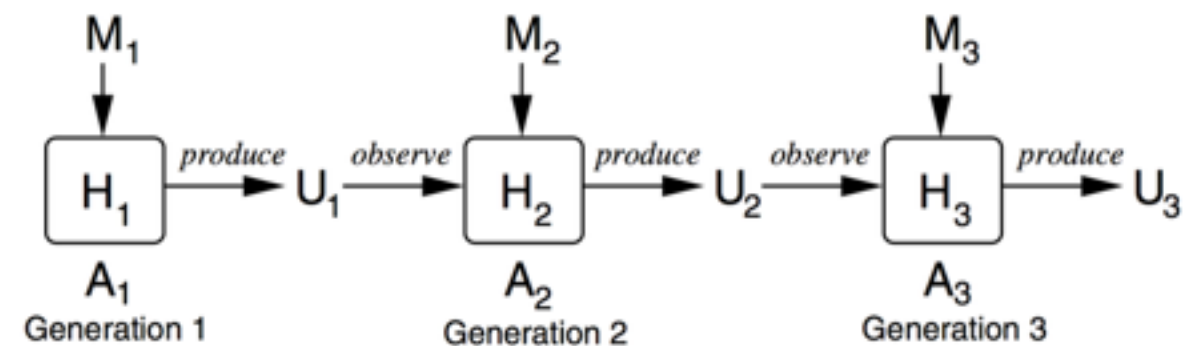
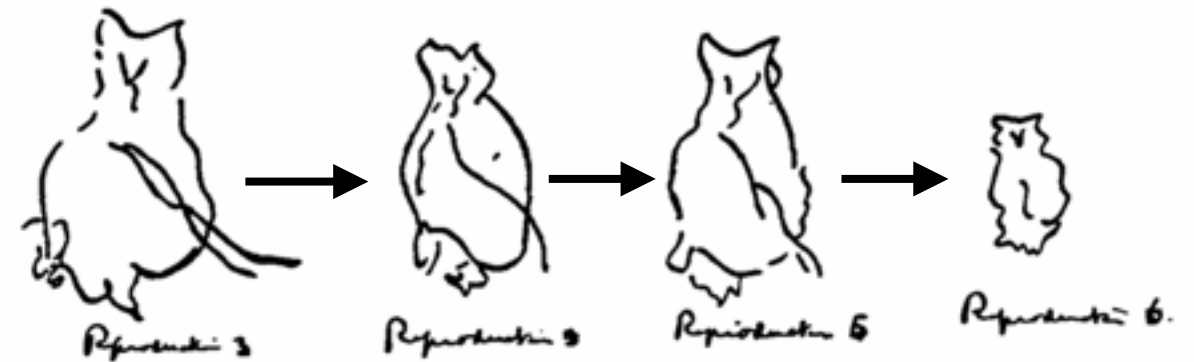


Figure 2. The iterated learning model. The  $i$ th generation of the population consists of a single agent  $A_i$  who has hypothesis  $H_i$ . Agent  $A_i$  is prompted with a set of meanings  $M_i$ . For each of these meanings the agent produces an utterance using  $H_i$ . This yields a set of utterances  $U_i$ . Agent  $A_{i+1}$  observes  $U_i$  and forms a hypothesis  $H_{i+1}$  to explain the set of observed utterances. This process of observation and hypothesis formation constitutes learning.



## The method of serial reproduction in memory

Bartlett (1920)



## Language as sequential reproduction of culture

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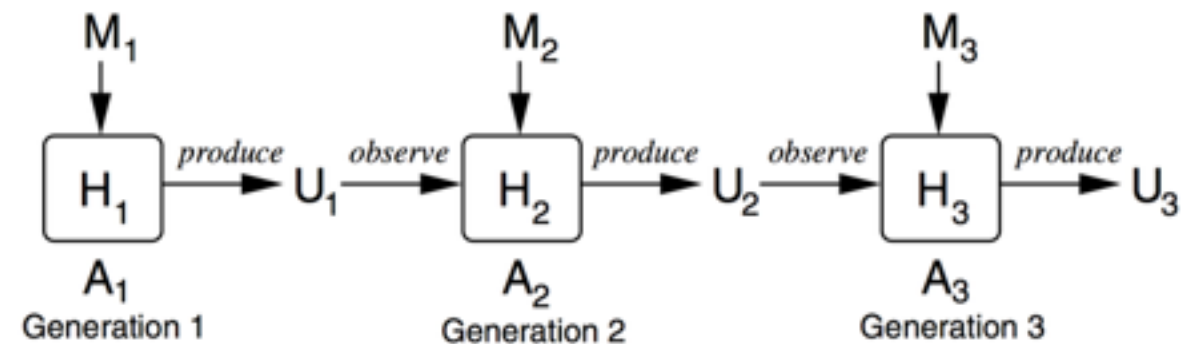
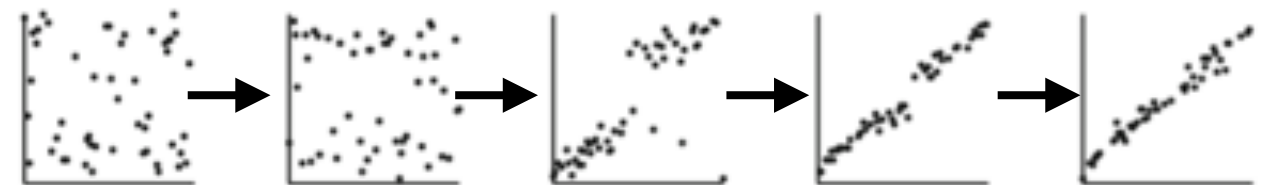


Figure 2. The iterated learning model. The  $i$ th generation of the population consists of a single agent  $A_i$  who has hypothesis  $H_i$ . Agent  $A_i$  is prompted with a set of meanings  $M_i$ . For each of these meanings the agent produces an utterance using  $H_i$ . This yields a set of utterances  $U_i$ . Agent  $A_{i+1}$  observes  $U_i$  and forms a hypothesis  $H_{i+1}$  to explain the set of observed utterances. This process of observation and hypothesis formation constitutes learning.

## The method of iterated learning reveals inductive bias

Kalish et al (2007)



# Example: function learning

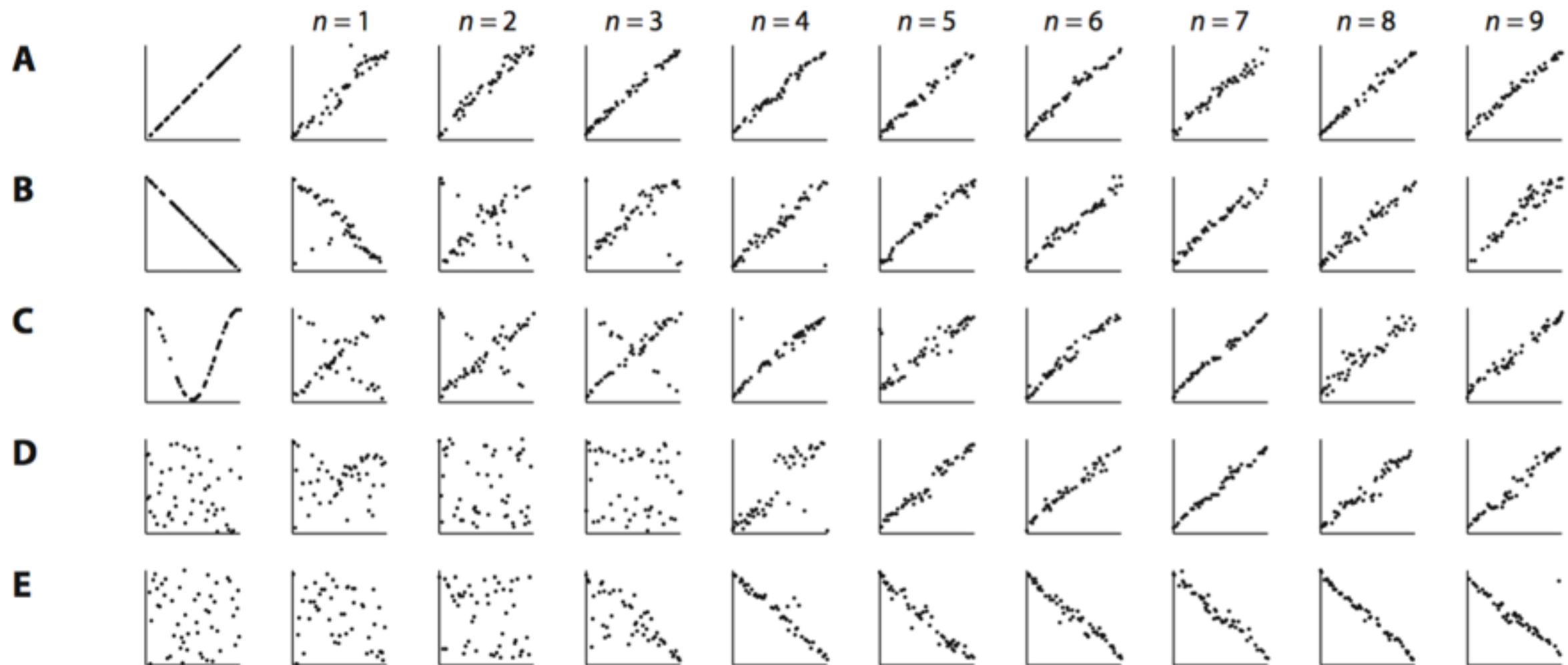
(Kalish et al 2007)



original

# Example: function learning

(Kalish et al 2007)



original

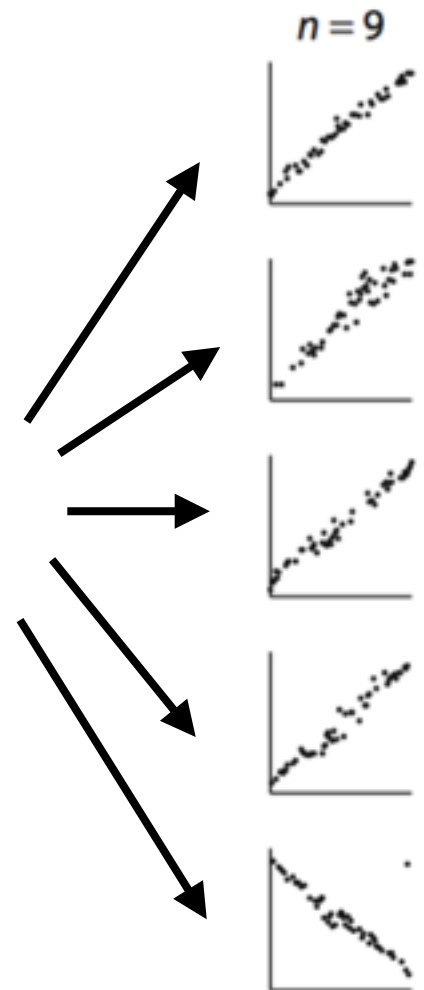


final

# Example: function learning

(Kalish et al 2007)

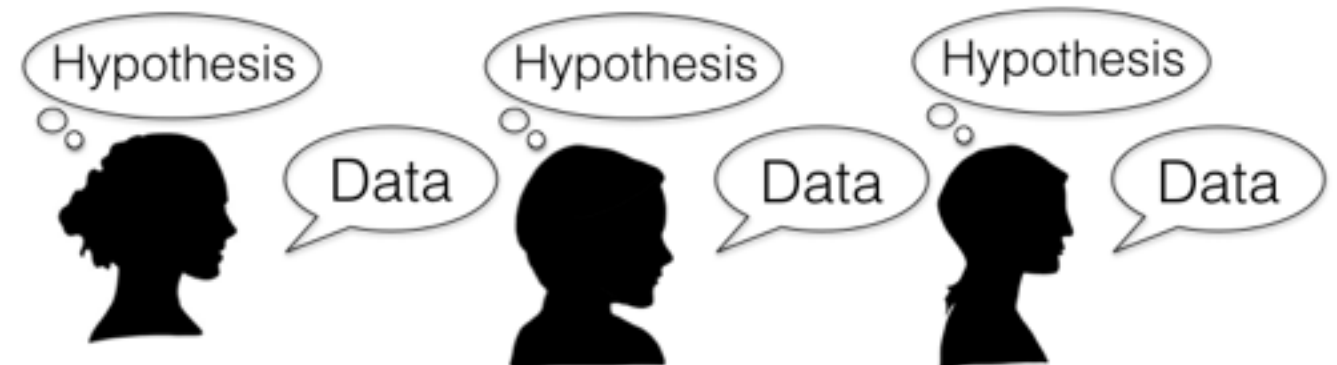
Conclusion: we have an inductive bias for linear functions



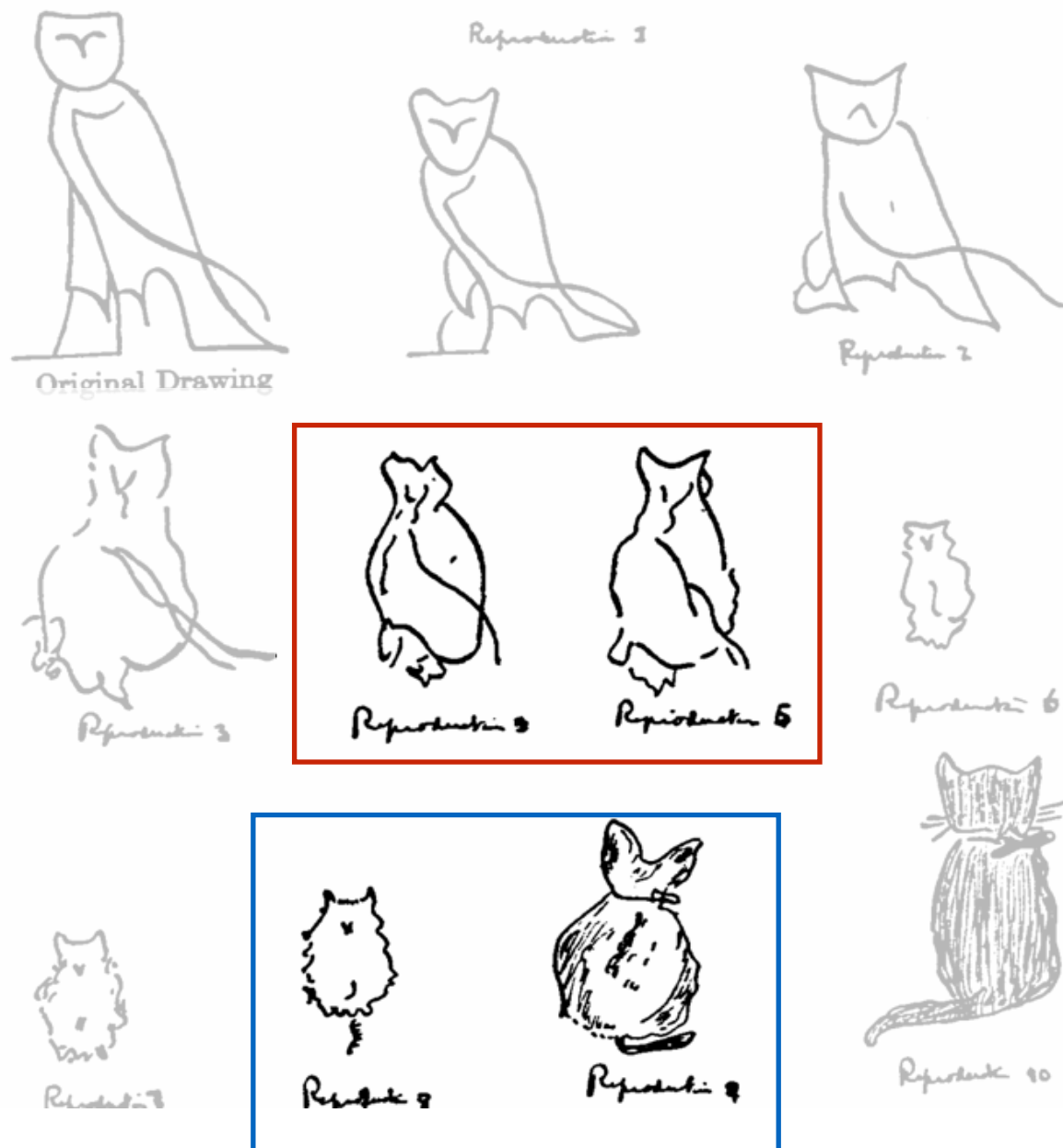
# Proof that iterated learning with Bayesian agents reveals the prior

$$\begin{aligned} P(h_n = i) &= \sum_j P_{\text{samp}, P_A}(h_n = i \mid h_{n-1} = j) P(h_{n-1} = j) \\ &= \sum_j \sum_{d \in \mathcal{D}} P_{\text{samp}}(h_n = i \mid d) P_{P_A}(d \mid h_{n-1} = j) P(h_{n-1} = j) \\ &= \sum_{d \in \mathcal{D}} P_{\text{samp}}(h_n = i \mid d) \sum_j P_{P_A}(d \mid h_{n-1} = j) P(h_{n-1} = j) \\ &= \sum_{d \in \mathcal{D}} P_{\text{samp}}(h_n = i \mid d) P_{P_A}(d) \\ &= \sum_{d \in \mathcal{D}} \frac{P_{P_A}(d \mid h_n = i) P(h_n = i)}{P_{P_A}(d)} P_{P_A}(d) \\ &= P(h_n = i) \sum_{d \in \mathcal{D}} P_{P_A}(d \mid h_n = i), \end{aligned}$$

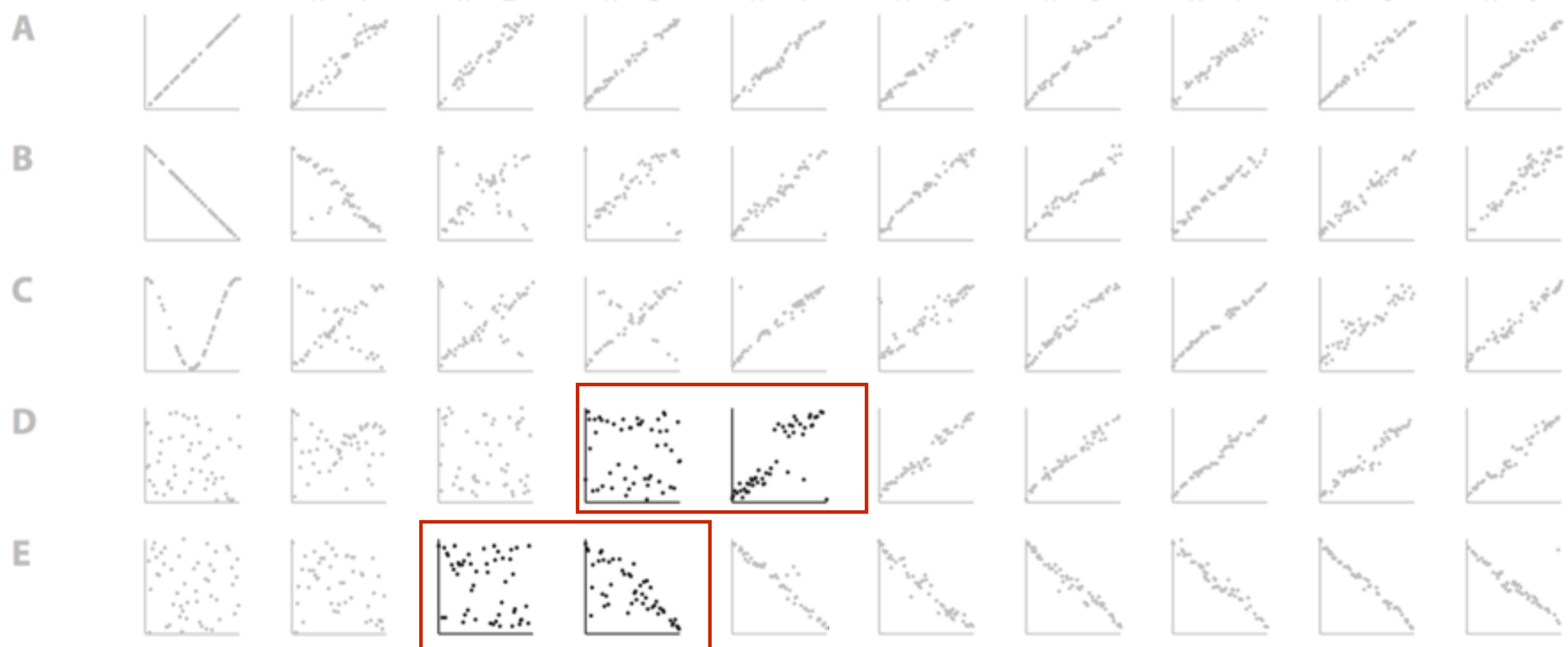
(Griffiths & Kalish 2007)



... as long as everyone has the same prior



Hm.



Hm.

So how do iterated learning chains  
behave when individual differences exist?

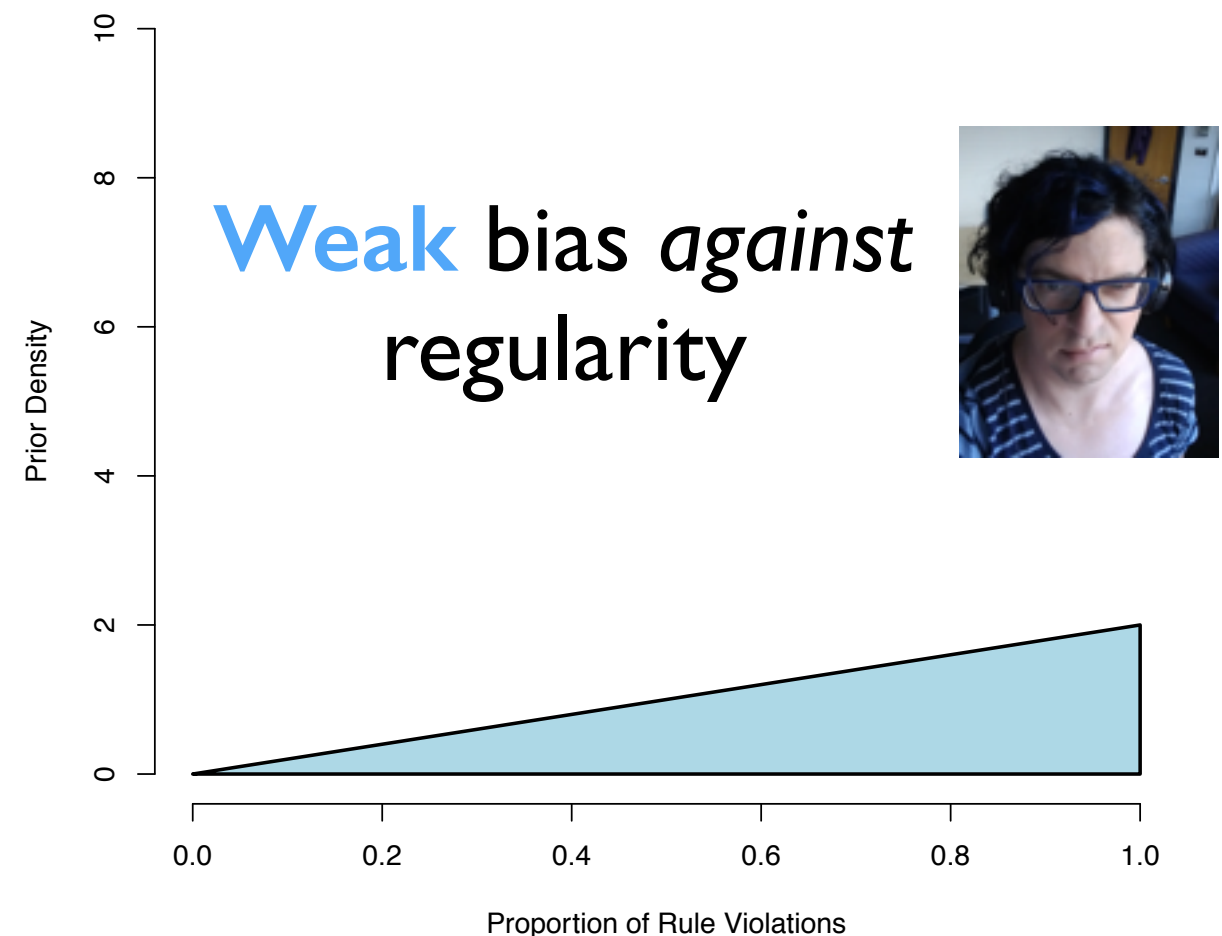
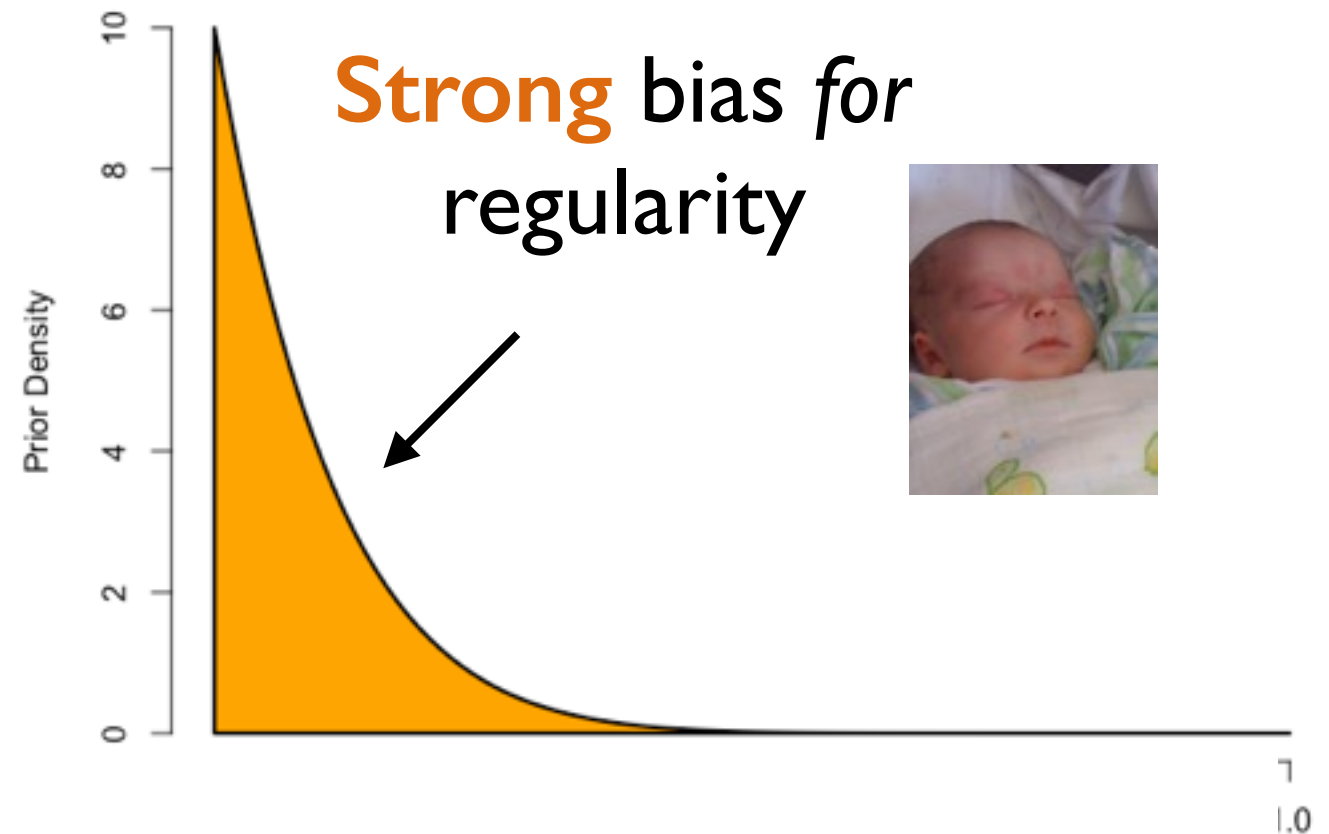


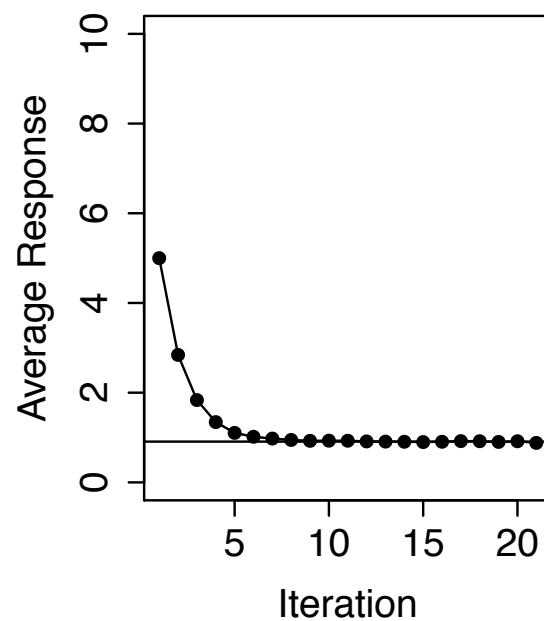
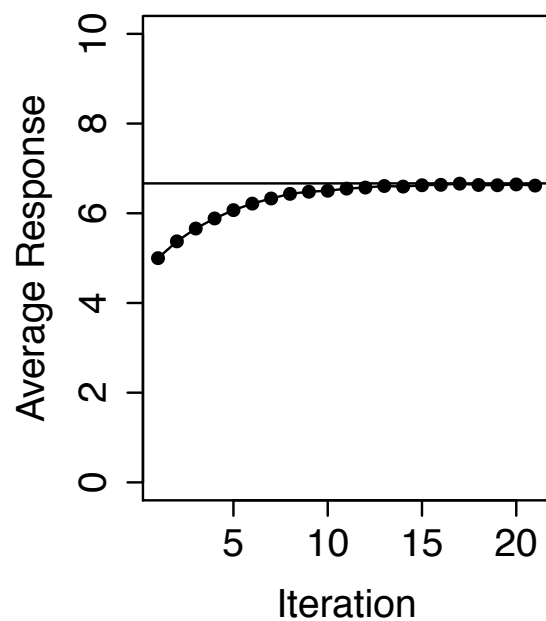


## Case study 1:

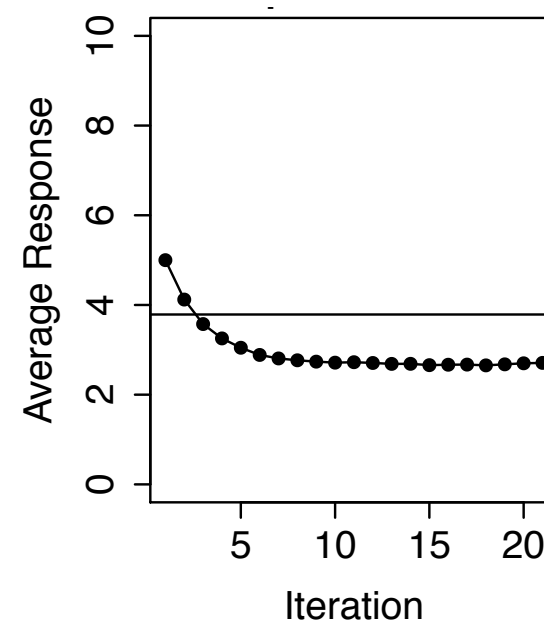
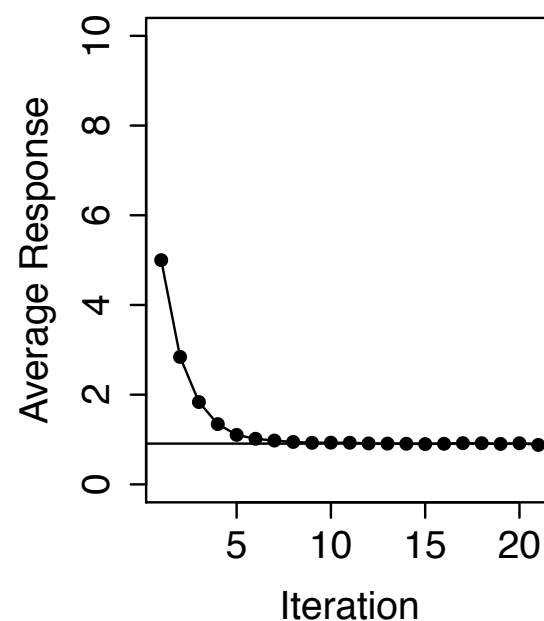
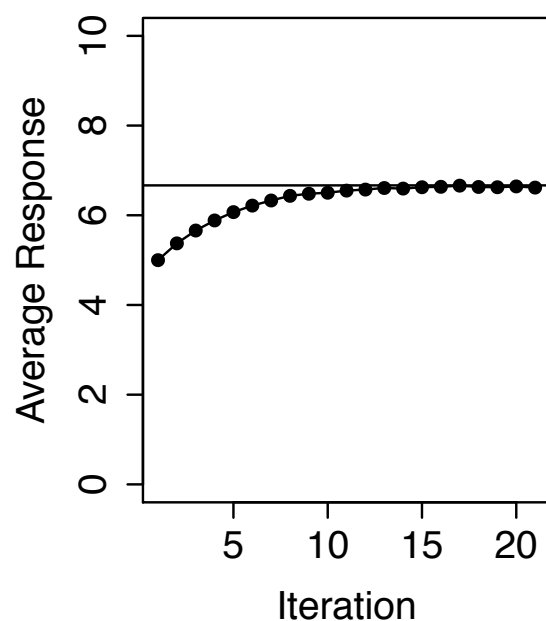
Does everybody contribute equally  
to the evolution of languages?

# Bayesian models for language regularisation with two different kinds of bias

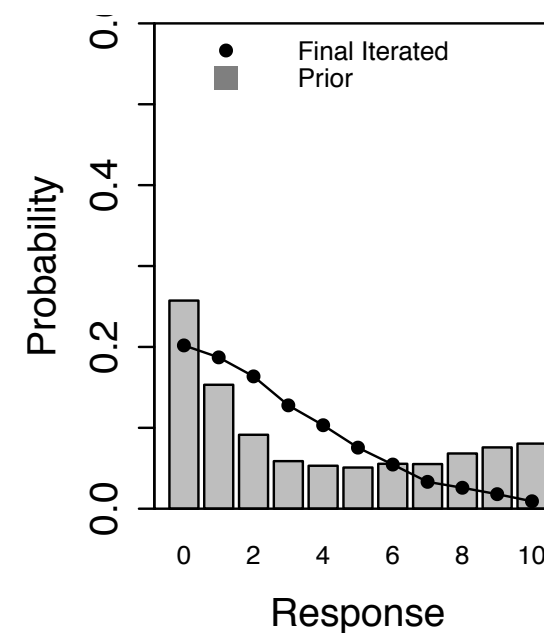
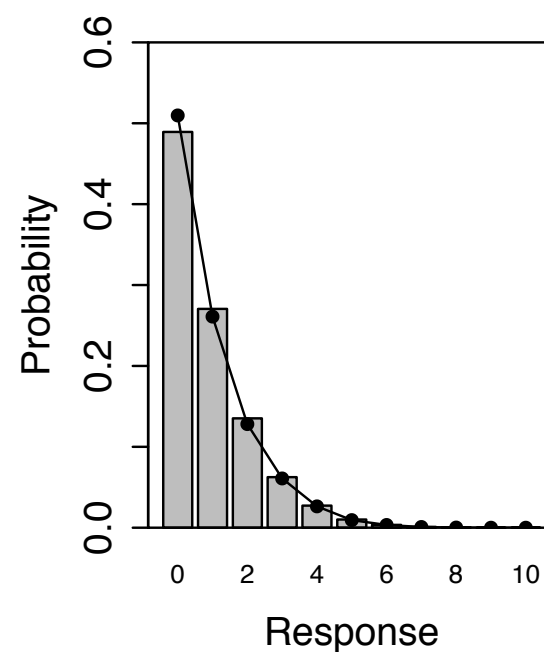
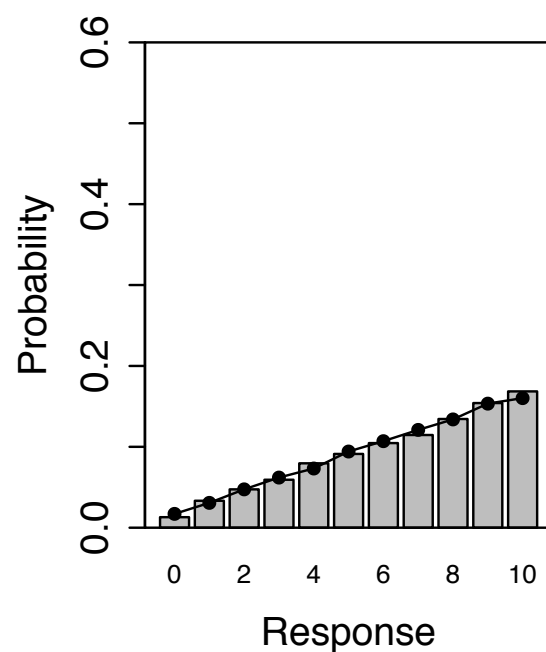




Homogenous  
iterated learning  
chains converge to  
the prior

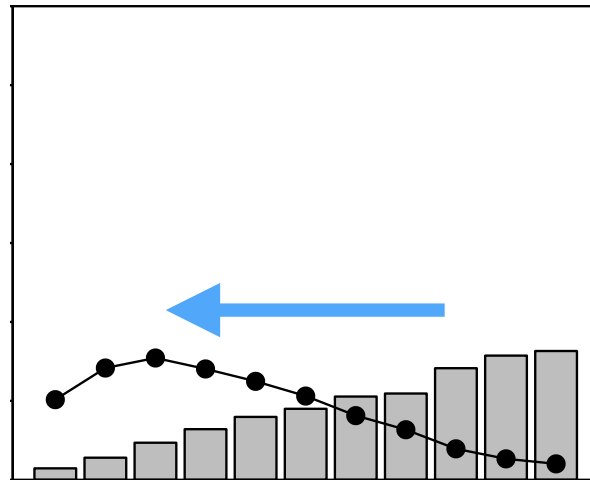


A heterogenous chain does not converge to the average of the prior biases

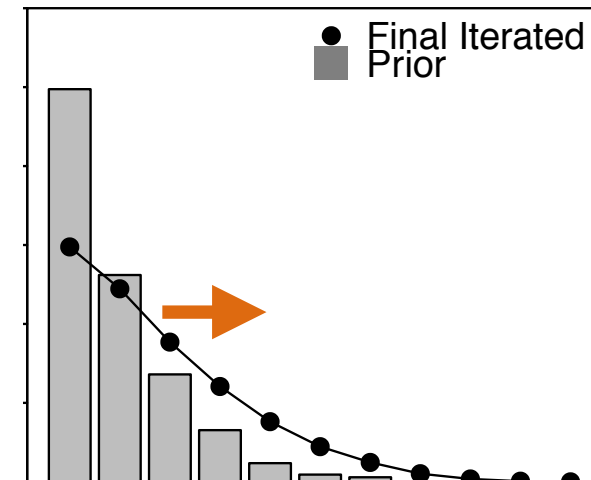


...and the distribution of responses is severely distorted

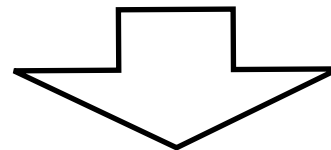
weak bias



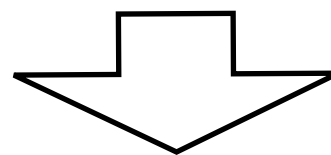
strong bias



strong bias



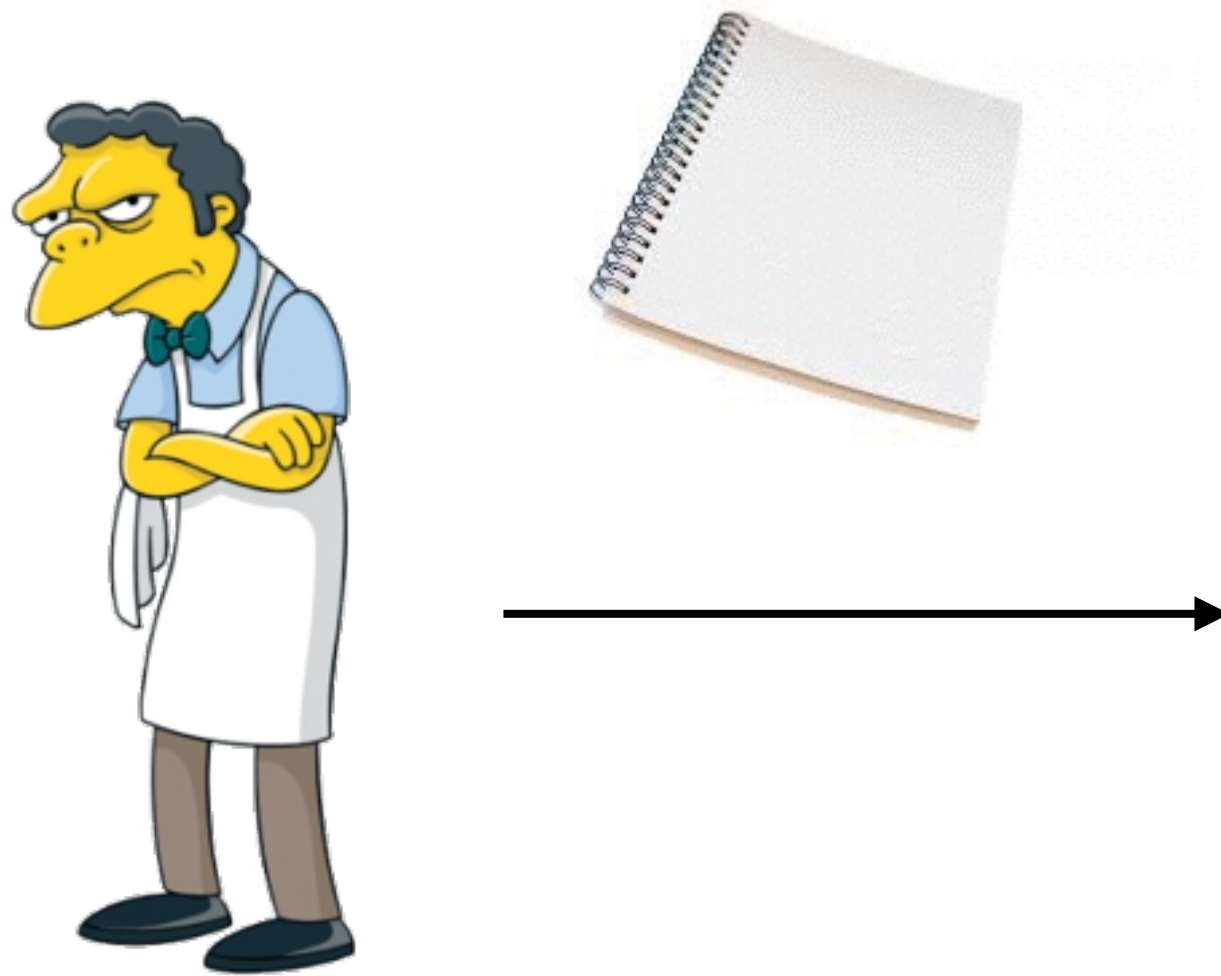
insensitivity to input



greater influence on the chain

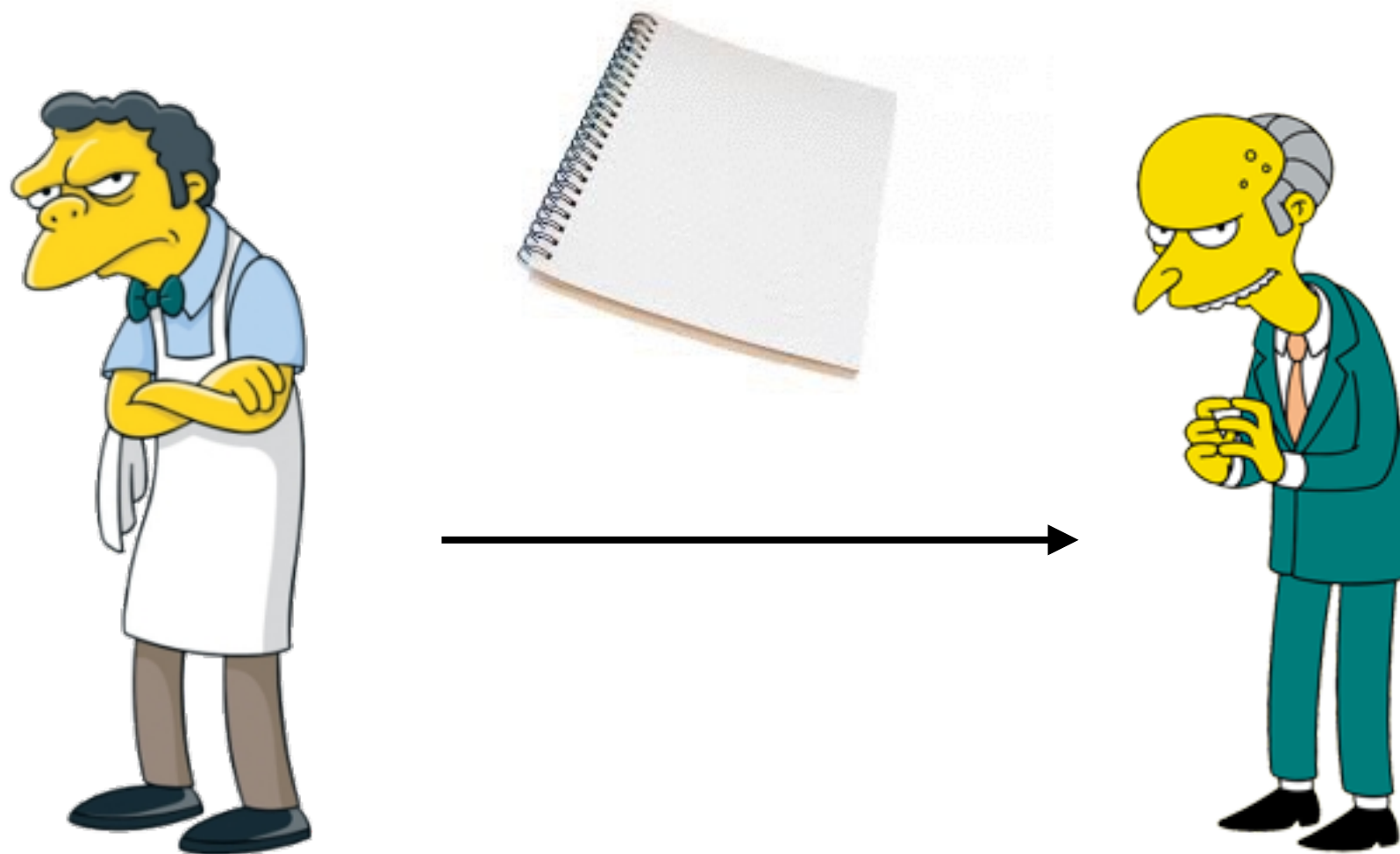
# Case study 2: Bayesian groupthink





Juror  $i$  records vote,  
removes sheet, passes  
notebook





Juror  $i$  records vote,  
removes sheet, passes  
notebook

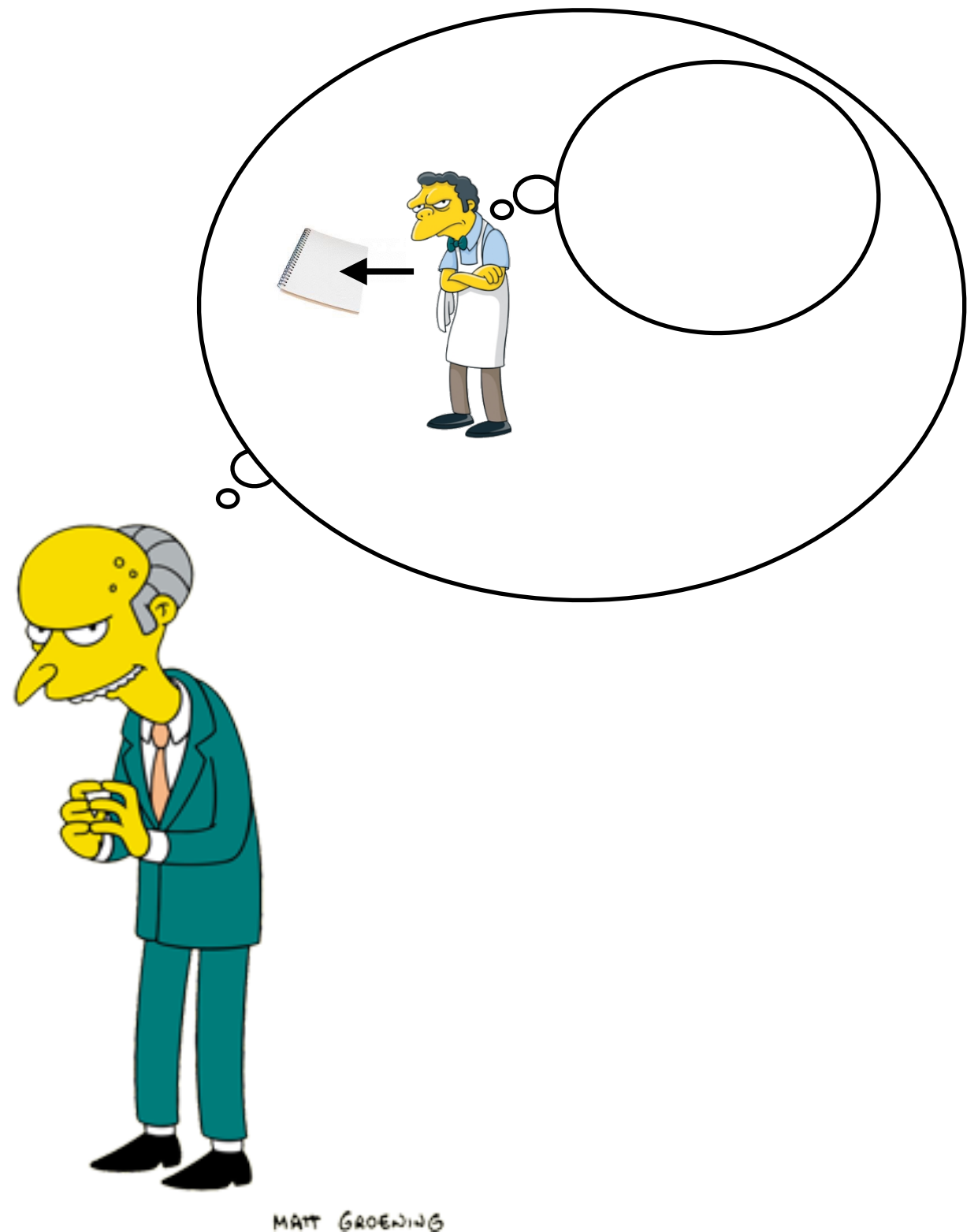
Juror  $i+1$  can see the  
previous vote via  
indentations...

Prior belief about guilt  
 $P(g)$  is set by the trial

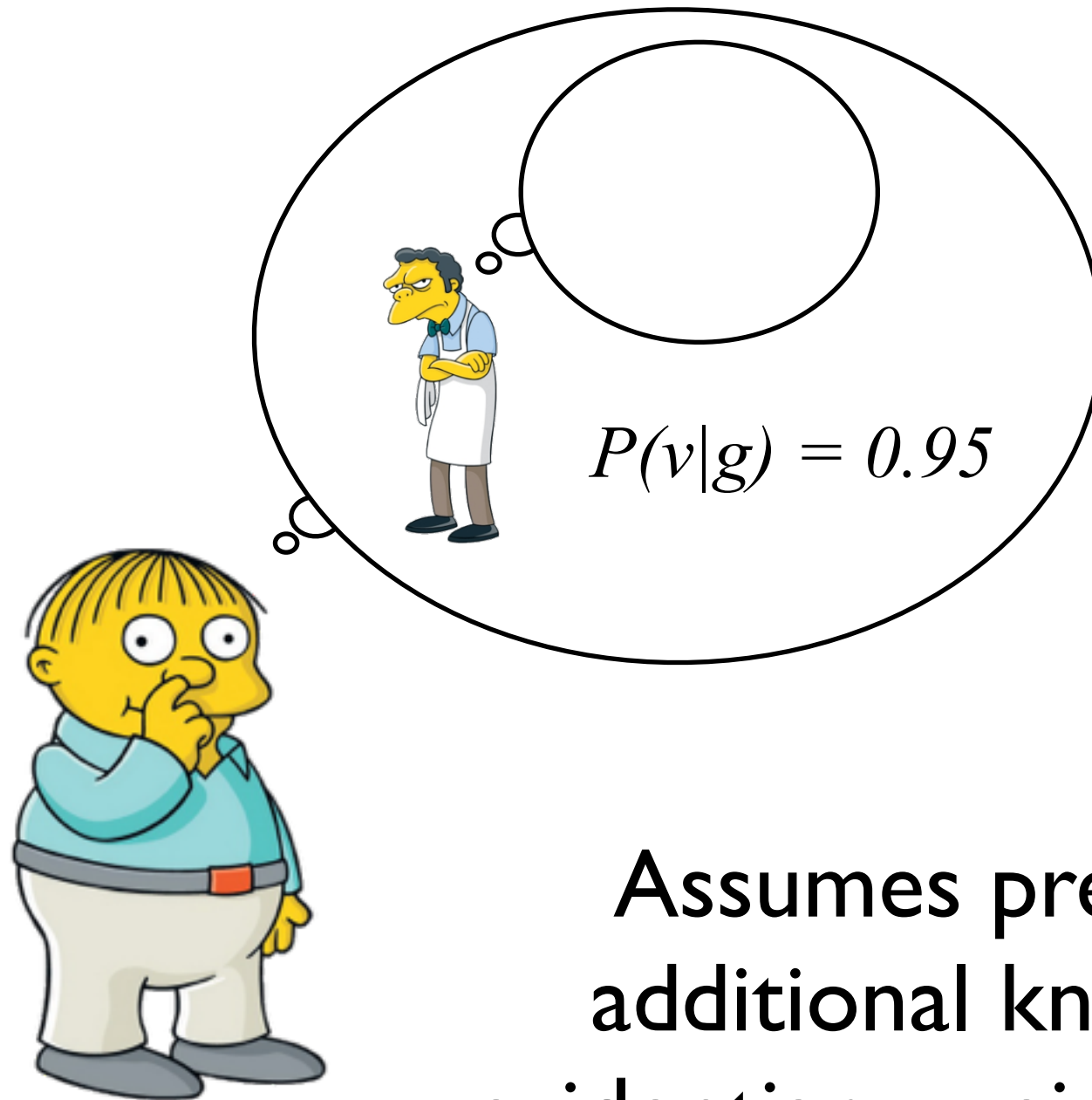


MATT GROENING

Likelihood of previous juror's  
vote  $P(v|g)$  requires *theory of  
mind*... what do they know  
that I don't know?

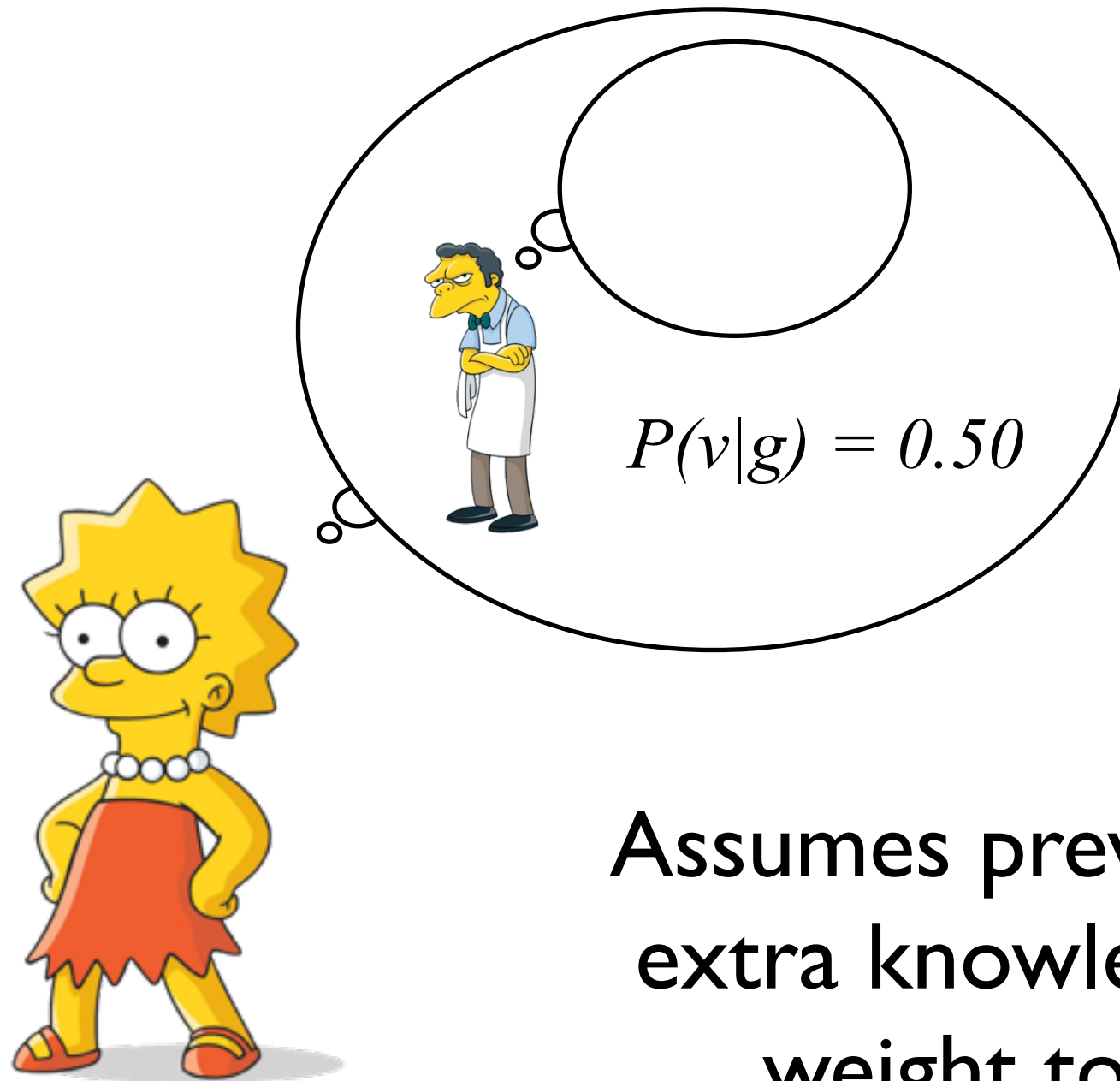


# Bayesian “sheep”

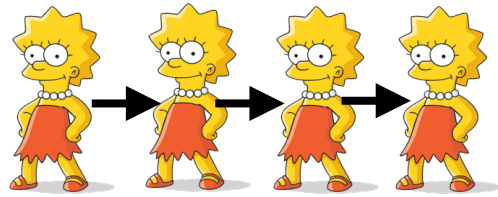


Assumes previous juror has additional knowledge, assigns evidentiary weight to their opinion

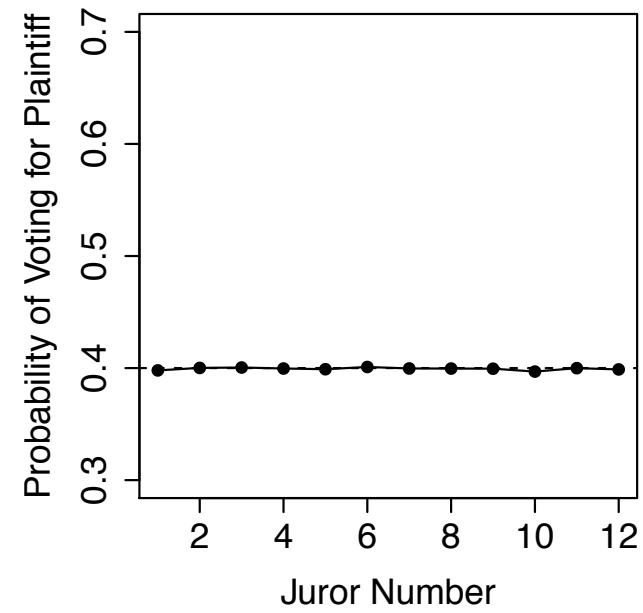
# Bayesian “goat”



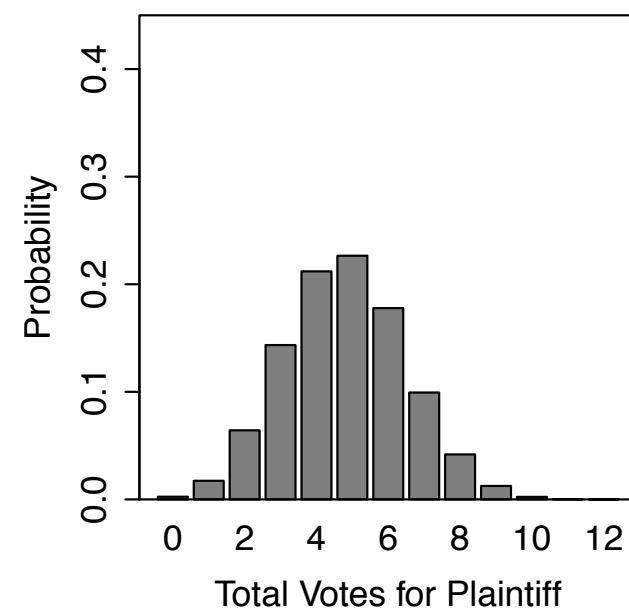
Assumes previous juror has no extra knowledge, assigns zero weight to their opinion



100% Goats

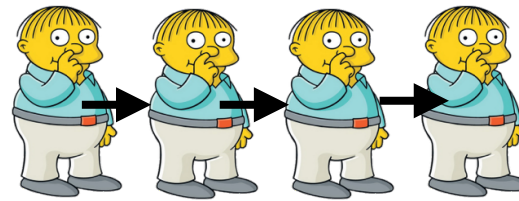


100% Goats

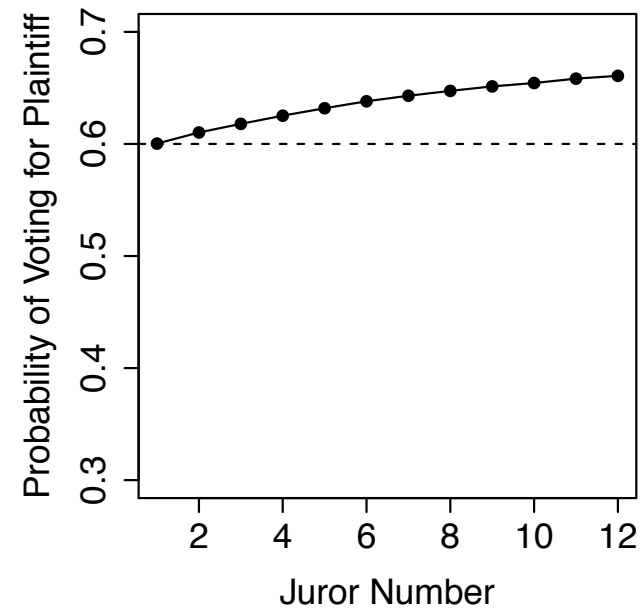


A jury of goats ignores one another and the “chain” converges just fine

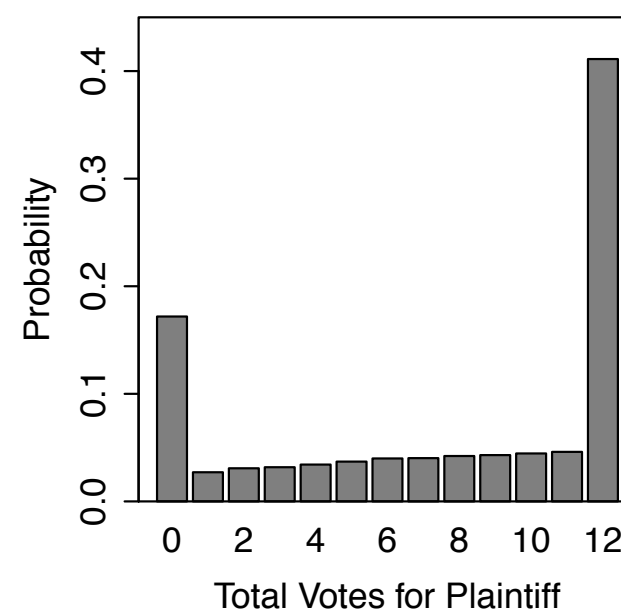




100% Sheep

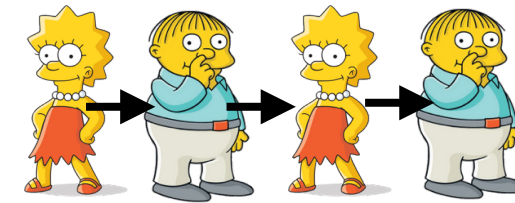


100% Sheep

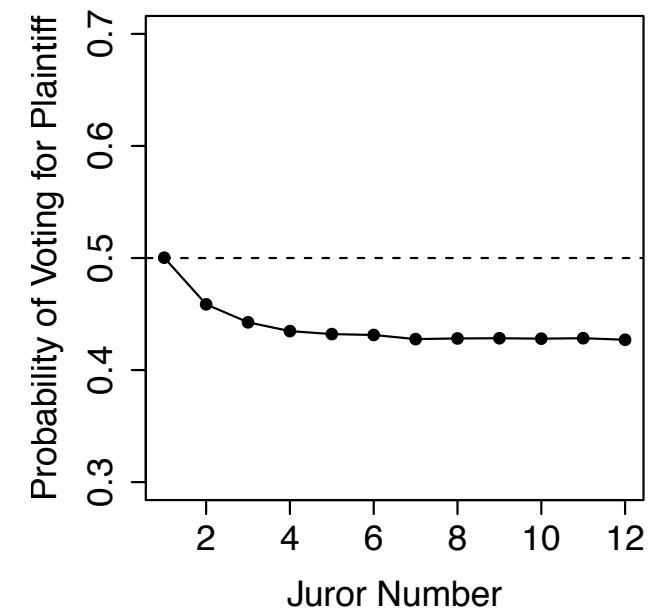


A jury of sheep  
displays groupthink

$$\begin{aligned}
 \pi T &\propto [d, p] \begin{bmatrix} 1-p & p \\ d & 1-d \end{bmatrix} \\
 &= [d(1-p) + pd, dp + p(1-d)] \\
 &= [d, p] \propto \pi
 \end{aligned}$$

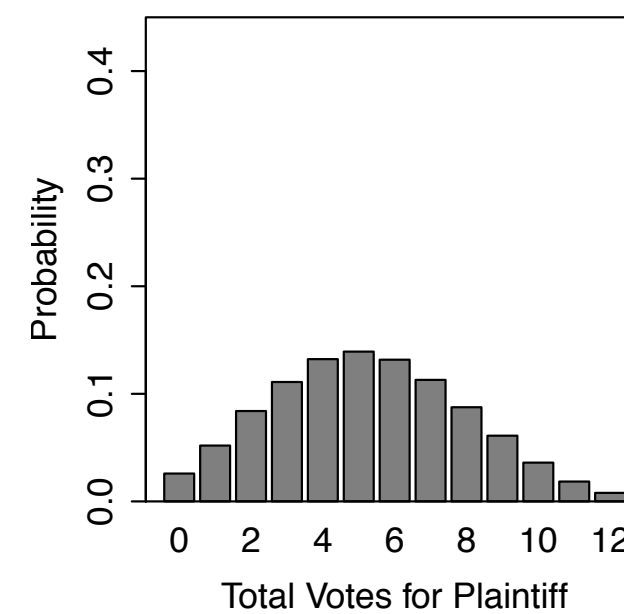


50% Sheep, 50% Goat



A mixed jury is  
dominated by goats

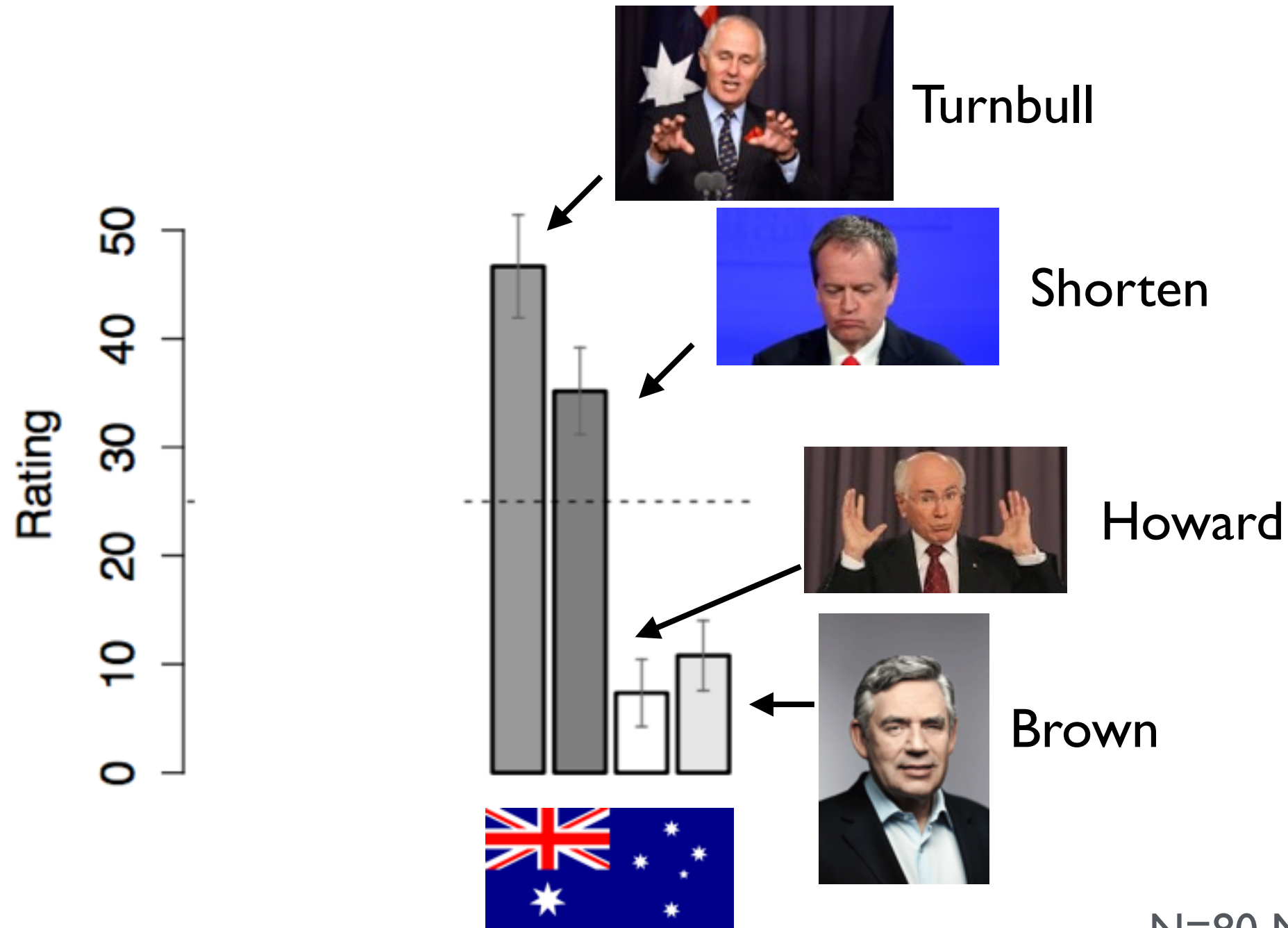
50% Sheep, 50% Goat



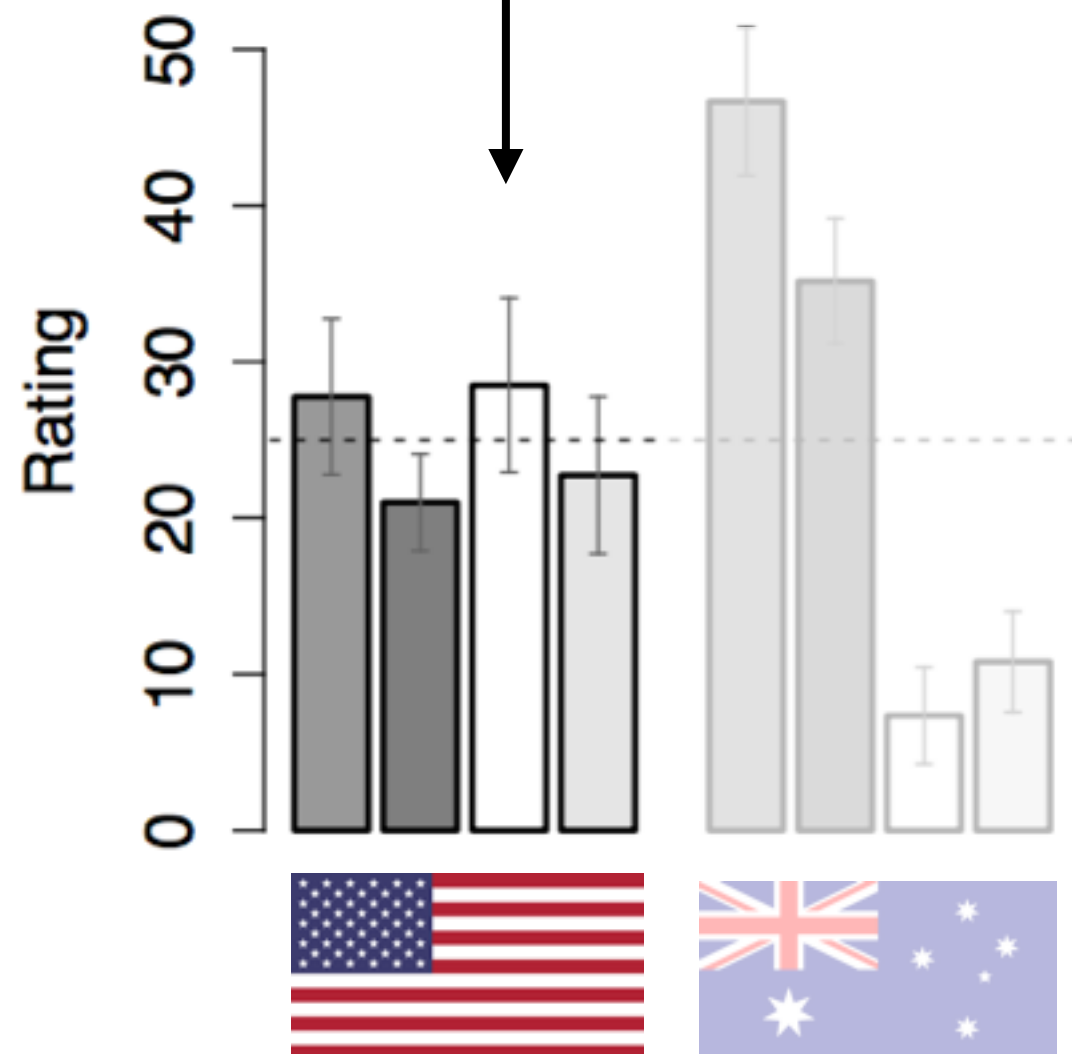


# Case study 3: An empirical illustration

# “Who will win the 2016 Australian election?”

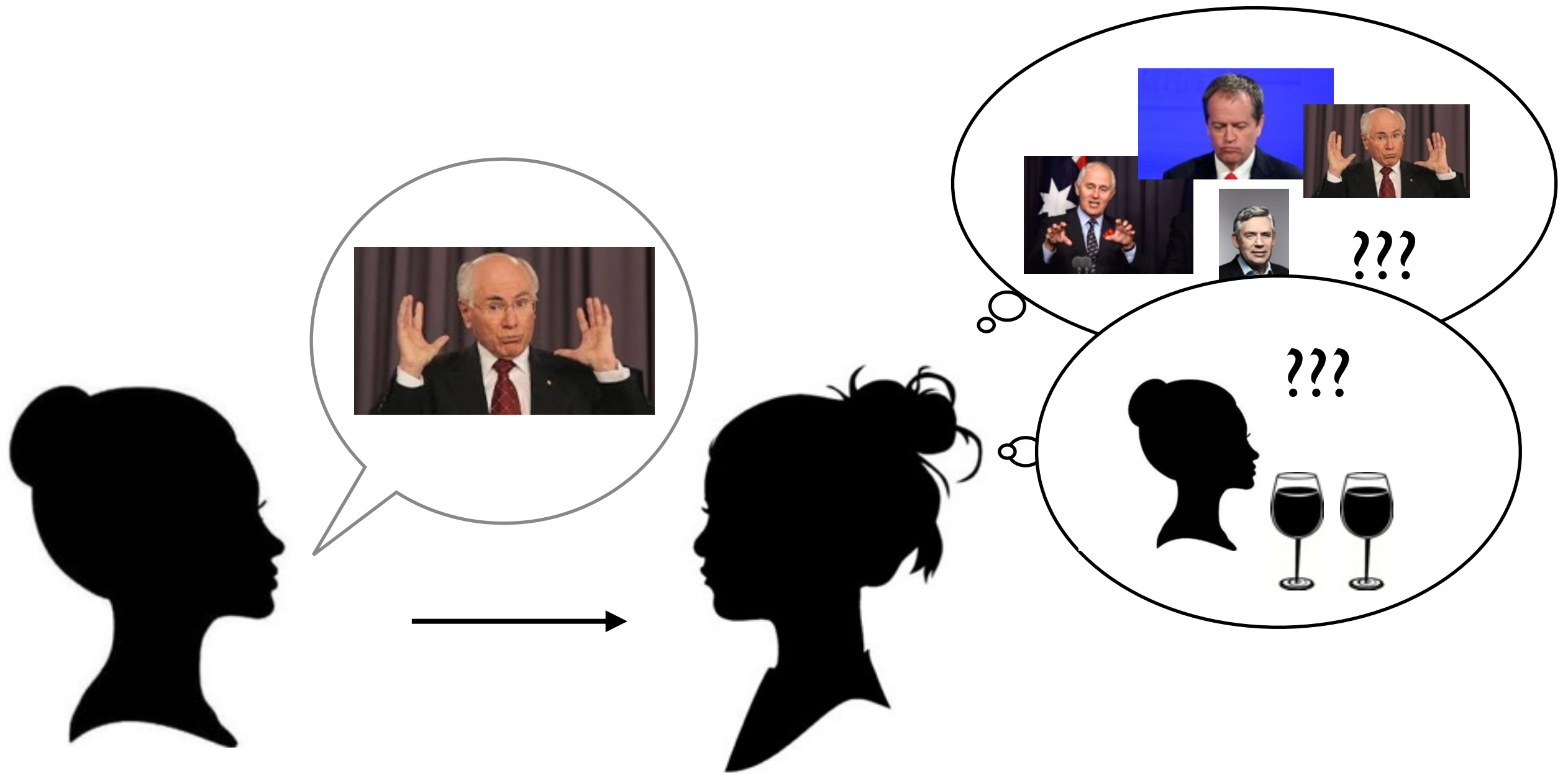


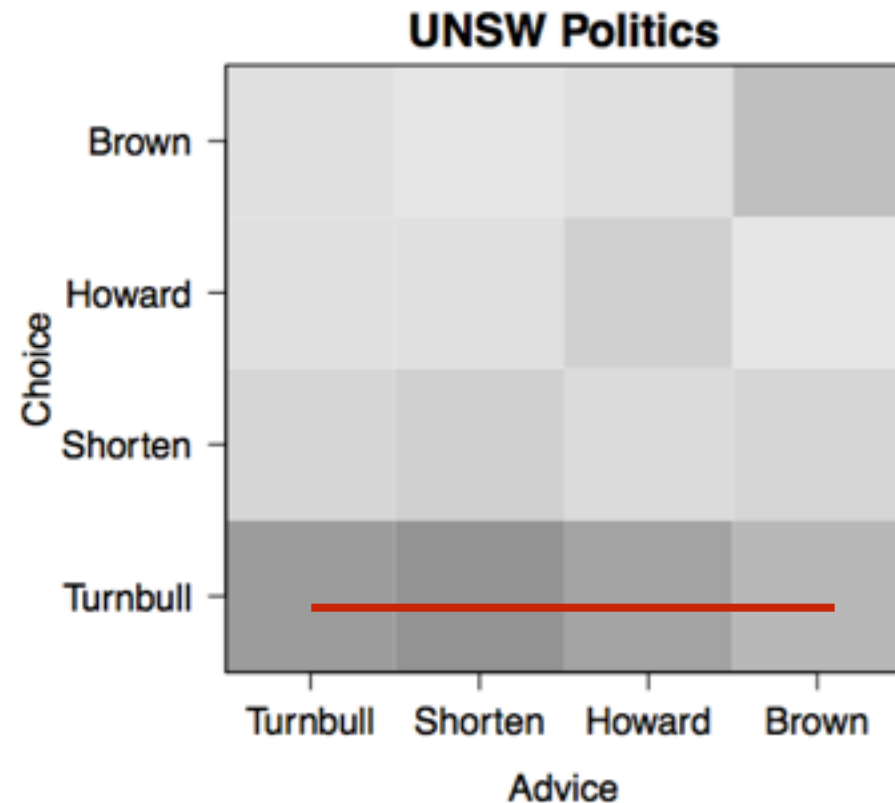
N=80 MTurk workers  
and UNSW students



N=80 MTurk workers  
and UNSW students

# The advisor task

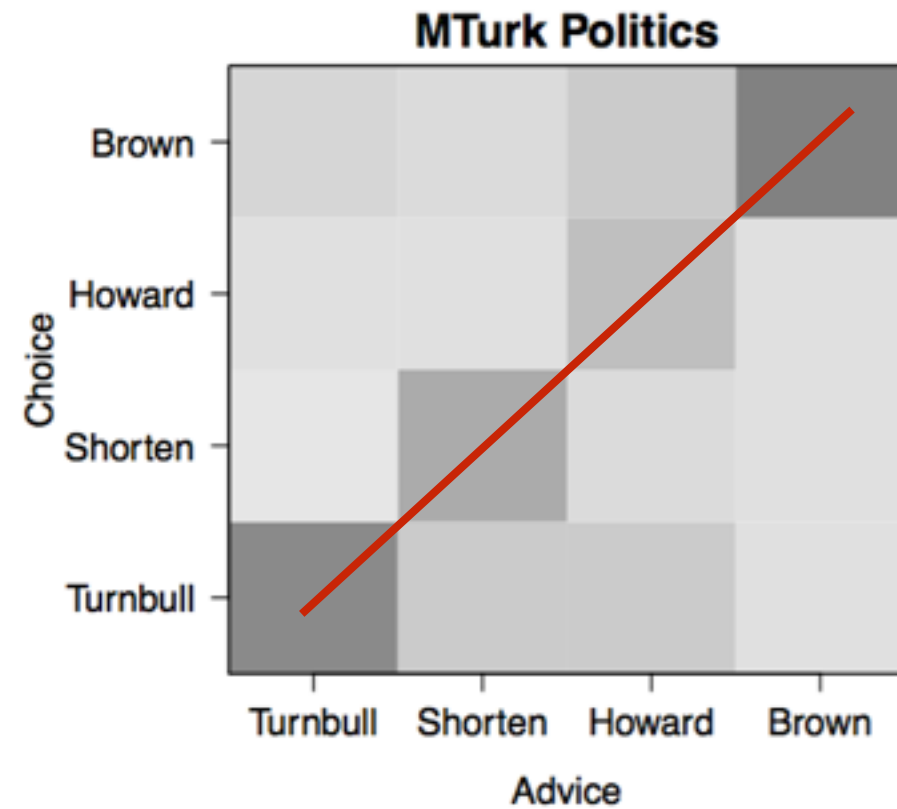




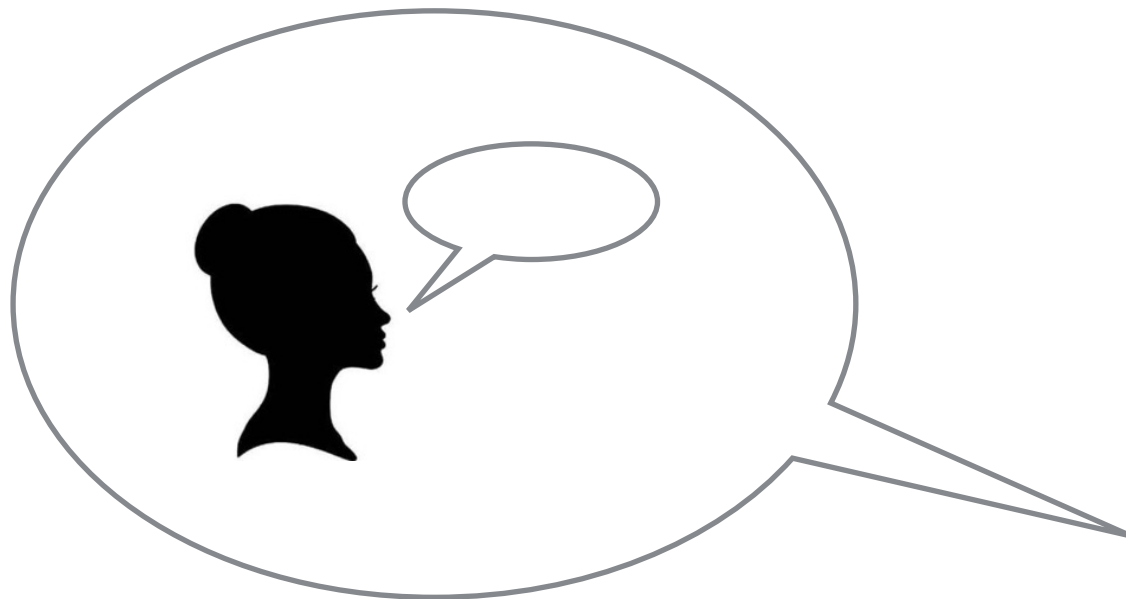
Australians ignored the advisor and predicted a Turnbull victory



N=124 UNSW students

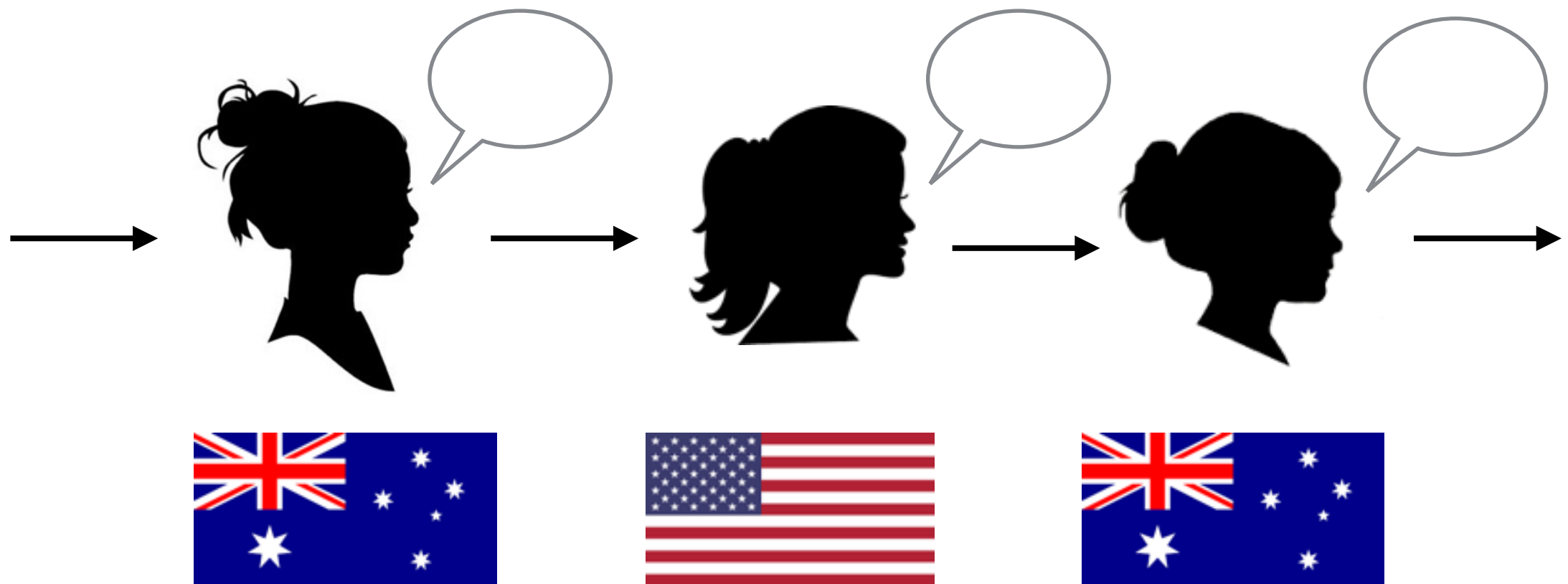


Americans followed  
the advisor regardless



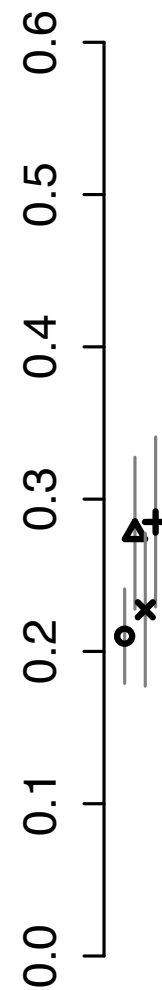
N=196 MTurk workers

Using these empirical “transition matrices”  
we can construct iterated learning chains  
with any mixture of nationalities



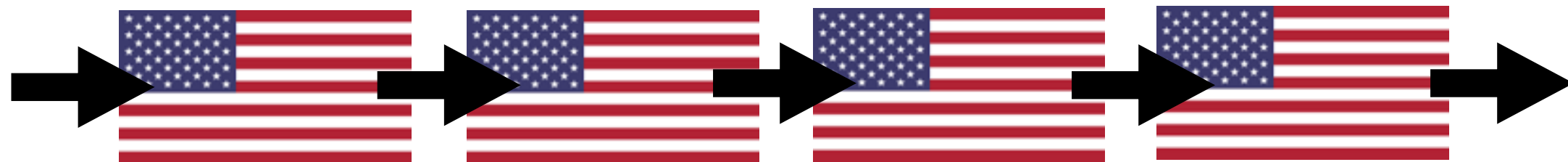


Americans claim to be totally ignorant about Australian politics...

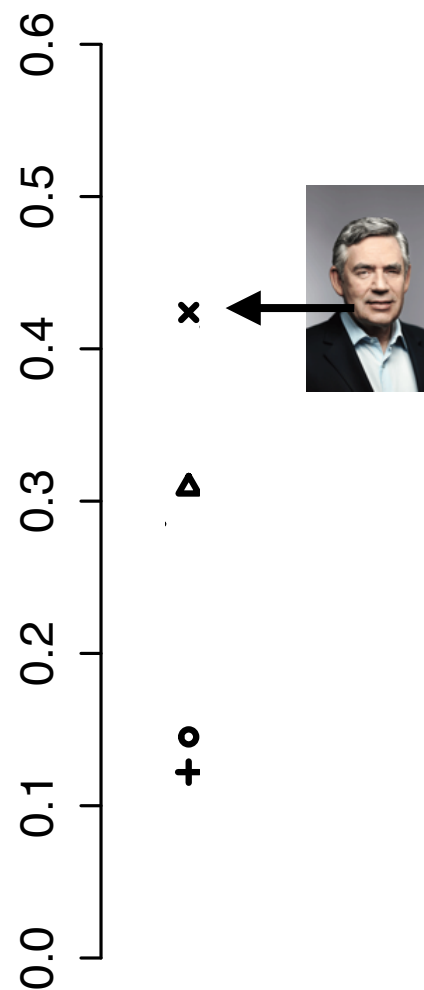


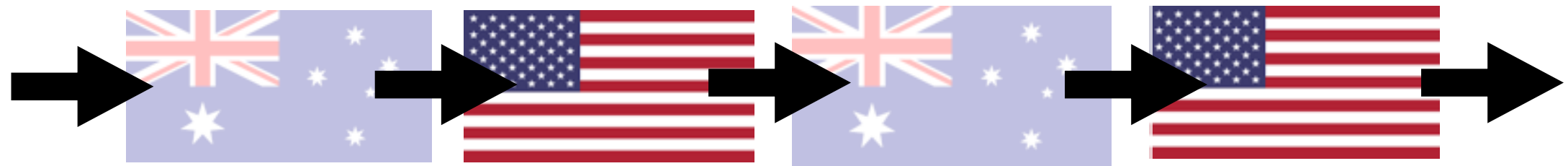
○ Shorten  
△ Turnbull  
+ Howard  
× Brown



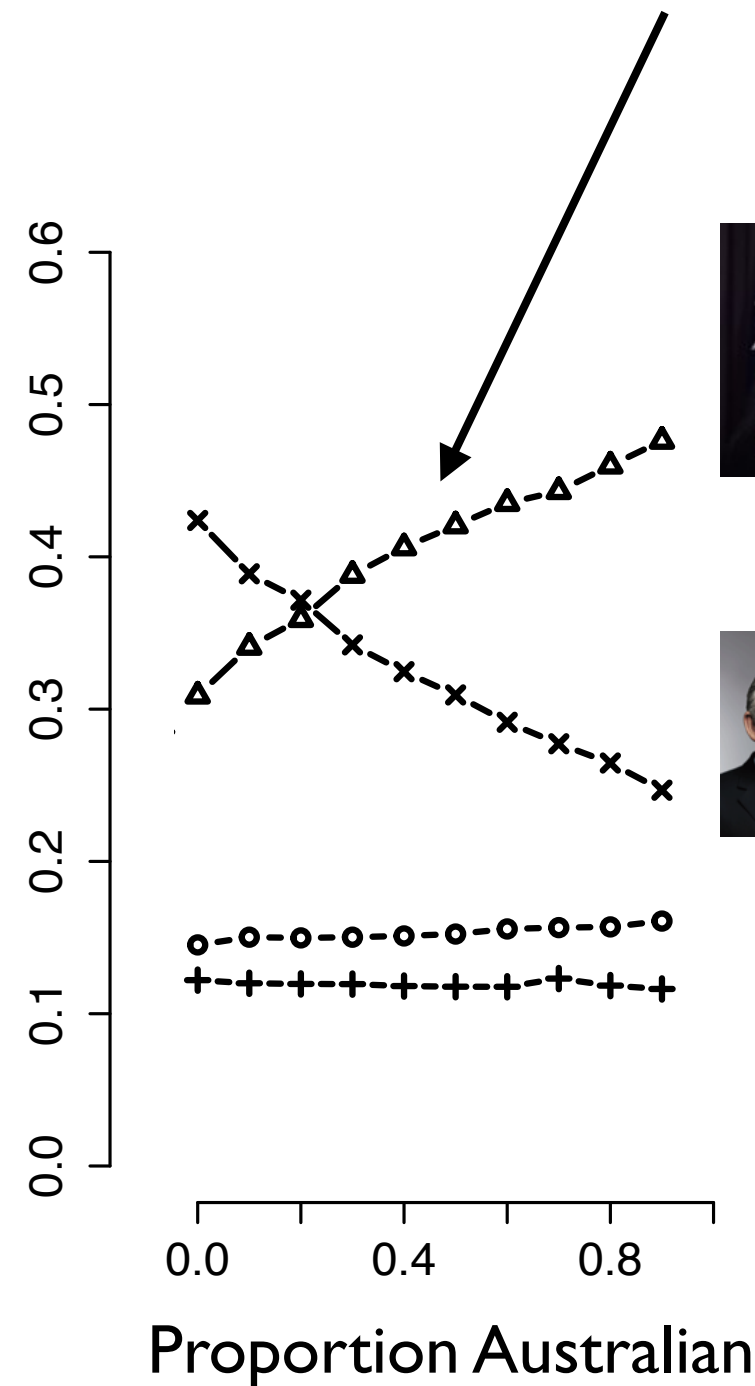


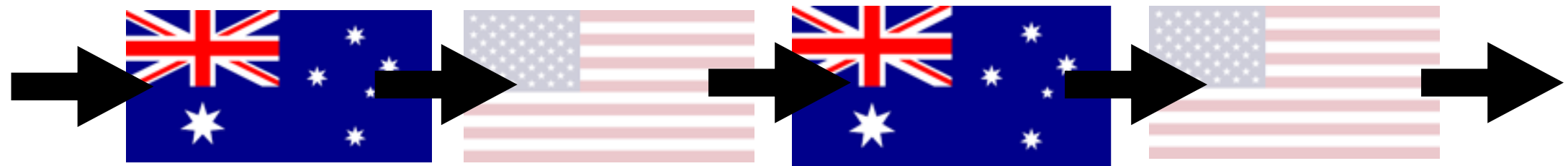
... and an all American  
iterated learning chain  
“reveals” a “preference”  
for Gordon Brown ...



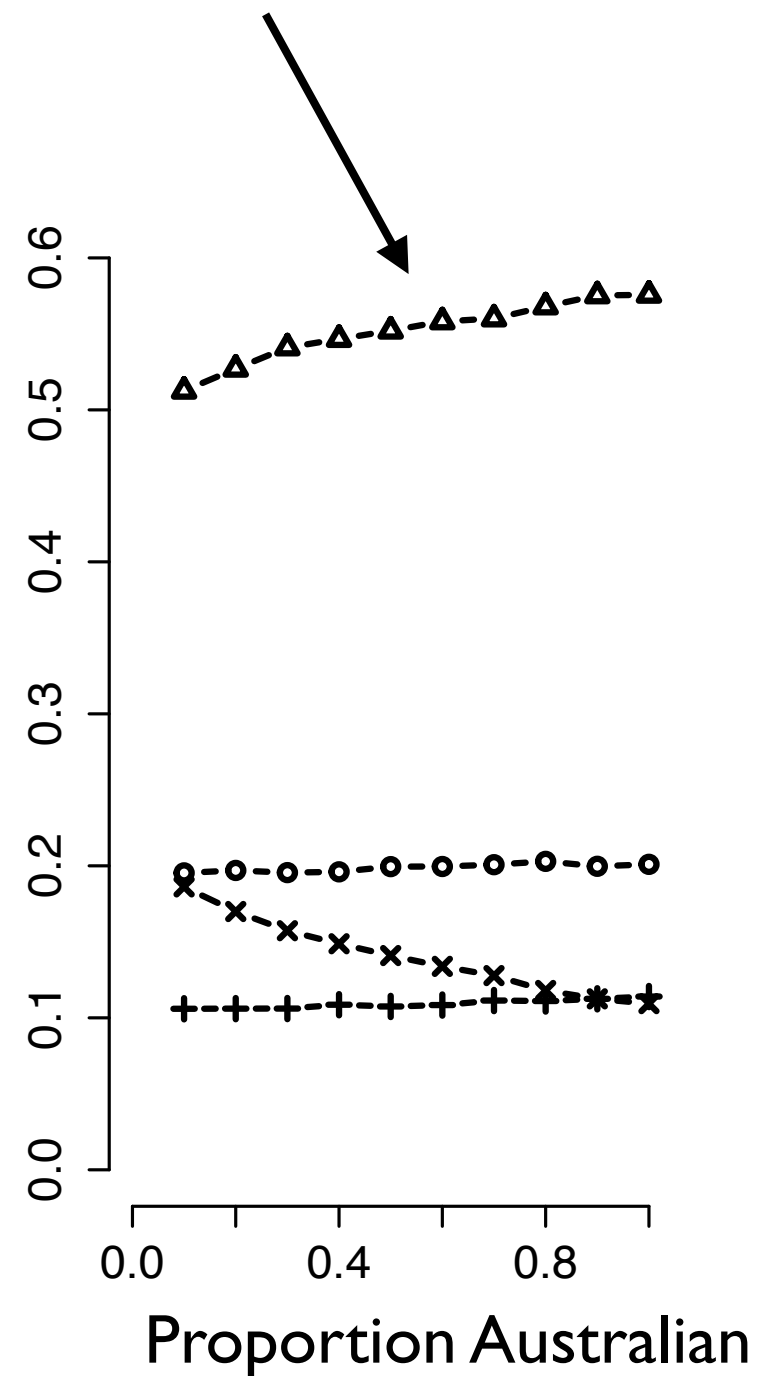


If we mix some  
Australians into the  
chain the Americans  
endorse Malcolm  
Trunbull





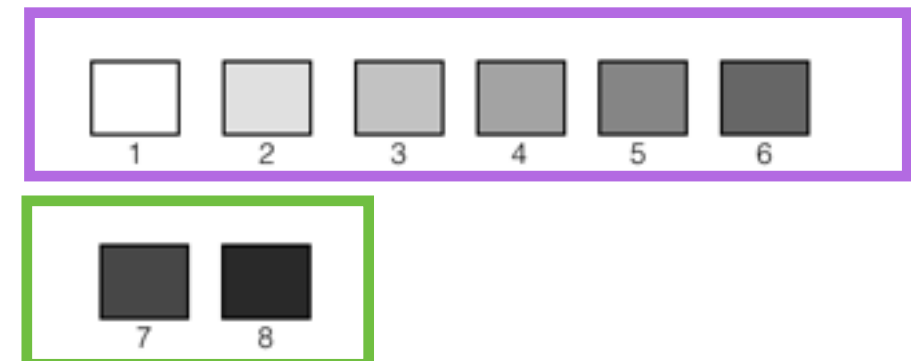
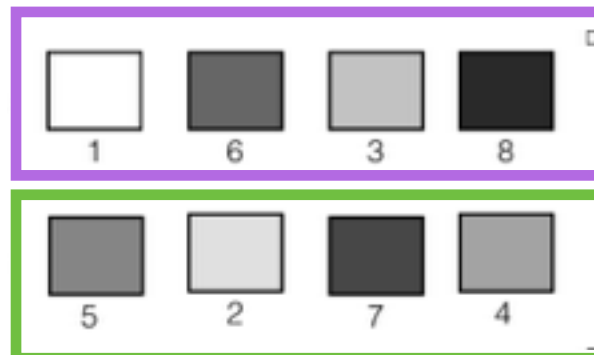
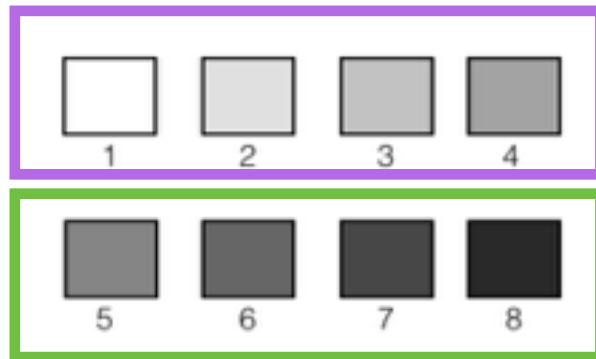
Australians choose  
Turnbull no matter  
how many Americans  
are included



Case study 4:  
A non-Bayesian example

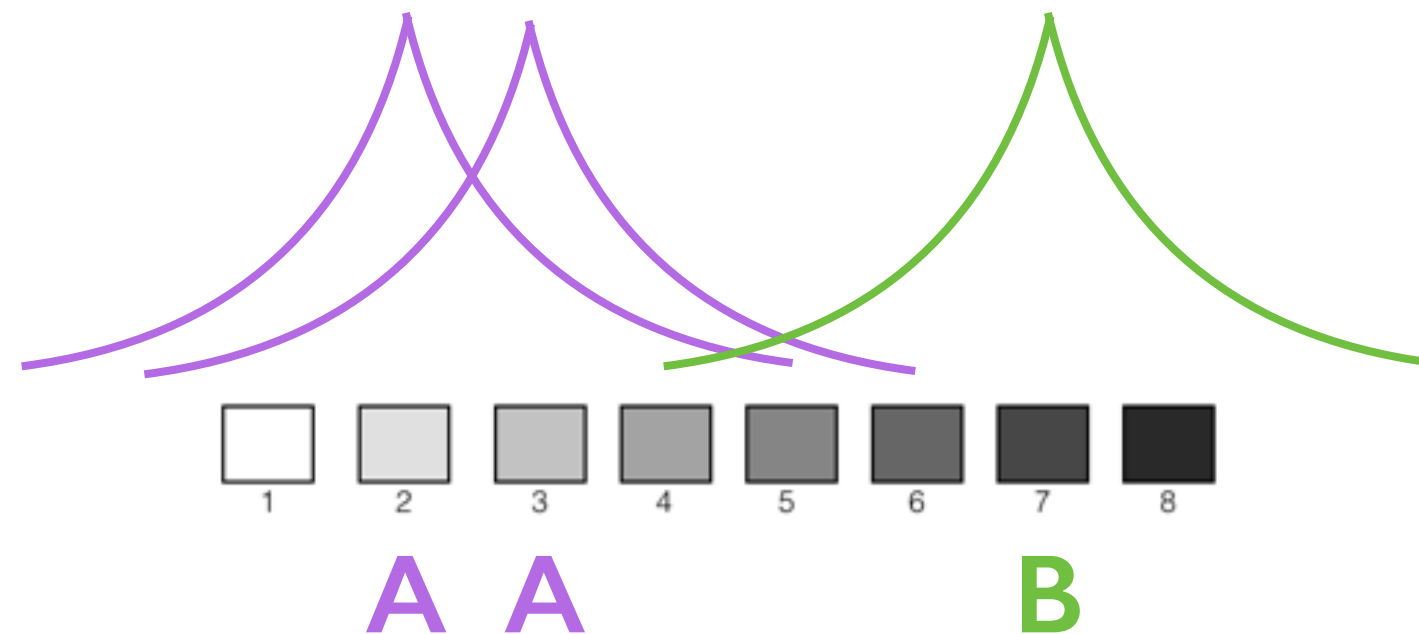
# Iterated learning can be used to study the biases people bring to categorisation problems

(e.g., Austerweil 2014)



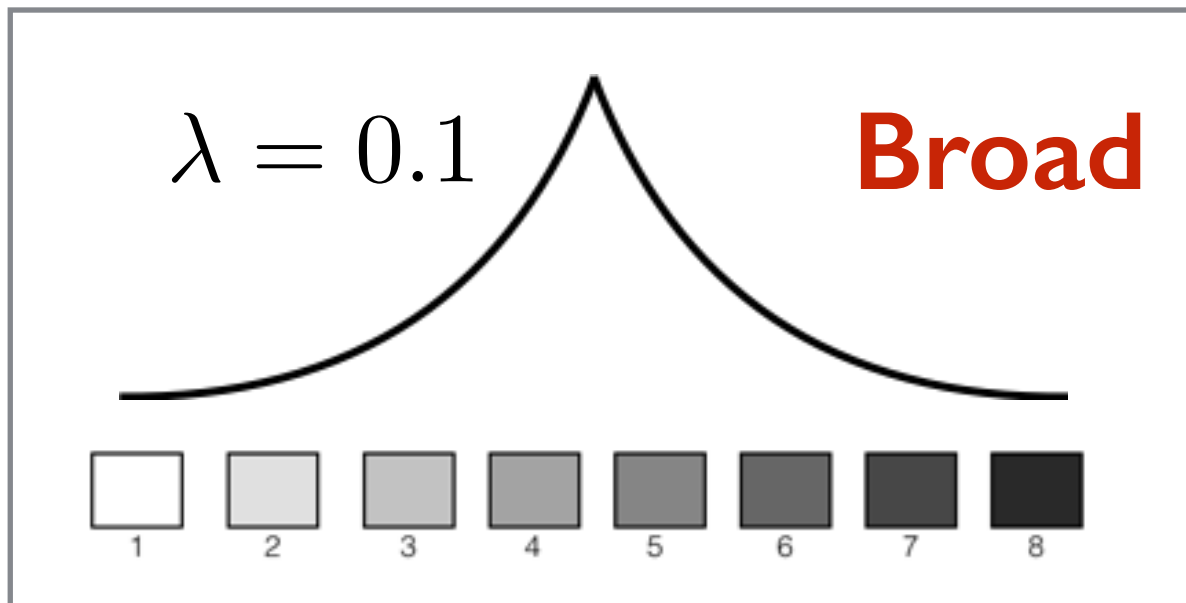
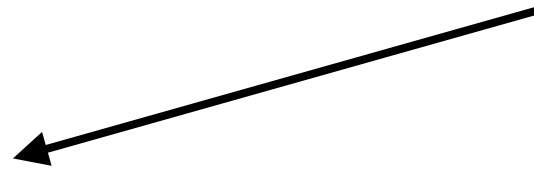
# Exemplar model of categorisation

(Nosofsky 1986; Pothos & Bailey 2009)

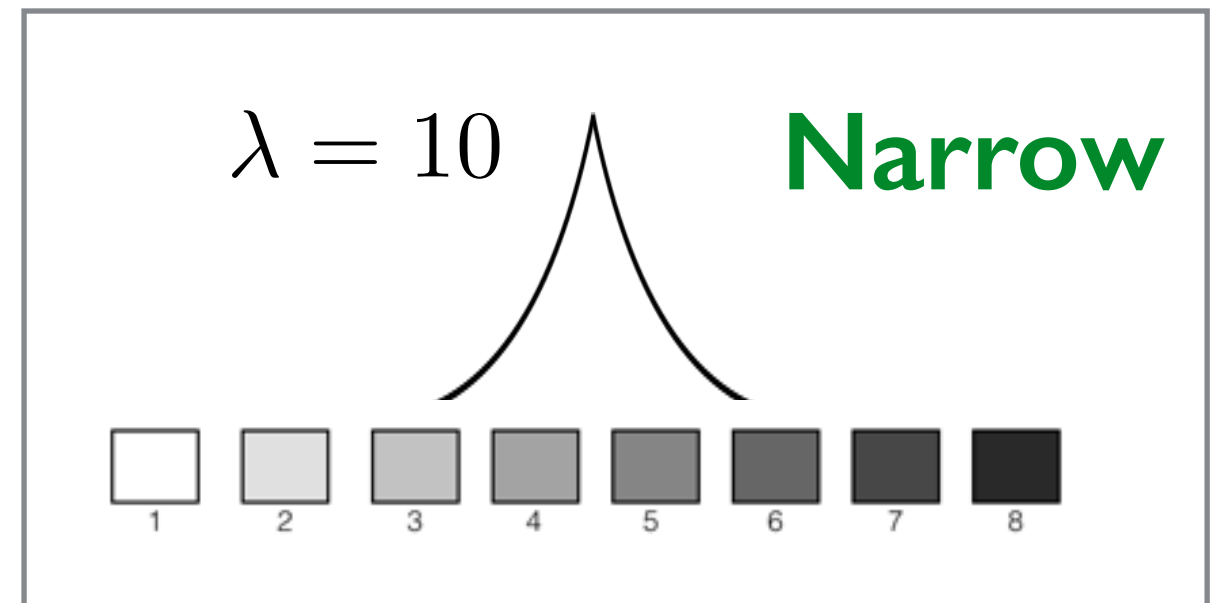
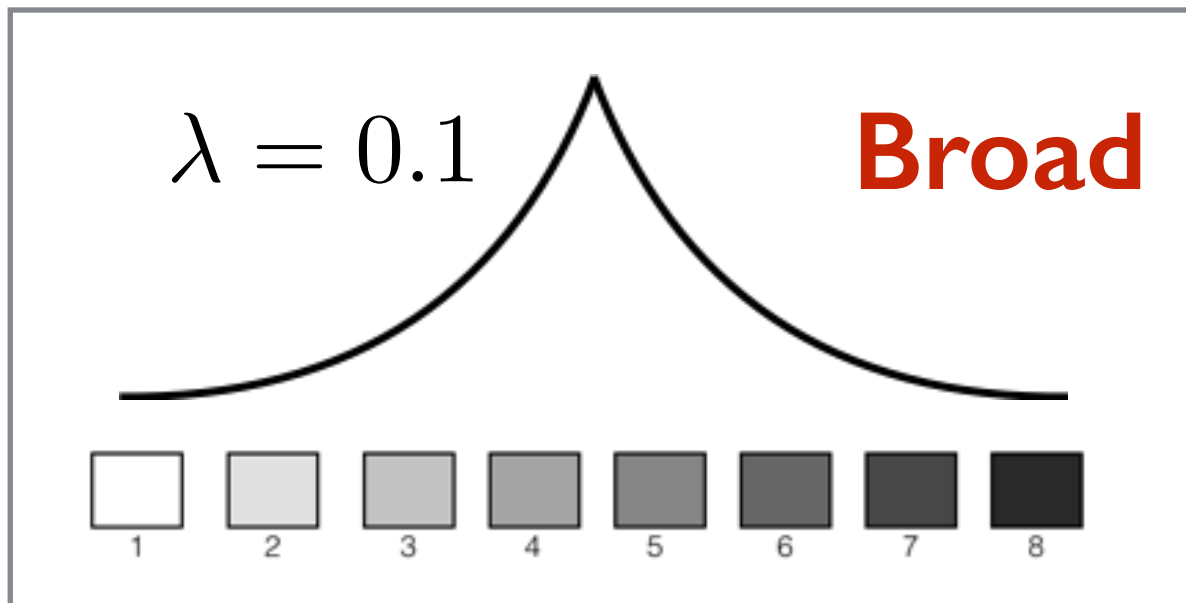
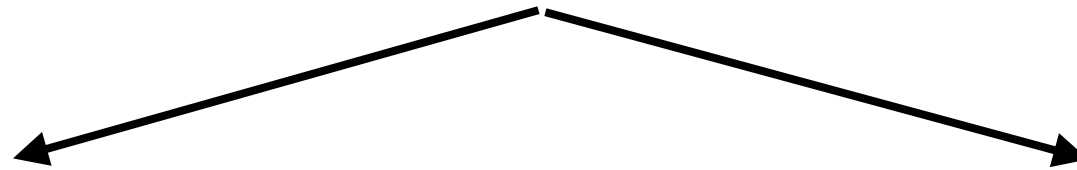


GCM: categorisation probability is  
proportional to sum similarity

GCM allows learners to vary in how broadly they generalise from a stimulus



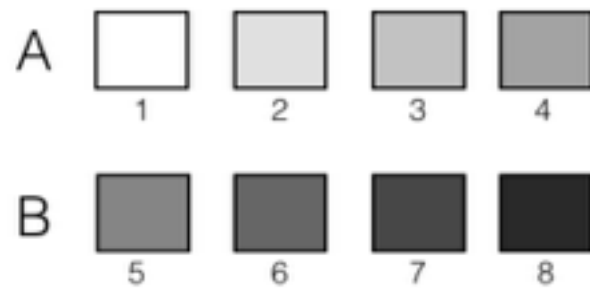
GCM allows learners to vary in how broadly they generalise from a stimulus





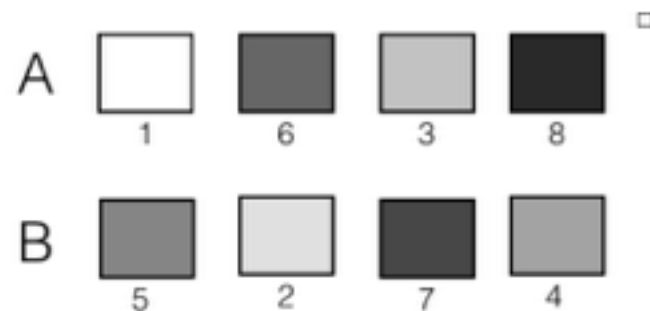
# Categorisation bias #1

Coherent categories:

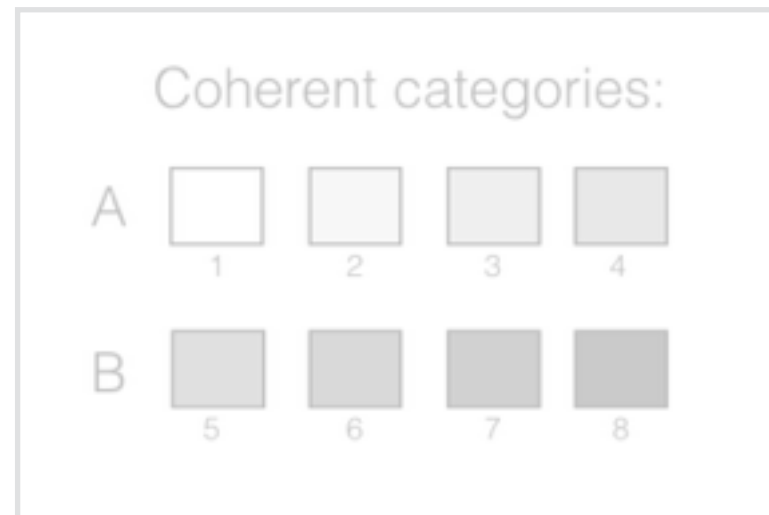


← Coherent systems  
assign similar items  
to the same category

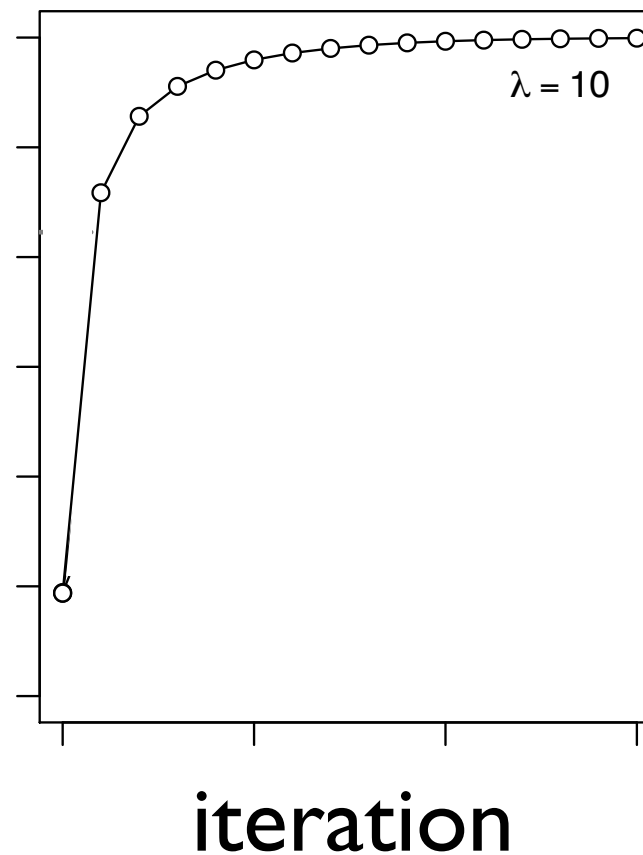
Incoherent categories:



# Iterated learning with GCM when learners are **homogenous**

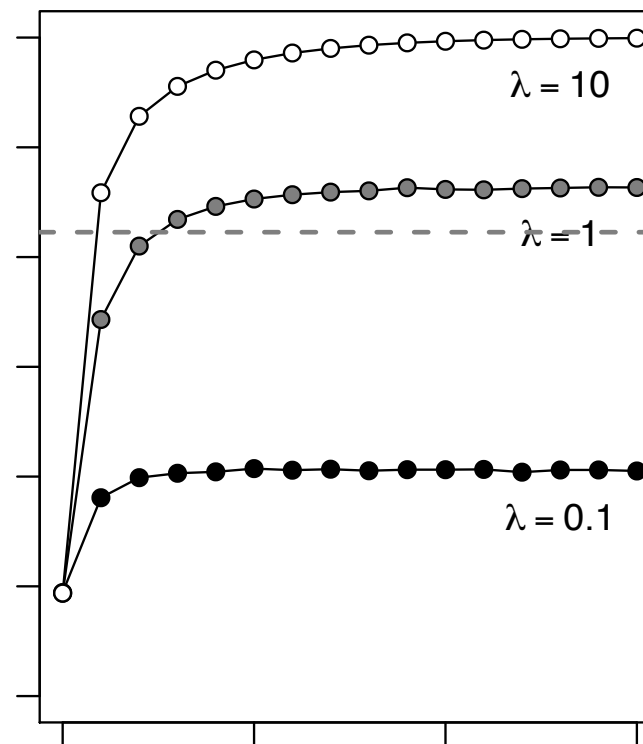
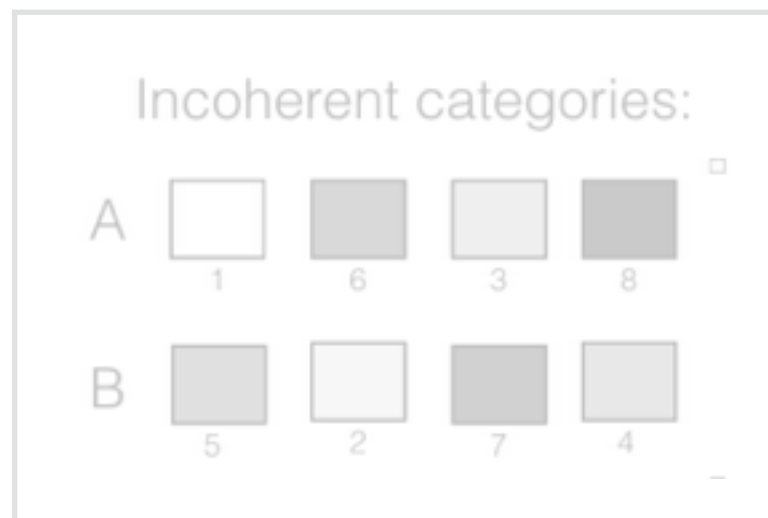
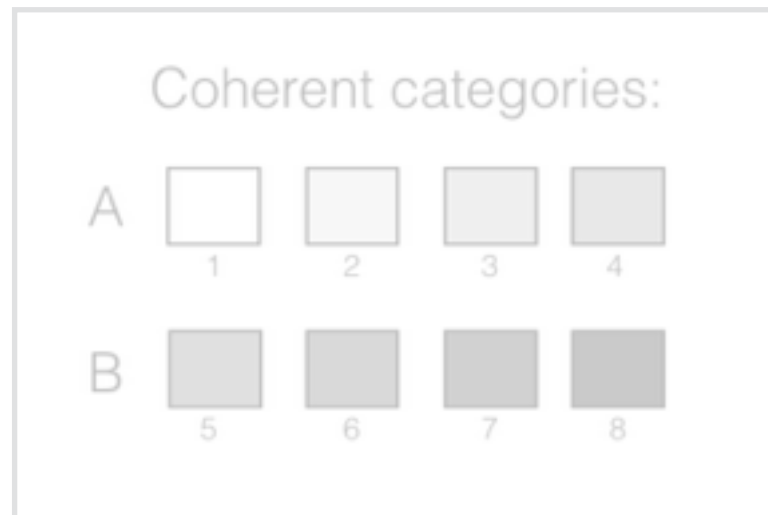


coherence



**Narrow**  
generalisation  
implies strong  
coherence bias

# Iterated learning with GCM when learners are **homogenous**



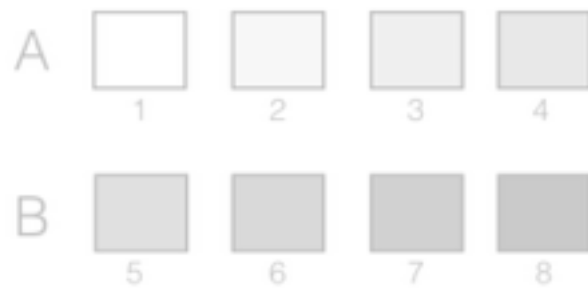
**Narrow**

**Broad**

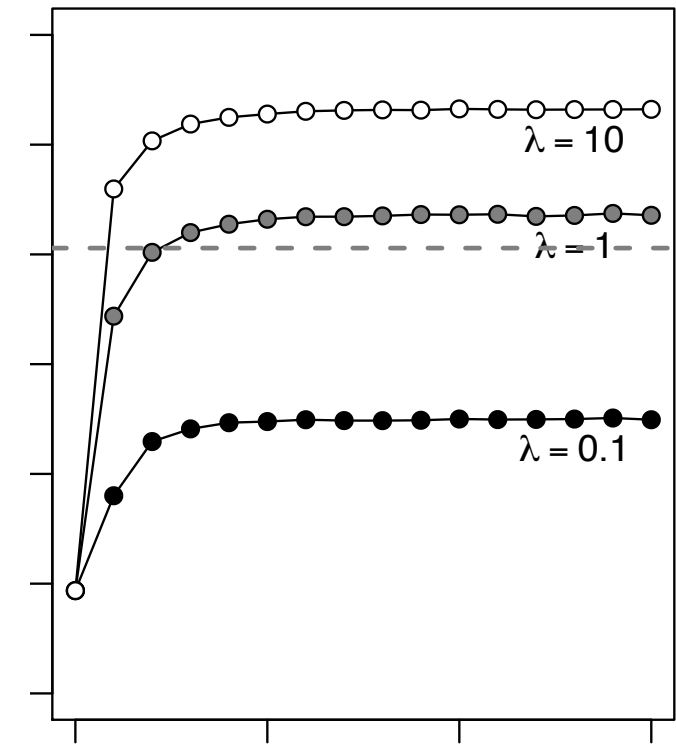
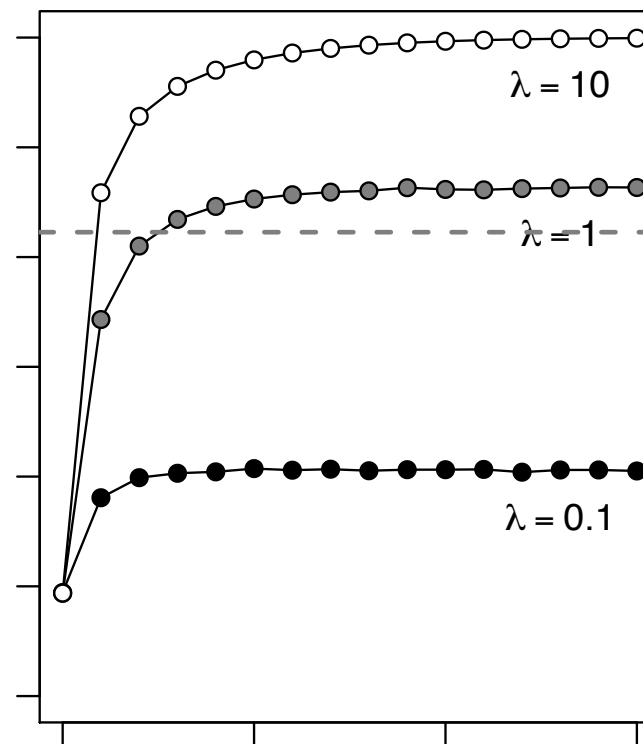
# Heterogeneity isn't much of a problem here



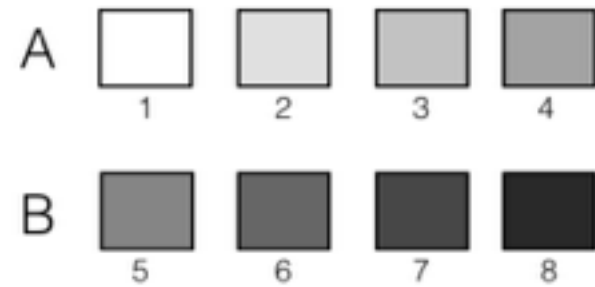
Coherent categories:



Incoherent categories:

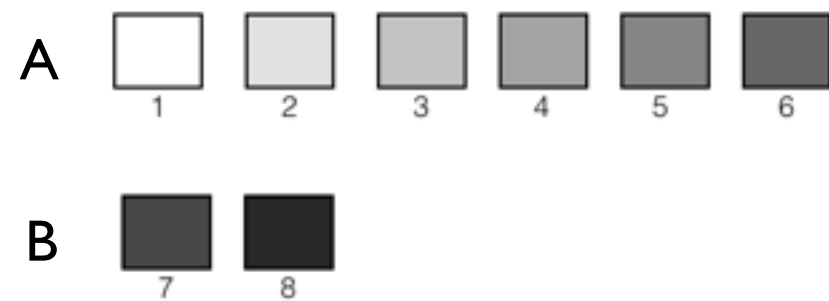


## Equally sized categories



## *Categorisation bias #2*

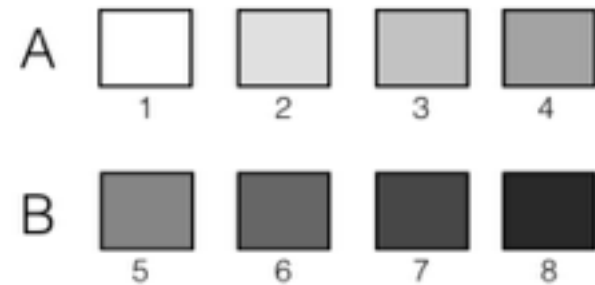
## Unequally sized categories



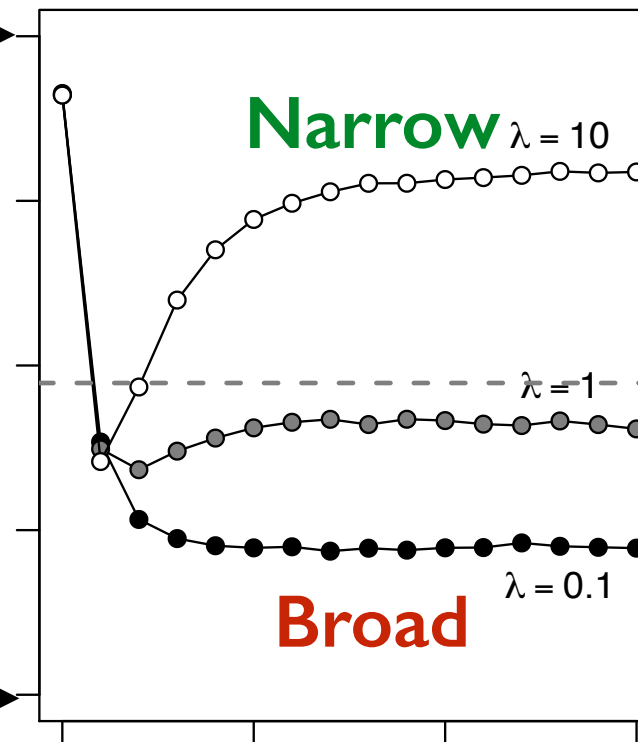
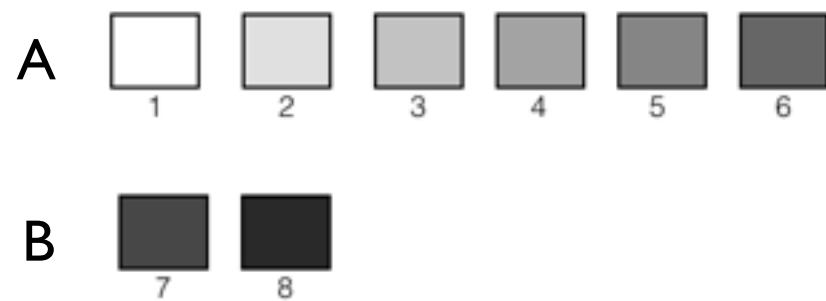
# Homogenous chains



## Equally sized categories



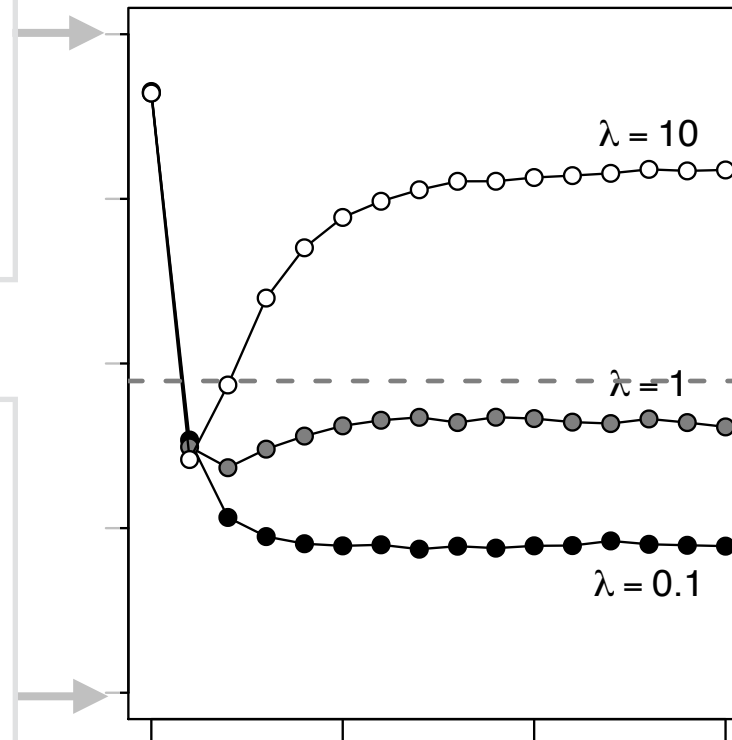
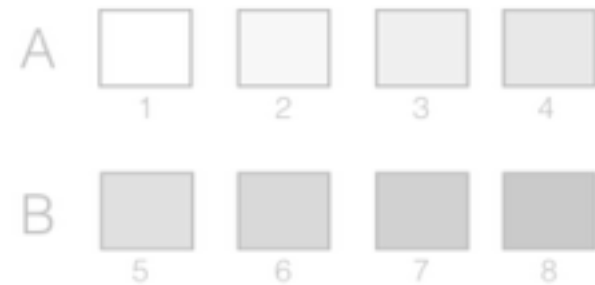
## Unequally sized categories



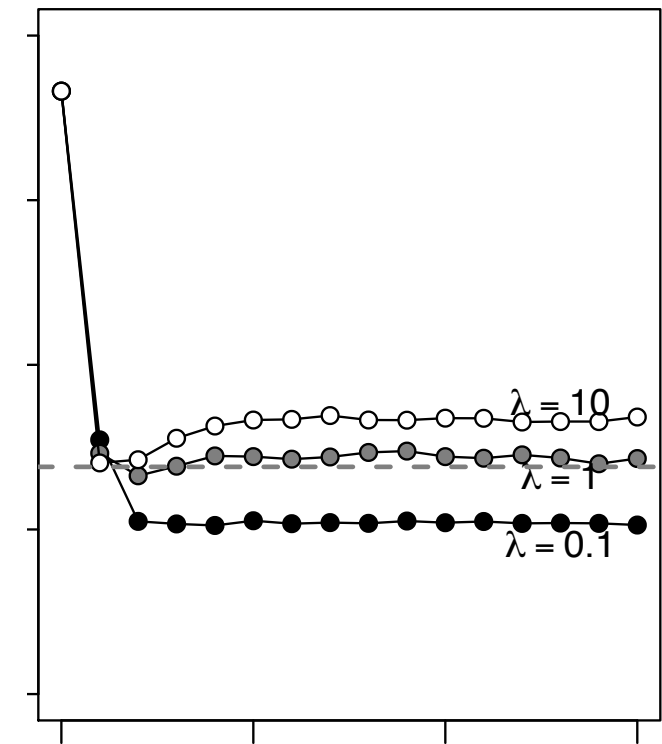
# Heterogenous chains



Equally sized categories



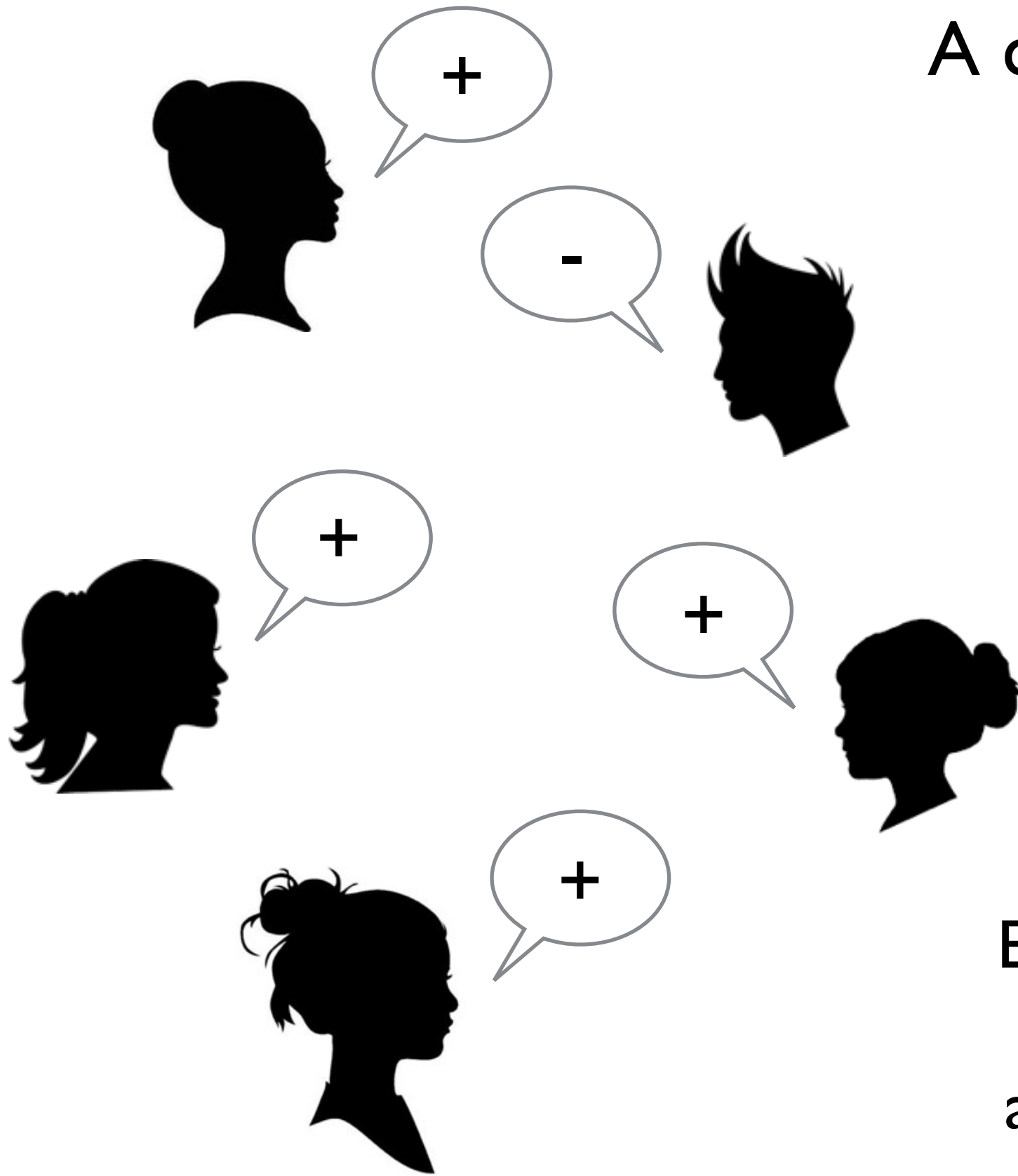
Unequally sized categories



Case study 5:  
Belief evolution in a self-organising  
Bayesian social network



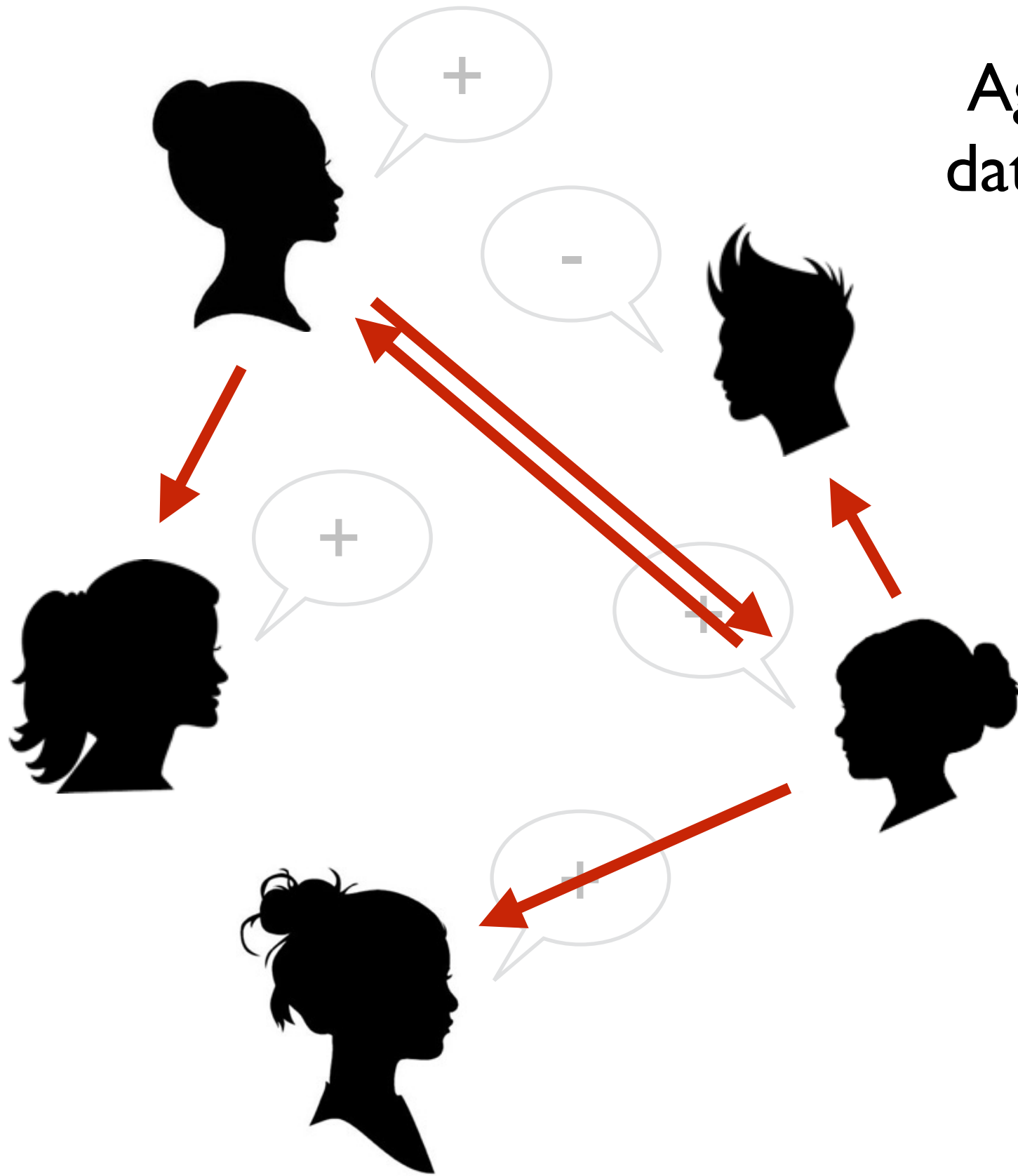
# A crowd of Bayesian speakers

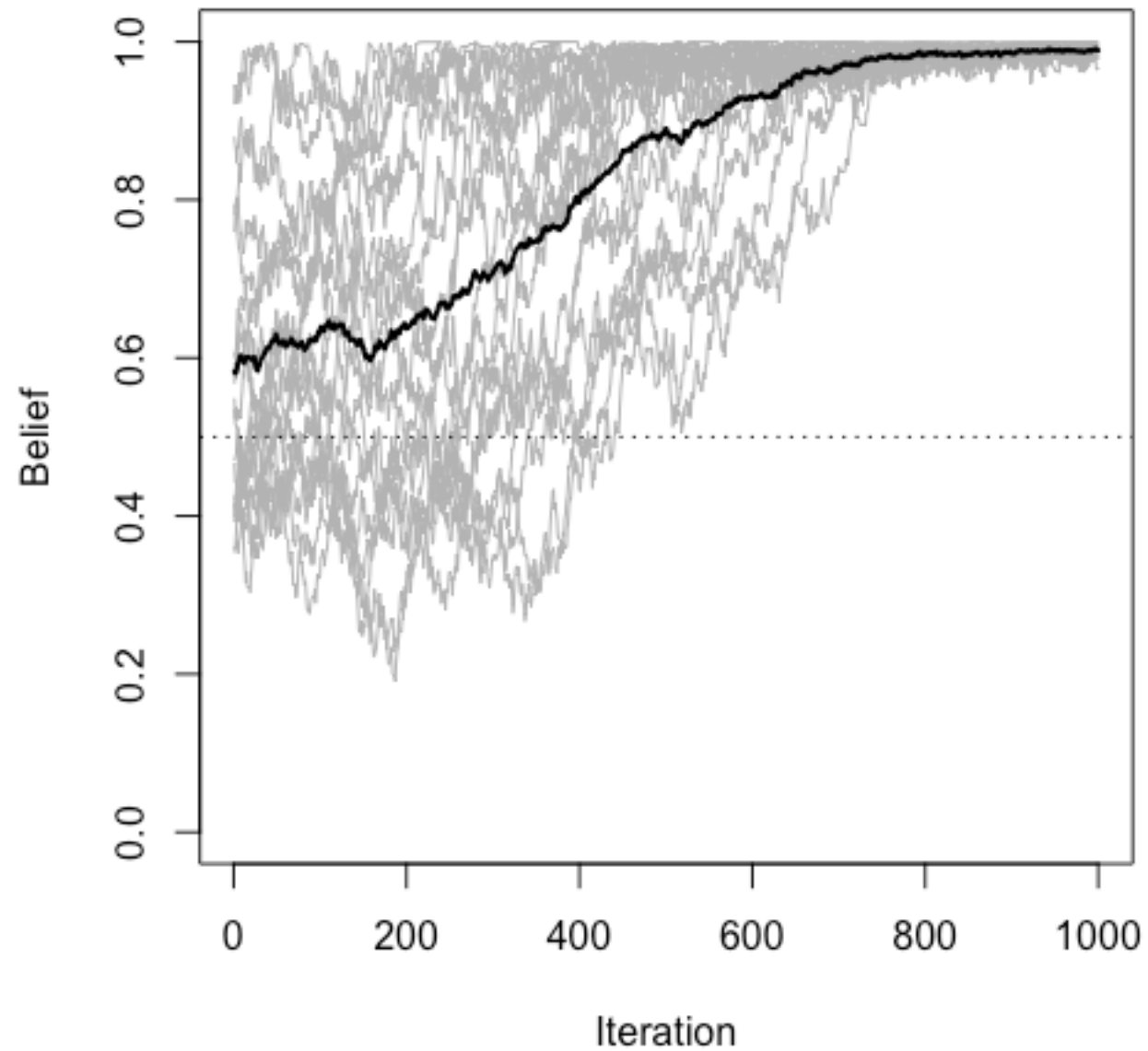


Each agent maintains belief  
about the rate of + and  
about the trustworthiness  
of other agents

Agents prefer to receive  
data from trusted sources

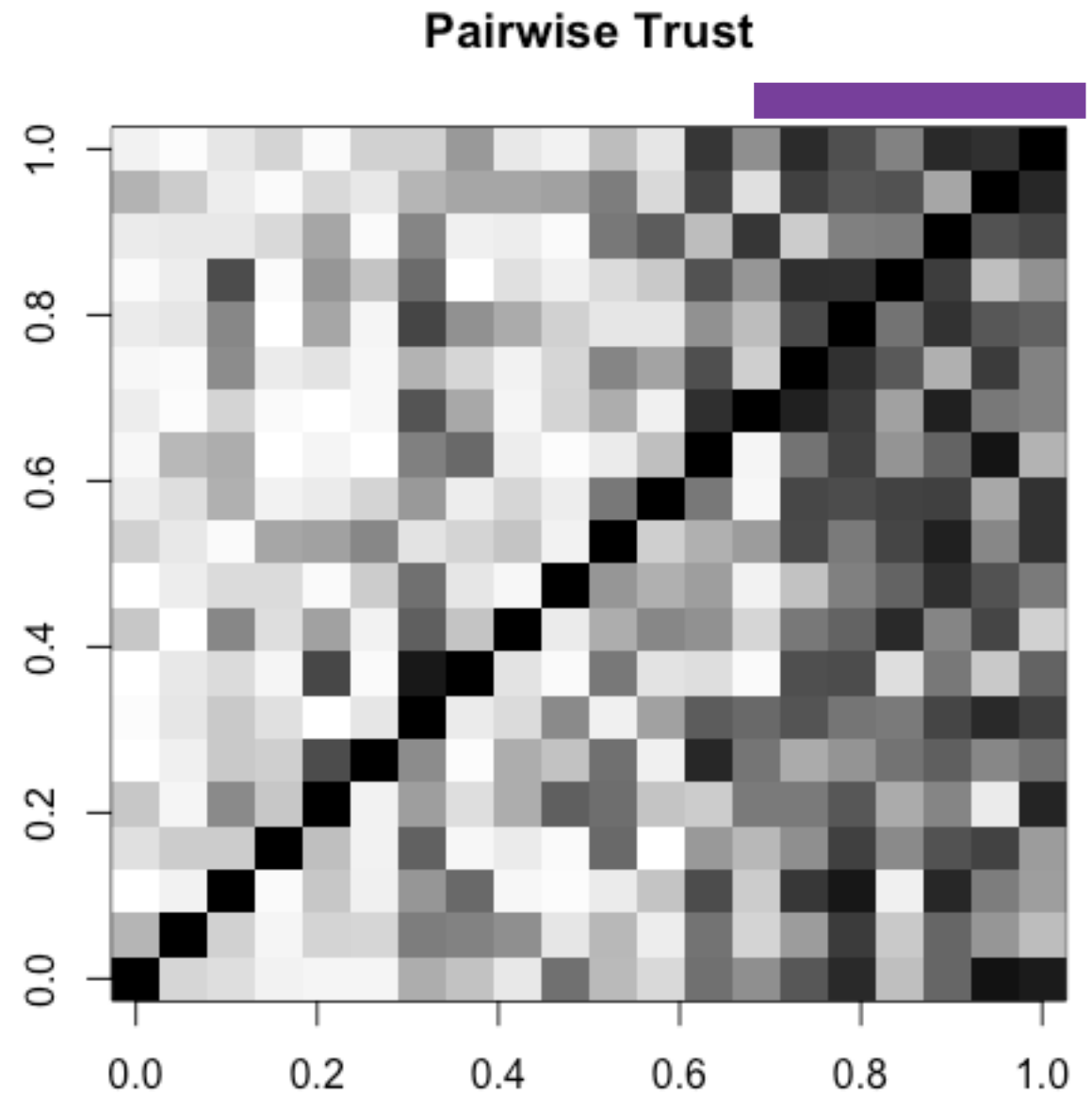
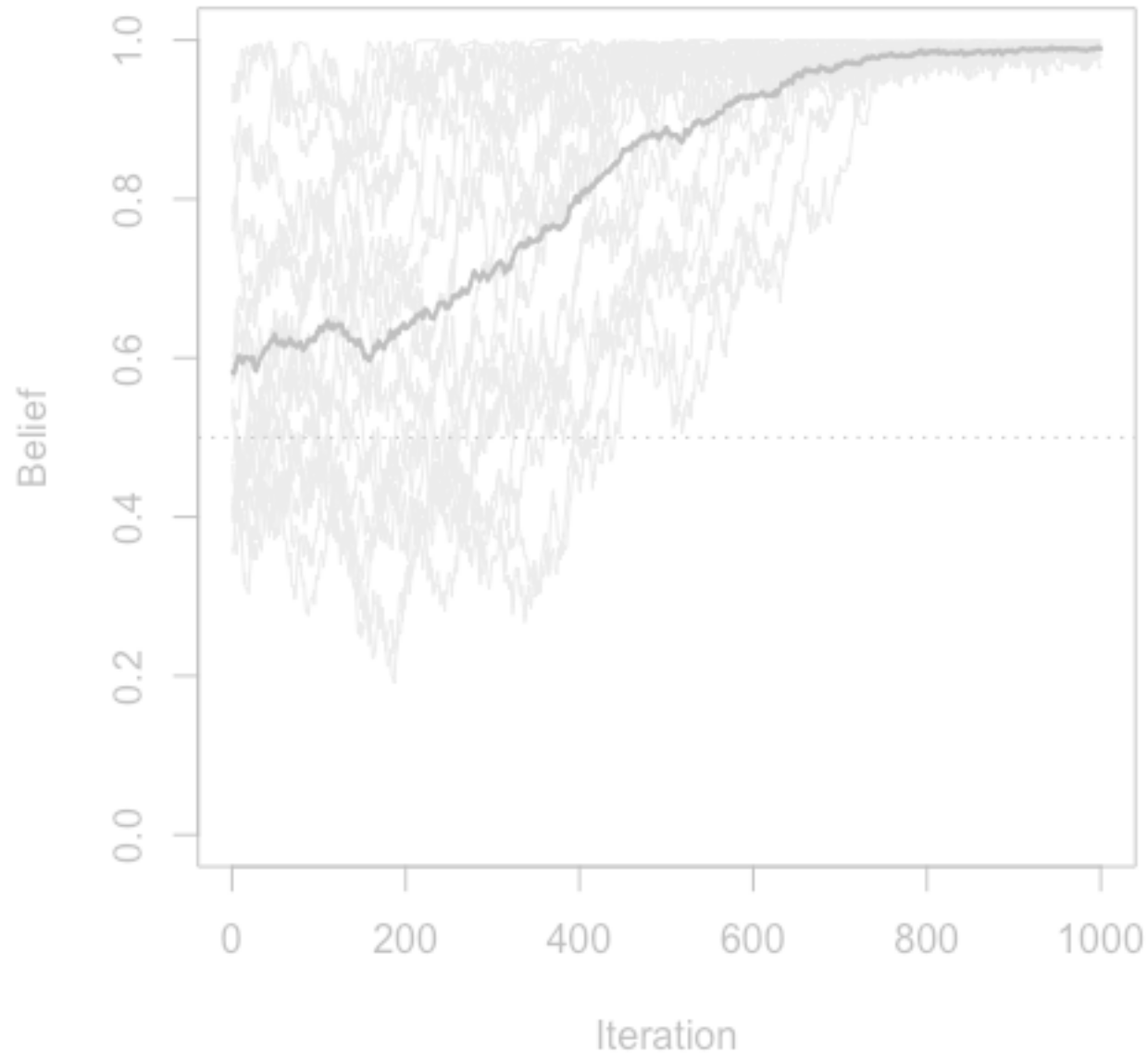
What could  
possibly go wrong?

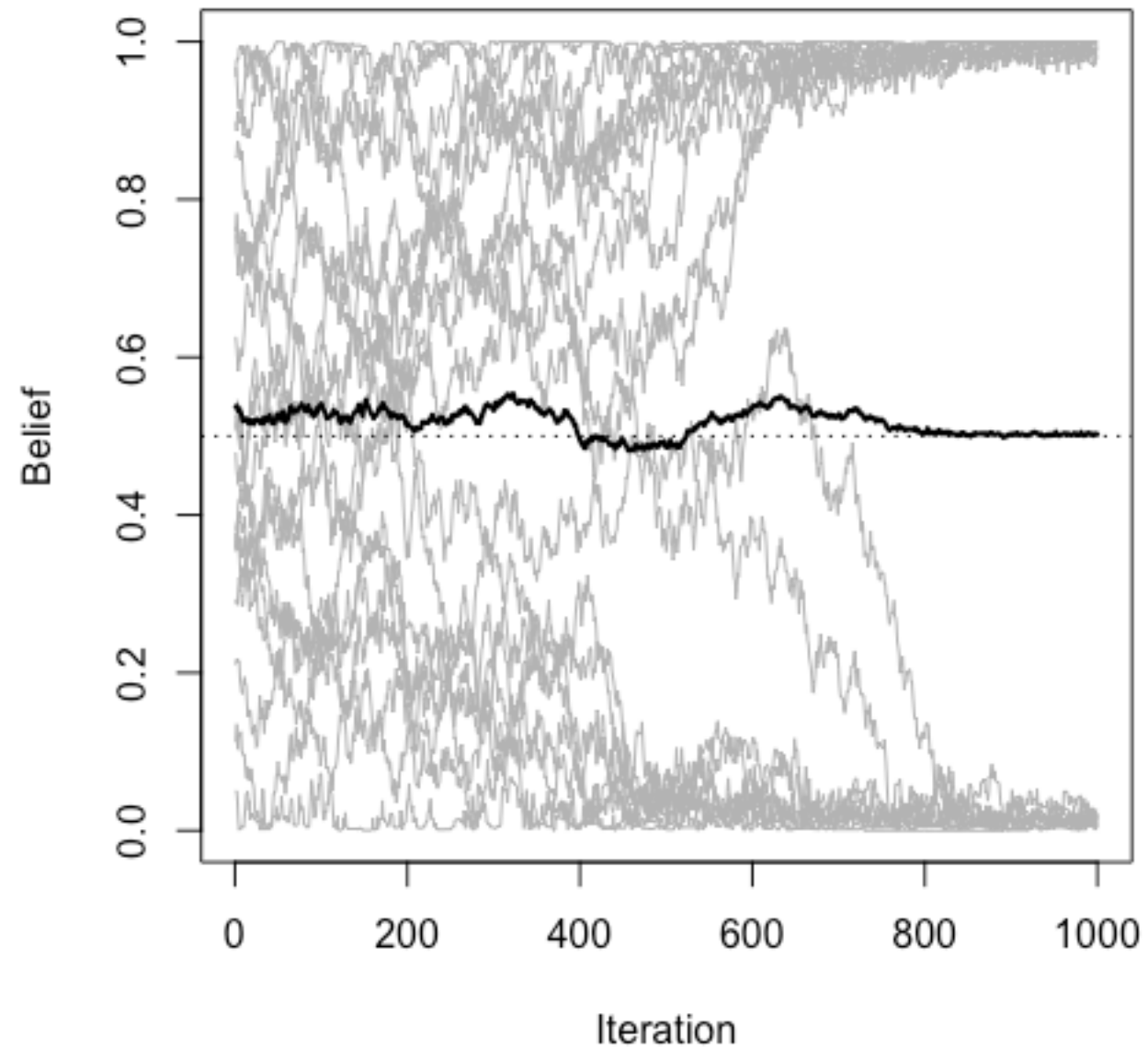




They might ratchet  
themselves into  
extremism?

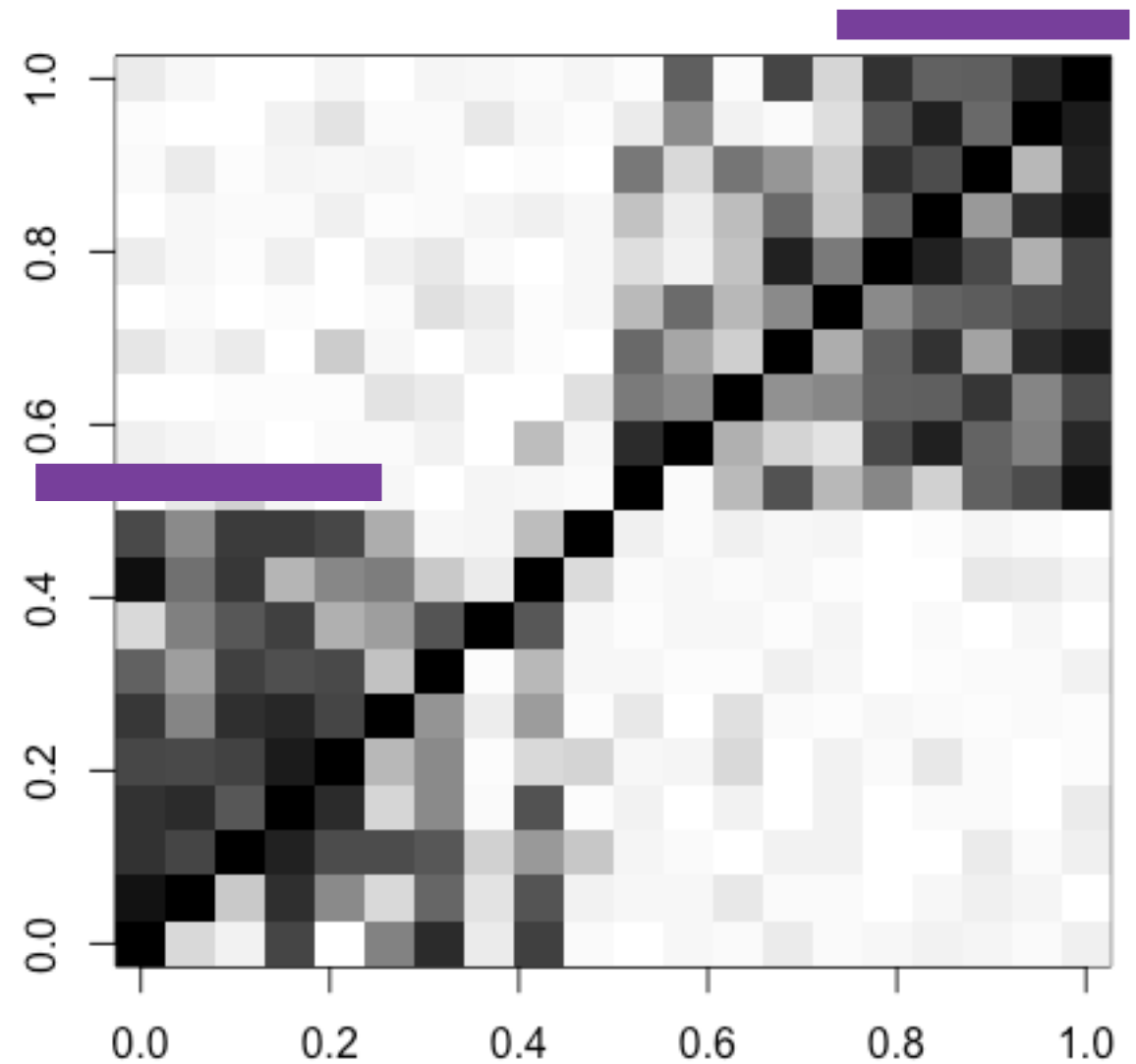
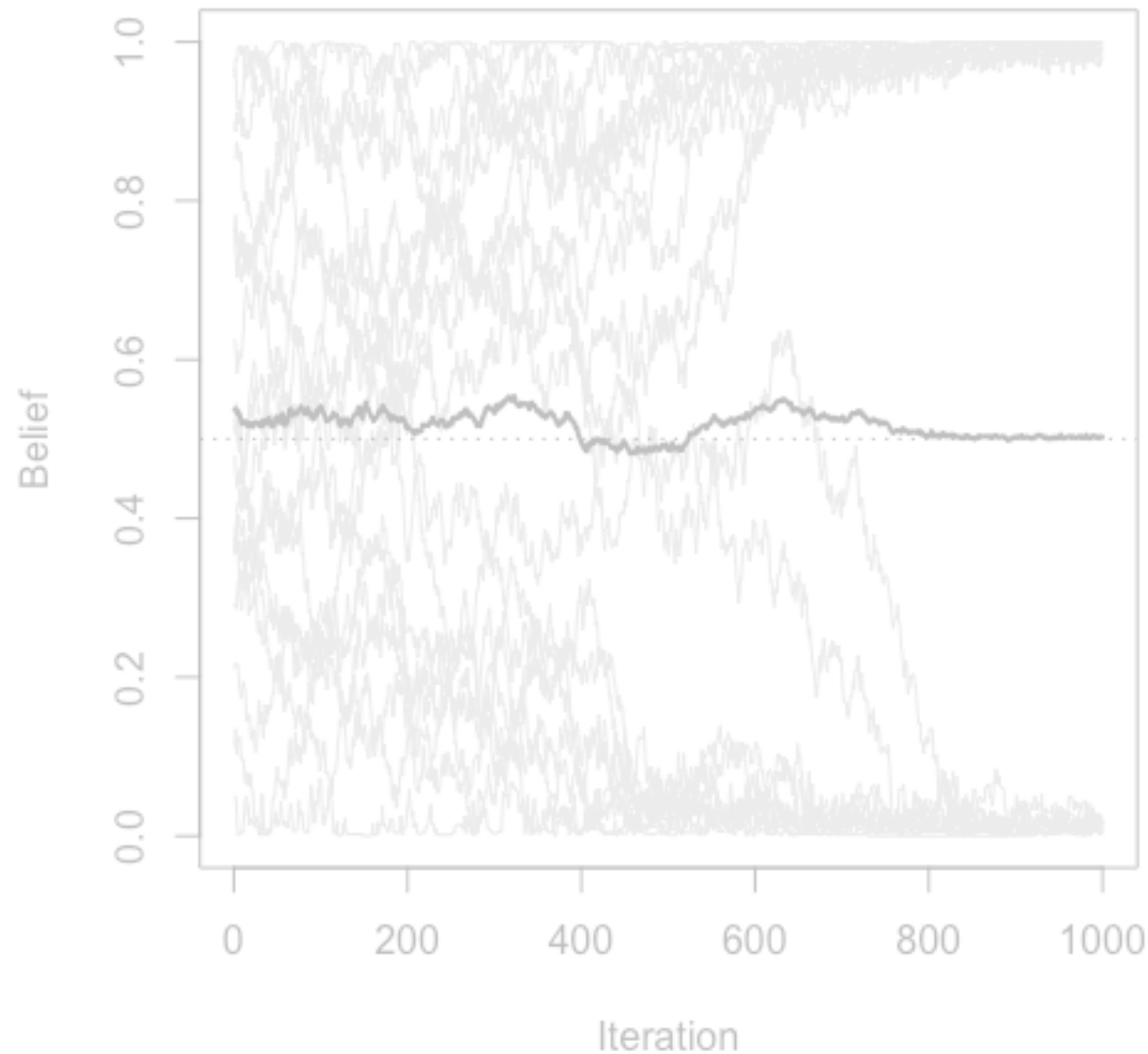
...with the biggest **extremists**  
being the most trusted agents



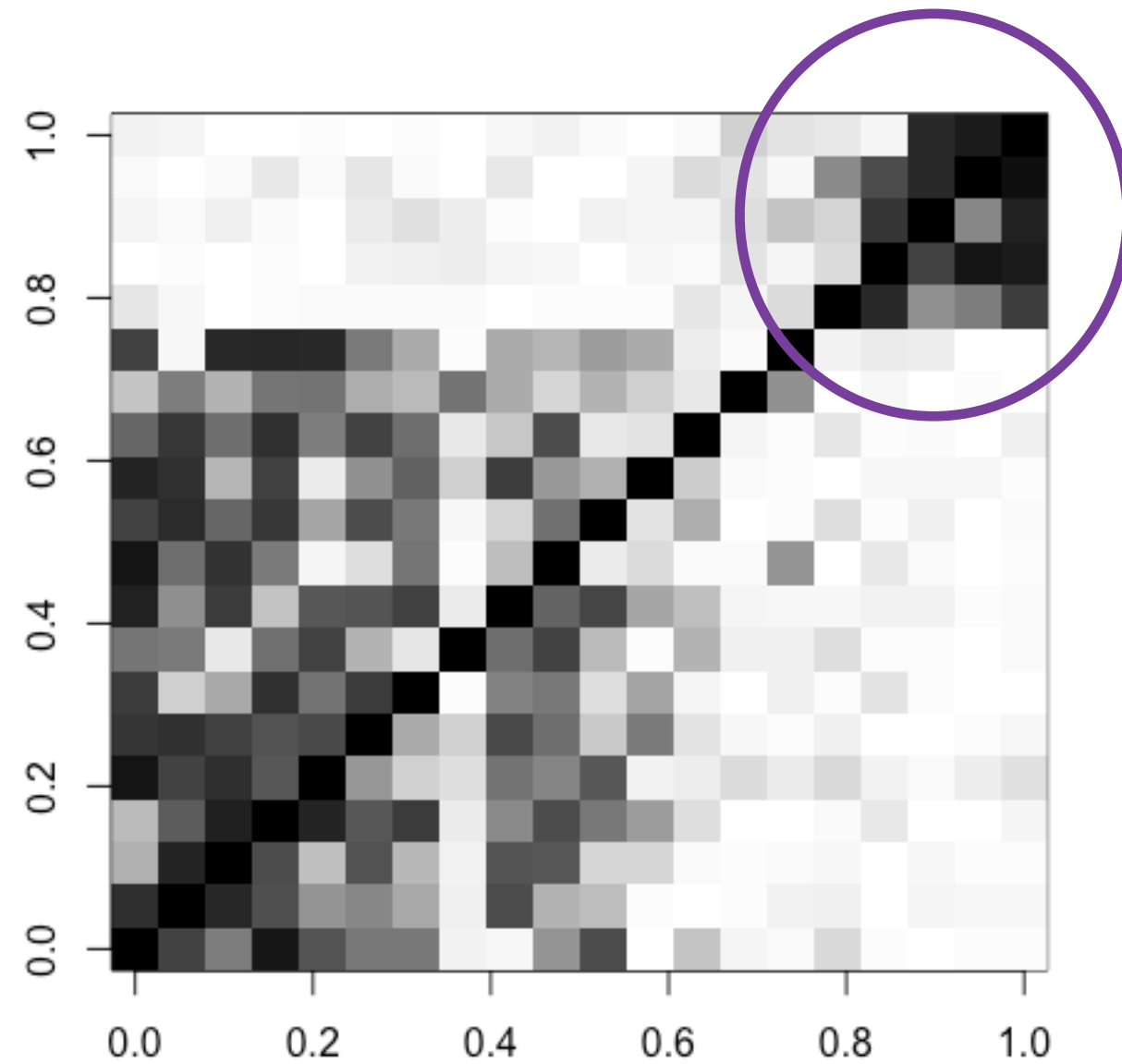
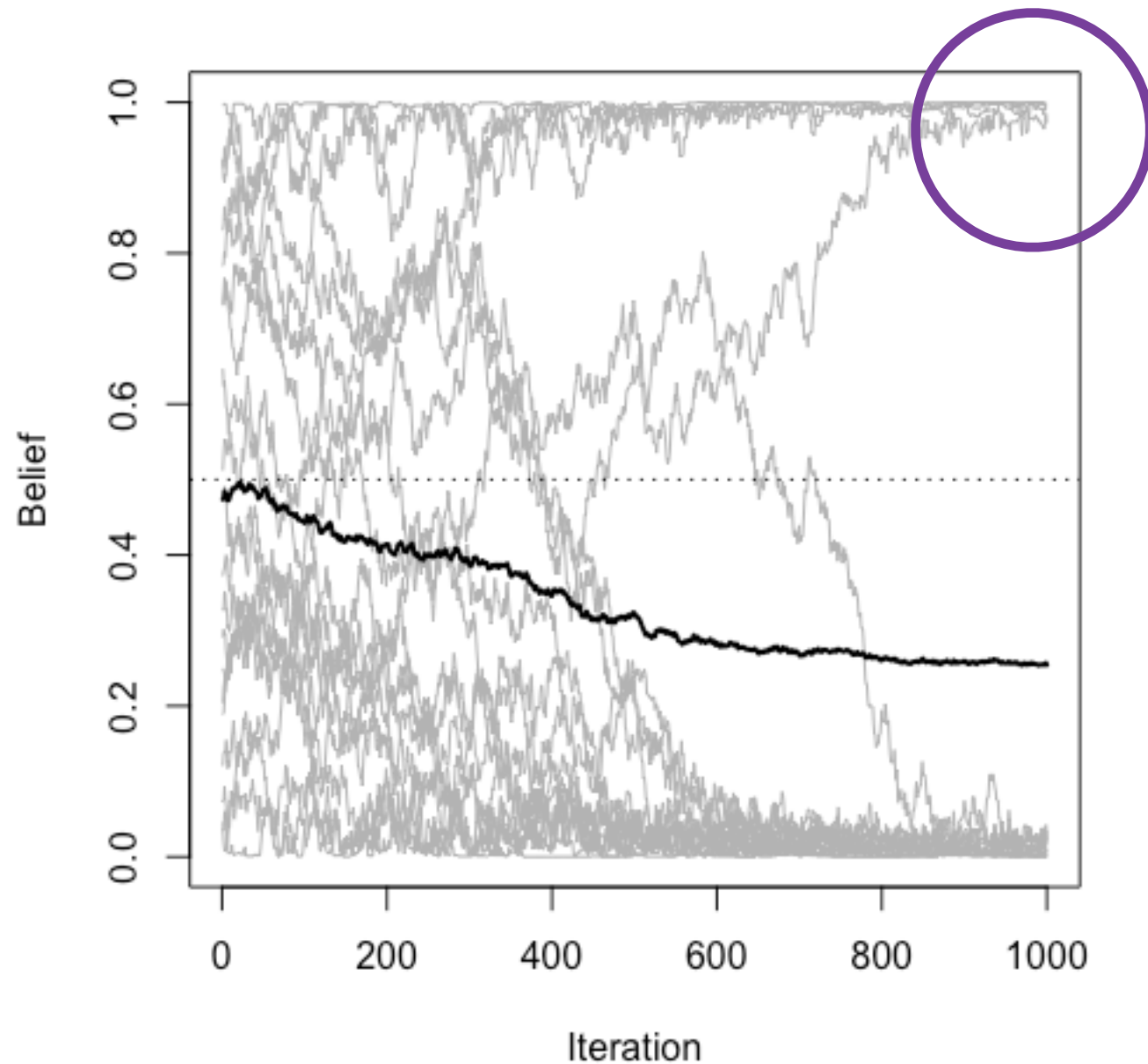


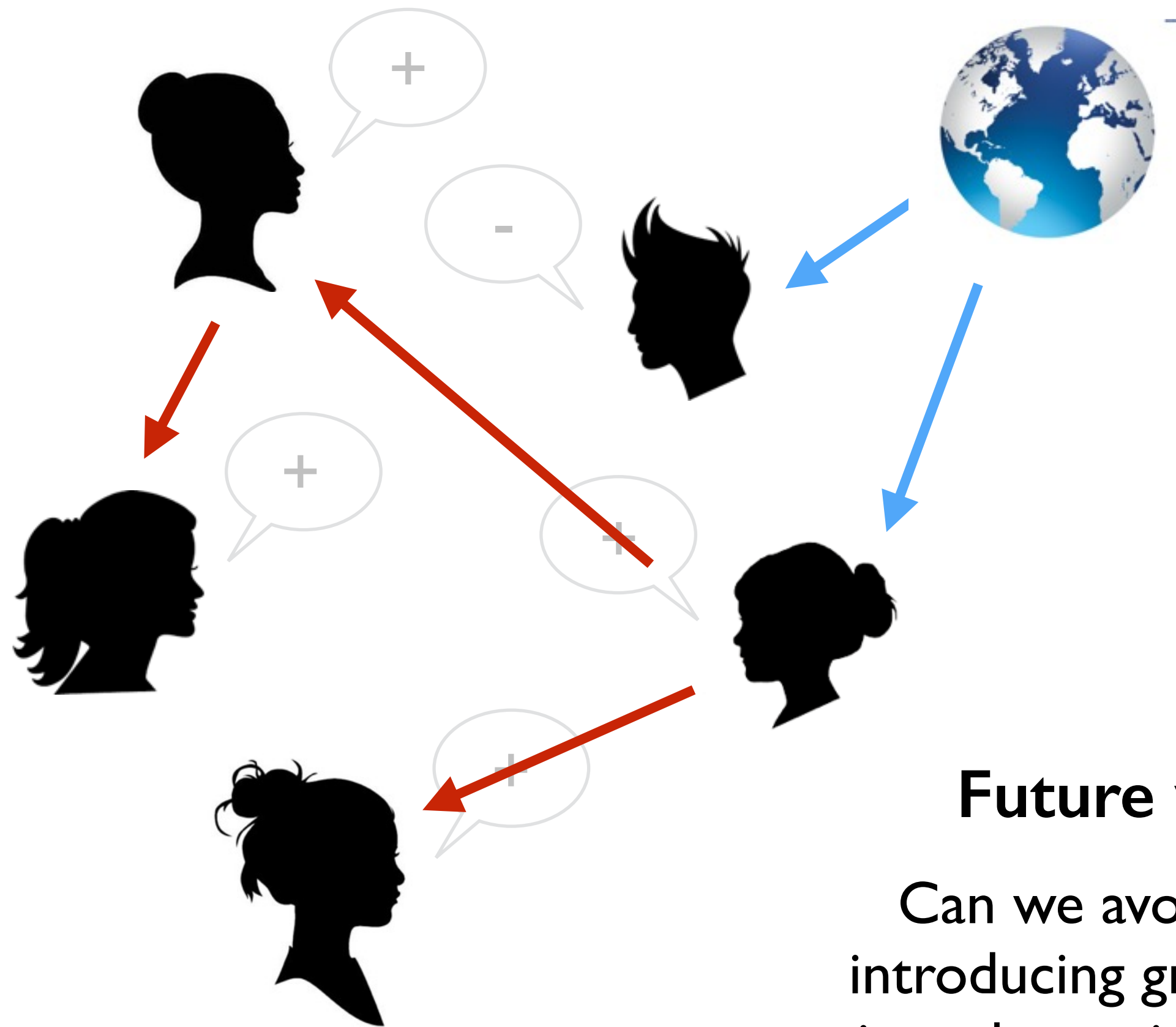
They might polarise  
into warring factions

...with the **extremists** being most trusted within group; and no between-group trust



And small “rogue” groups might form  
their own isolated world.

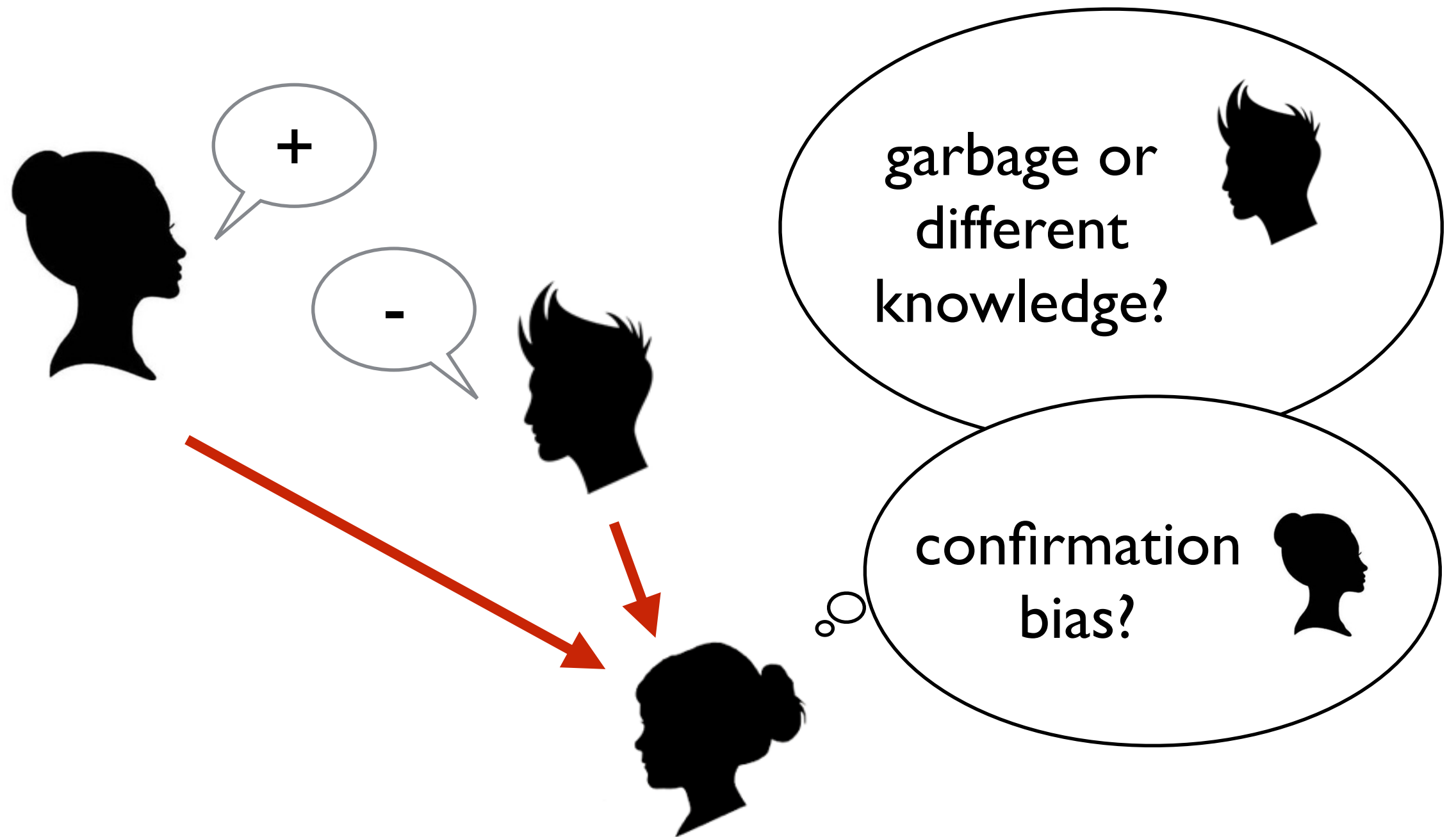




## Future work:

Can we avoid this by introducing ground truth into the social network?





## Future work:

Can we avoid this by giving our agents a more sophisticated ToM?

- Summary:

- Iterated learning distorts inductive bias when individual differences are present
- Miscalibrated agents can distort their own inductive biases even in homogenous chains
- IL chains favour learners with strong biases
- The magnitude of the distortion is variable
- Social structure, theory of mind, the link to the world... they all matter

- Implications:

- IL is limited as a tool for “revealing inductive priors”
- IL is potentially useful for studying “distortions” in cultural and linguistic evolution

Thanks!

